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**Nonlinear Applied Analysis**



”Learn to labour and to wait”

Longfellow



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# Introduction

The purpose of this course is to present several classes of nonlinear operators  $f : X \rightarrow X$  and to discuss different properties (existence, uniqueness, data dependence, various stability properties) of the fixed point equation

$$x = f(x), x \in X$$

in metric and topological settings. Then, using fixed point approaches and techniques, existence, uniqueness, data dependence results for different types of operatorial equations are given.

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# Chapter 1

## Contractive-type operators and fixed points

### 1.1 Background in Analysis

#### Metric spaces

Let  $(X, d)$  be a metric space. Recall that a metric  $d$  on a nonempty set  $X$  is a functional  $d : X \times X \rightarrow \mathbb{R}_+$  satisfying the following axioms

- (i)  $d(x, y) = 0$  if and only if  $x = y$
- (ii)  $d(x, y) = d(y, x)$  for every  $x, y \in X$
- (iii)  $d(x, y) \leq d(x, z) + d(z, y)$ , for every  $x, y, z \in X$ .

In what follows, sometimes we will need to consider infinite-valued metrics, also called generalized metrics.

Let  $(X, +, \cdot, \mathbb{R})$  be a linear space. Then a functional  $p : X \rightarrow \mathbb{R}_+$  is said to be a norm on  $X$  if it satisfies the following axioms

- (i)  $p(x) = 0$  if and only if  $x = \Theta$
- (ii)  $p(\lambda x) = |\lambda|p(x)$ , for each  $x \in X$  and  $\lambda \in \mathbb{R}_+$
- (iii)  $p(x + y) \leq p(x) + p(y)$ , for each  $x, y \in X$ .

Usually we denote  $p(x) := \|x\|$ ,  $x \in X$ .

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The pair  $(X, \|\cdot\|)$ , where  $X$  is a nonempty set and  $\|\cdot\|$  is a norm on it is called a normed space.

It is well-known that each norm induces a metric on  $X$ , by the formula

$$d(x, y) := \|x - y\|.$$

Throughout this course, we denote by  $P(X)$  the space of all nonempty subsets of a nonempty set  $X$ . By  $P_{cp}(X)$  we will denote the space of all nonempty compact subsets of  $X$ .

If  $(X, d)$  is a metric space,  $x_0 \in X$  and  $r > 0$ , then

$$B_d(x_0; r) := \{x \in X \mid d(x_0, x) < r\}$$

and respectively

$$\tilde{B}(x_0; r) := \{x \in X \mid d(x_0, x) \leq r\}$$

denote the open, respectively the closed ball of radius  $R$  centered in  $x$ .

If  $X$  is a topological space and  $Y$  is a subset of  $X$ , then we will denote by  $\bar{Y}$  the closure and by  $\text{int}Y$  the interior of the set  $Y$ . Also, if  $X$  is a normed space and  $Y$  is a nonempty subset of  $X$ , then  $\text{co}Y$  respectively  $\overline{\text{co}Y}$  denote the convex hull, respectively the closed convex hull of the set  $Y$ .

**Exercise.** Consider on  $\mathbb{R}$  the functional

$$d(x, y) = \begin{cases} 2, & \text{if } x \neq y \\ 0, & \text{otherwise} \end{cases}$$

Show that  $d$  is a metric on  $\mathbb{R}$  and then determine  $B_d(0; 2)$ ,  $\tilde{B}(0; 2)$  and  $\overline{B_d(0; 2)}$ .

It is well-known that each metric space is a topological space, with the topology generated by the family of all open balls from  $X$ . It is called the metric topology on  $X$ . Moreover, if  $(X, d)$  is a metric space, then

$d : X \times X \rightarrow \mathbb{R}$  is continuous in the metric topology. A similar property holds for norms.

### Sequences in metric spaces

Let  $(X, d)$  be a metric space. The sequence  $(x_n)_{n \in \mathbb{N}}$  is called:

(i) Cauchy if for each  $\epsilon > 0$  there is  $N_\epsilon \in \mathbb{N}^*$  such that for each  $n, m \geq N_\epsilon$ ,  $m > n$  we have  $d(x_n, x_m) < \epsilon$  (or, equivalently, if  $d(x_n, x_{n+p}) \rightarrow 0$  as  $n, p \rightarrow +\infty$  independently).

(ii) convergent to  $x^* \in X$  if for each  $\epsilon > 0$  there is  $N_\epsilon \in \mathbb{N}^*$  such that for each  $n \geq N_\epsilon$  we have  $d(x_n, x^*) < \epsilon$ .

Of course, any convergent sequence in  $X$  is Cauchy in  $X$ .

A metric space  $(X, d)$  is called complete if any Cauchy sequence in  $X$  is convergent in  $X$ . Any closed subset of a complete metric space is complete.

A Banach space is a normed space having the property that it is complete with respect to the metric induced by the norm.

**Theorem 9.** *A uniformly continuous function maps Cauchy sequences into Cauchy sequences.*

**Proof.** Let  $f : (X, d) \rightarrow (Y, \rho)$  be a uniformly continuous function. Let  $(x_n)$  be a Cauchy sequence in  $X$ . To see that  $(f(x_n))$  is a Cauchy sequence, let  $\epsilon > 0$ . Then there is a  $\delta > 0$  such that for every  $x, y \in X$ ,  $d(x, y) < \delta$  implies that  $\rho(f(x), f(y)) < \epsilon$ . Thus there exists an  $N(\epsilon) \in \mathbb{N}$  such that  $d(x_m, x_n) < \delta$  for any  $m, n \geq N(\epsilon)$ . It follows that  $\rho(f(x_m), f(x_n)) < \epsilon$  for any  $m, n \geq N(\epsilon)$ . Hence  $(f(x_n))$  is a Cauchy sequence in  $Y$ .

**Remark.** If  $f$  is not uniformly continuous, then the theorem may not be true. For example,  $f(x) = \frac{1}{x}$  is continuous on  $]0, \infty[$  and  $x_n = \frac{1}{n}$  is a Cauchy sequence in  $]0, \infty[$  but  $f(x_n) = n$  is not a Cauchy sequence.

**Remark.** If  $d(x_n, x_{n+1}) \leq a_n$  for every  $n \in \mathbb{N}$ , and  $\sum_{n \geq 1} a_n < \infty$ , then the sequence  $(x_n)$  is Cauchy.

**Examples of complete metric spaces**

1)  $(\mathbb{R}^n, d)$  is a complete metric space with each of the following functionals

$$d_E(x, y) := \sqrt{\sum_{i=1}^n (x_i - y_i)^2}$$

$$d_M(x, y) := \sum_{i=1}^n |x_i - y_i|$$

$$d_C(x, y) := \max_{i \in \{1, 2, \dots, n\}} |x_i - y_i|.$$

2)  $(C([a, b], \mathbb{R}^n), d)$  is a complete metric space with each of the following functionals:

$$d_C(x, y) := \max_{t \in [a, b]} d_{\mathbb{R}^n}(x(t), y(t))$$

$$d_B(x, y) := \max_{t \in [a, b]} (d_{\mathbb{R}^n}(x(t), y(t)) \cdot e^{-\tau(t-a)}).$$

3)  $(P_{cp}(X), H)$  is a complete metric space, provided  $(X, d)$  is a complete metric space, where  $H : P_{cp}(X) \times P_{cp}(X) \rightarrow \mathbb{R}_+$  is the so-called Pompeiu-Hausdorff metric, defined below.

$$H_d(A, B) := \max\{\sup_{a \in A} \inf_{b \in B} d(a, b), \sup_{b \in B} \inf_{a \in A} d(a, b)\}.$$

**Equivalence of metrics**

Let  $X$  be a nonempty set and  $d_1, d_2$  two metrics on  $X$ .

The two metrics are said to be topologically equivalent if they generate the same topology on  $X$ . There are many equivalent ways of expressing this condition. For example:

♠ a subset  $A$  of  $X$  is  $d_1$ -open if and only if it is  $d_2$ -open

♠ the identity function  $I : X \rightarrow X$  is both  $(d_1, d_2)$ -continuous and  $(d_2, d_1)$ -continuous.

By definition, two metrics  $d_1$  and  $d_2$  on  $X$  are called metrically (strongly) equivalent if for each  $x \in X$  there exists  $c_1, c_2 > 0$  such that

$$c_1 d_1(x, y) \leq d_2(x, y) \leq c_2 d_1(x, y), \text{ for each } y \in X.$$

If two metrics are strongly equivalent then they also are topologically equivalent. But the reverse implication, in general, does not hold.

### Examples of Banach spaces

1)  $(\mathbb{R}^n, \|\cdot\|)$  is a Banach space with each of the following functionals

$$\|x\|_E := \sqrt{\sum_{i=1}^n x_i^2}$$

$$\|x\|_M := \sum_{i=1}^n |x_i|$$

$$\|x\|_C := \max_{i \in \{1, 2, \dots, n\}} |x_i|.$$

2)  $(C([a, b], \mathbb{R}^n), d)$  is a Banach space with each of the following functionals:

$$\|x\|_C := \max_{t \in [a, b]} \|x(t)\|_{\mathbb{R}^n}$$

$$\|x\|_B := \max_{t \in [a, b]} (\|x(t)\|_{\mathbb{R}^n} \cdot e^{-\tau(t-a)}).$$

**Remark.** The unit interval  $[0, 1]$  is a complete metric space, but it is not a Banach space because it is not a linear space.

### Equivalence of norms

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By definition, two norms  $\|\cdot\|_1$  and  $\|\cdot\|_2$  on  $X$  are called topologically equivalent if they generate the same topology on  $X$ .

By definition, two norms  $\|\cdot\|_1$  and  $\|\cdot\|_2$  on  $X$  are called strongly equivalent if for each  $x \in X$  there exists  $c_1, c_2 > 0$  such that

$$c_1\|x\|_1 \leq \|x\|_2 \leq c_2\|x\|_1.$$

If two norms are strongly equivalent then they also are topologically equivalent. But the reverse implication, in generally, does not hold.

## 1.2 The Banach-Caccioppoli contraction principle

Some definitions first.

**Definition.** If  $X$  is a nonempty set and  $f : X \rightarrow X$  an operator then  $x \in X$  is called a fixed point for  $f$  iff  $x = f(x)$ . Denote by  $Fix(f)$  the fixed point set of  $f$ . Also, denote by  $I(f) := \{Y \in P(X) \mid f(Y) \subset Y\}$  the set of all nonempty invariant subsets of  $f$ .

**Definition.** Let  $X$  be a nonempty set,  $x \in X$  and  $f : X \rightarrow X$  be an operator. Then the sequence of successive approximations  $(x_n)_{n \in \mathbb{N}} \subset X$  for  $f$  starting from  $x$  is defined as follows:

$$x_0 = x, \quad x_n = f^n(x), \quad \text{for } n \in \mathbb{N},$$

where  $f^0 := 1_X$ ,  $f^1 := f$ ,  $\dots$ ,  $f^{n+1} = f \circ f^n$ ,  $n \in \mathbb{N}$  are the iterate operators of  $f$ . As consequence, we also have the following recurrence relation:

$$x_0 = x, \quad x_{n+1} = f(x_n), \quad n \in \mathbb{N}.$$

**Definition.** If  $(X, d)$  is a metric space and  $f : X \rightarrow X$  is an operator, then  $f$  is said to be:

- i)  $\alpha$ -Lipschitz if there is  $\alpha \in \mathbb{R}_+$  such that for every  $x, y \in X$  we have  $d(f(x), f(y)) \leq \alpha d(x, y)$ ;
- ii)  $\alpha$ -contraction if it is  $\alpha$ -Lipschitz with  $\alpha \in [0, 1[$ ;
- iii) nonexpansive if it is 1-Lipschitz;
- iv) contractive if for each  $x, y \in X$ ,  $x \neq y$  we have  $d(f(x), f(y)) < d(x, y)$ .

### The Banach-Caccioppoli contraction principle.

*Let  $(X, d)$  be a complete metric space and  $Y$  a closed subset of  $X$ . Let  $f : Y \rightarrow Y$  be an  $\alpha$ -contraction. Then we have the following conclusions:*

- (i)  $Fix(f) = \{x^*\}$ ;
- (ii) for each  $x \in Y$  the sequence of successive approximations (i.e.  $x_0 = x$ ,  $x_n := f^n(x_0)$ ,  $n \geq 1$ ) for  $f$  starting from  $x$  converges to  $x^*$ ;

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$$(iii) \ d(x_n, x^*) \leq \frac{\alpha^n}{1-\alpha} \cdot d(x_0, f(x_0)), \text{ for each } n \in \mathbb{N}.$$

$$(iv) \ d(x_{n+1}, x^*) \leq \frac{\alpha}{1-\alpha} \cdot d(x_n, x_{n+1}), \text{ for each } n \in \mathbb{N}.$$

**Steps of the proof.**

1)  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence, since

$$(*) \quad d(x_n, x_{n+p}) \leq \frac{\alpha^n}{1-\alpha} \cdot d(x_0, x_1), \text{ for each } n \in \mathbb{N} \text{ and each } p \in \mathbb{N}^*.$$

2)  $\lim_{n \rightarrow +\infty} x_n = x^* \in \text{Fix}(f)$ .

3) the uniqueness of the fixed point, by reductio ad absurdum.

4) Using (\*) we get (iii) and (iv).  $\square$



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### Exercises and examples.

1) Let  $f \in C^1(\mathbb{R})$ . Then

$f$  is  $\alpha$ -Lipschitz if and only if  $|f'(x)| \leq \alpha$ , for each  $x \in \mathbb{R}$ .

**Hint.** Use the Mean Value Theorem.

2) Let  $f : ]0, 1[ \rightarrow ]0, 1[$ ,  $f(x) = \frac{x}{2}$  and  $g : \mathbb{R} \rightarrow \mathbb{R}$ ,  $g(x) = \frac{\pi}{2} + x - \arctan x$ .

Show that  $f$  and  $g$  are fixed point free mappings. Please comment the connection with Banach-Caccioppoli theorem.

3) Let  $f : ]0, 1[ \rightarrow \mathbb{R}$ ,  $f(x) = 2x(1 - x)$  (the logistic operator).

(a) Find  $Fix(f)$

(b) Is  $f$  a contraction on  $[0, 1]$  ?

(c) Find a closed invariant subset  $A \subset [0, 1]$  such that  $f$  to be contraction on  $A$ .

4) Consider  $c > 0$  and the sequence  $(x_n)_{n \in \mathbb{N}} \subset \mathbb{R}$  given by

$$x_0 = 1, \quad x_{n+1} = \frac{1}{2} \left( x_n + \frac{c}{x_n} \right), \quad n \in \mathbb{N}.$$

a) Show (by fixed point methods) that  $\lim_{n \rightarrow +\infty} x_n = \sqrt{c}$ ;

b) Find  $\sqrt{2}$  with an error less than  $10^{-2}$ .

**Hint.** Use the Banach-Caccioppoli theorem.  $\square$

### 1.3 Consequences, applications and extensions

Let present first a data dependence result.

**The continuous dependence of the fixed point of the Banach-Caccioppoli contraction principle.**

Let  $(X, d)$  be a complete metric space and  $f, g : X \rightarrow X$  such that:

(i)  $f$  is an  $\alpha$ -contraction (denote by  $x_f^*$  its unique fixed point);

(ii) There exists  $x_g^* \in \text{Fix}(g)$ ;

(iii) There exists  $\eta > 0$  such that  $d(f(x), g(x)) \leq \eta$ , for each  $x \in X$ .

Then  $d(x_f^*, x_g^*) \leq \frac{\eta}{1-\alpha}$ .

**Remark.** J. Hadamard (1902) defines the concept of well-posedness for a certain mathematical problem.

**Remark.** A.N. Tychonov define another concept of well-posed problem (in the sense of Tychonov).

**Definition.** Let  $(X, d)$  be a metric space and  $f : X \rightarrow X$  be an operator. Consider the fixed point problem

$$x = f(x), \quad x \in X. \quad (1.1)$$

We say that the fixed point problem for the operator  $f$  is well-posed if  $\text{Fix}(f) = \{x^*\}$  and, if  $x_n \in X$ ,  $n \in \mathbb{N}$  is a sequence such that

$$d(x_n, f(x_n)) \rightarrow 0 \text{ as } n \rightarrow \infty,$$

then

$$x_n \rightarrow x^* \text{ as } n \rightarrow \infty.$$

**Theorem.** Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$  an  $\alpha$ -contraction. Then, the fixed point problem for  $f$  is well-posed.

**Definition.** Let  $(X, d)$  be a metric space and  $f : X \rightarrow X$  be an operator. Consider the fixed point problem

$$x = f(x), \quad x \in X. \quad (1.2)$$

We say that the operator  $f$  has:

(a) the limit shadowing property if for any sequence  $(y_n)_{n \in \mathbb{N}} \subset X$  with the property

$$(d(y_{n+1}, f(y_n))) \rightarrow 0 \text{ as } n \rightarrow \infty,$$

there exists  $x \in X$  such that

$$d(y_n, f^n(x)) \rightarrow 0 \text{ as } n \rightarrow \infty.$$

(b) the Ostrowski's property if  $Fix f = \{x^*\}$  and for any sequence  $(y_n)_{n \in \mathbb{N}} \subset X$  with the property

$$(d(y_{n+1}, f(y_n))) \rightarrow 0 \text{ as } n \rightarrow \infty,$$

we have that

$$y_n \rightarrow x^* \text{ as } n \rightarrow \infty.$$

For our next result we need the following auxiliary result.

**Cauchy's Lemma.** Let  $(a_n)_{n \in \mathbb{N}}$  and  $(b_n)_{n \in \mathbb{N}}$  be two sequences of non-negative real numbers, such that  $\sum_{k=0}^{+\infty} a_k < +\infty$  and  $\lim_{n \rightarrow +\infty} b_n = 0$ . Then

$$\lim_{n \rightarrow +\infty} \left( \sum_{k=0}^n a_{n-k} b_k \right) = 0.$$

**Theorem.** Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$  an  $\alpha$ -contraction. Then, the operator  $f$  has the Ostrowski's property and the limit shadowing property.

**Proof.** By the Contraction Principle, we know that  $Fix(f) = \{x^*\}$ .

Let  $(y_n)_{n \in \mathbb{N}}$  be a sequence in  $X$  such that  $d(y_{n+1}, f(y_n)) \rightarrow 0$  as  $n \rightarrow \infty$ .

We shall prove first that  $d(y_n, x^*) \rightarrow 0$  as  $n \rightarrow +\infty$ . We successively have:

$$\begin{aligned} d(x^*, y_{n+1}) &\leq d(x^*, f(y_n)) + d(y_{n+1}, f(y_n)) = d(f(x^*), f(y_n)) + d(y_{n+1}, f(y_n)) \\ &\leq \alpha d(x^*, y_n) + d(y_{n+1}, f(y_n)) \leq \alpha[\alpha d(x^*, y_{n-1}) + d(y_n, f(y_{n-1}))] + \\ d(y_{n+1}, f(y_n)) &\leq \dots \leq \alpha^{n+1} d(x^*, y_0) + \alpha^n d(y_1, f(y_0)) + \dots + d(y_{n+1}, f(y_n)). \end{aligned}$$

By Cauchy's Lemma, the right hand side tends to 0 as  $n \rightarrow +\infty$ . Thus,  $d(x^*, y_{n+1}) \rightarrow 0$  as  $n \rightarrow +\infty$ . This shows that  $f$  has the Ostrowski's property.

Now, for arbitrary  $x \in X$ , we have

$$d(y_n, f^n(x)) \leq d(y_n, x^*) + d(x^*, f^n(x)) \rightarrow 0 \text{ as } n \rightarrow +\infty.$$

**Definition.** Let  $(X, d)$  be a metric space and  $f : X \rightarrow X$  be an operator. Consider the fixed point problem

$$x = f(x), \quad x \in X. \quad (1.3)$$

We say that the operator  $f$  has the Ulam-Hyers stability property if there exists  $c > 0$ , such that for every  $\varepsilon > 0$  and every  $\varepsilon$ -solution  $y^*$  of the fixed point problem  $x = f(x)$  (which means that  $y^*$  satisfies the following relation

$$d(y^*, f(y^*)) \leq \varepsilon),$$

there exists a solution  $x^* \in X$  of the fixed point problem  $x = f(x)$  such that

$$d(x^*, y^*) \leq c\varepsilon.$$

**Theorem.** Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$  be an  $\alpha$ -contraction. Then, the fixed point problem  $x = f(x)$  has the Ulam-Hyers property.

**The local form of the Banach-Caccioppoli contraction principle.**

Let  $(X, d)$  be a complete metric space,  $x_0 \in X$  and  $r > 0$ . Let  $f : B(x_0; r) \rightarrow X$  be an  $\alpha$ -contraction such that  $d(x_0, f(x_0)) < (1 - \alpha)r$ . Then  $\text{Fix} f \neq \emptyset$ .

**Hint.**

Consider  $0 < \epsilon < r$  such that  $d(x_0, f(x_0)) \leq (1 - \alpha)\epsilon < (1 - \alpha)r$ . Show that  $\tilde{B}(x_0; \epsilon) \in I(f)$  and apply the Banach-Caccioppoli theorem.  $\square$

An application of the above results are the so-called domain invariance principles.

Let  $E$  be a Banach space and  $X \subset E$ . Let  $f : X \rightarrow E$  be an operator. Then the operator  $g : X \rightarrow E$  defined by  $g(x) = x - f(x)$  is said to be the field generated by  $f$ .

We have the following result.

**Theorem.**

Let  $E$  be a Banach space and  $U$  an open subset of it. Let  $f : U \rightarrow E$  be an  $\alpha$ -contraction.

Then the following conclusions hold:

- i) the field  $g$  generated by  $f$  is an open operator, i.e., the image of any open set is open too;
- ii)  $g(U)$  is open in  $E$ ;
- iii)  $g : U \rightarrow g(U)$  is a homeomorphism.

**Sketch of the proof.**

i)  $g$  is open operator if and only if for any  $V$  an open subset of  $U$  the set  $g(V)$  is open in  $E$  too. For, it's enough to prove that for any  $y \in g(V)$  there exists  $W$  an open neighborhood of  $y$  such that  $W \subset g(V)$ .

In order to get the conclusion, one can prove first that the following implication holds:

$$\text{for } u \in V \text{ and each } B(u; r) \subset V \Rightarrow B(g(u); (1 - \alpha)r) \subset g(B(u; r)).$$

In order to prove it, we will apply the local form of the Banach-Caccioppoli principle. Indeed, let  $u \in V$  and  $y \in B(g(u); (1 - \alpha)r)$ , i.e.,  $\|y - g(u)\| < (1 - \alpha)r$ . We have to show that  $y \in g(B(u; r))$ , which means that there exists  $x \in B(u; r)$  such that  $y = g(x)$ . This means that we are looking for  $x \in B(u; r)$  such that  $y + f(x) = x$ . For this conclusion, it is enough to apply the local form of the Banach-Caccioppoli principle for  $h : B(u; r) \rightarrow X$ ,  $h(x) = y + f(x)$ . We can do it, since  $h$  is an  $\alpha$ -contraction and  $d(u, h(u)) = \|u - h(u)\| = \|u - f(u) - y\| = \|g(u) - y\| < (1 - \alpha)r$ .

Now, let  $V$  be an open subset of  $U$  and take any  $y \in g(V)$ . Then, there exists  $u \in V$  such that  $y = g(u)$ . Notice that, since  $V$  is open, there exists  $B(u; r) \subset V$ . Take  $W := B(g(u); (1 - \alpha)r)$ . Hence, by the above proof, we have  $W \subset g(B(u; r)) \subset g(V)$ .

(ii) Apply (i) for  $U = V$ .

(iii)  $g : U \rightarrow g(U)$  is surjective and continuous. Moreover, it is also injective since

$$\begin{aligned} \|g(x) - g(y)\| &= \|x - f(x) - y + f(y)\| = \|(x - y) - (f(x) - f(y))\| \geq \\ &\|x - y\| - \|f(x) - f(y)\| \geq (1 - \alpha)\|x - y\|. \end{aligned}$$

Then, if  $g(x) = g(y)$ , then  $x = y$ . Additionally,  $g^{-1}$  is continuous too, since for any open set  $V \subset g(U)$  we have that  $(g^{-1})^{-1}(V) = g(V)$  is open (by (i)). Thus,  $g$  is a homeomorphism.  $\square$

Other local fixed point theorems are the following.

**Theorem.**

Let  $E$  be a Banach space and let  $f : \tilde{B}(0; r) \rightarrow E$  be an  $\alpha$ -contraction, such that  $f(\partial\tilde{B}(0; r)) \subset \tilde{B}(0; r)$ . Then  $\text{Fix}(f) = \{x^*\}$ .

**Proof.** Let us define, for  $x \in \tilde{B}(0; r)$

$$G(x) := \frac{1}{2}(x + f(x)).$$

Then we have:

- (i)  $Fix(f) = Fix(G)$ ;  
 (ii)  $G : \tilde{B}(0; r) \rightarrow \tilde{B}(0; r)$  (take  $G(x) := \frac{1}{2}(x + f(u) + f(x) - f(u))$ , where  $u := \frac{r}{\|x\|}x$ ); Indeed, we have

$$\begin{aligned} \|G(x)\| &= \left\| \frac{1}{2}(x + f(u) + f(x) - f(u)) \right\| \leq \frac{1}{2}(\|x\| + \|f(u)\| + \|f(x) - f(u)\|) \leq \\ &\frac{1}{2}(\|x\| + r + \alpha\|x - u\|) \leq \frac{1}{2}[\|x\| + r + \alpha(r - \|x\|)] = \frac{1}{2}[(1 + \alpha)r + (1 - \alpha)\|x\|] \leq \\ &\frac{1}{2}[(1 - \alpha)r + (1 + \alpha)r] = r. \end{aligned}$$

- (iii)  $G$  is  $\frac{1+\alpha}{2}$ -contraction.

**Theorem.**

Let  $E$  be a Banach space and let  $f : \tilde{B}(0; r) \rightarrow E$  be an  $\alpha$ -contraction, such that  $f(-x) = -f(x)$ , for each  $x \in \partial\tilde{B}(0; r)$ . Then  $Fix(f) = \{x^*\}$ .

**Proof.** Show that  $f(-x) = -f(x)$ , for each  $x \in \partial\tilde{B}(0; r)$  implies that  $f(\partial\tilde{B}(0; r)) \subset \tilde{B}(0; r)$ . (indeed, for  $x \in \partial\tilde{B}(0; r)$  we have:

$$2\|f(x)\| = \|f(x) - f(-x)\| \leq 2\alpha\|x\|.$$

Thus,  $\|f(x)\| \leq \alpha\|x\| = \alpha r < r$ .

**Exercise.** Show, by fixed point methods, that for each  $y \in \mathbb{R}$  the equation  $x - \frac{1}{3}\sin x = y$  has a unique solution in  $\mathbb{R}$ .

**Continuation results for contractions**

Let  $(X, d)$  be a complete metric space and  $Y$  a closed subset such that  $int Y \neq \emptyset$ . Denote by  $CR(Y, X)$  the family of all contractions from  $Y$  to  $X$ . Let  $(J, \rho)$  the metric space of parameters.

**Definition.** The family  $(H_\lambda)_{\lambda \in J} \subset CR(Y, X)$  is said to be  $\alpha$ -contractive if  $\alpha \in [0, 1[$  and there is  $M > 0$  and  $p \in ]0, 1]$  such that:

- (i)  $d(H_\lambda(x_1), H_\lambda(x_2)) \leq \alpha d(x_1, x_2)$ , for each  $x_1, x_2 \in Y$  and  $\lambda \in J$ ;  
 (ii)  $d(H_\lambda(x), H_\mu(x)) \leq M[\rho(\lambda, \mu)]^p$ , for each  $x \in Y$  and  $\lambda, \mu \in J$ .

Denote by  $A := \partial Y$ ,  $U := \text{int}Y$  and by  $CR_A(Y, X) := \{f \in CR(Y, X) : f|_A : A \rightarrow X \text{ is fixed point free}\}$ .

**Theorem.** *Let  $(X, d)$  be a complete metric space and  $Y$  a closed subset such that  $\text{int}Y \neq \emptyset$ . Let  $(J, \rho)$  be a connex metric space and  $(H_\lambda)_{\lambda \in J}$  be an  $\alpha$ -contractive family from  $CR_A(Y, X)$ . Then:*

(i) *if there exists  $\lambda_0^* \in J$  such that the equation  $H_{\lambda_0^*}(x) = x$  has a solution then the equation  $H_\lambda(x) = x$  has a unique solution for every  $\lambda \in J$ ;*

(ii) *if  $H_\lambda(x_\lambda) = x_\lambda$  for  $\lambda \in J$  then the operator  $j : J \rightarrow \text{int}Y$  given by  $j(\lambda) = x_\lambda$  is continuous.*



**Kannan's fixed point theorem**

The following result is a fixed point theorem for operators which are not necessarily continuous.

**Theorem.** *Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$  be a Kannan type contraction, i.e. there exists  $\alpha \in ]0, \frac{1}{2}[$  such that*

$$d(f(x), f(y)) \leq \alpha[d(x, f(x)) + d(y, f(y))], \text{ for each } x, y \in X.$$

*Then we have the following conclusions:*

- (i)  $\text{Fix}(f) = \{x^*\}$ ;
- (ii) for each  $x \in X$  the sequence of successive approximations (i.e.  $x_0 \in X$ ,  $x_n := f^n(x_0)$ ,  $n \geq 1$ ) for  $f$  starting from  $x$  converges to  $x^*$ .

**Steps of the proof.**

Let  $x_0 \in X$  be arbitrary and  $x_n := f^n(x_0)$ , for  $n \geq 1$ . Thus  $x_{n+1} = f(x_n)$ ,  $n \in \mathbb{N}$ . Then we have:

- 1)  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence; Notice first that

$$d(x_n, x_{n+1}) \leq \frac{\alpha}{1-\alpha} d(x_{n-1}, x_n) \leq k^n d(x_0, x_1), \text{ for each } n \geq 1,$$

where  $k := \frac{\alpha}{1-\alpha} < 1$ . Thus, as a consequence, we obtain

$$d(x_n, x_{n+p}) \leq \frac{k^n}{1-k} \cdot d(x_0, x_1), \text{ for each } n \in \mathbb{N} \text{ and each } p \in \mathbb{N}^*.$$

- 2)  $\lim_{n \rightarrow +\infty} x_n = x^* \in X$ , by the completeness of the space.

- 3)  $x^* \in \text{Fix}(f)$  since we can write  $d(x^*, f(x^*)) \leq d(x^*, f(x_n)) + d(f(x_n), f(x^*)) \leq d(x^*, x_{n+1}) + \alpha(d(x_n, x_{n+1}) + d(x^*, f(x^*)))$ . Thus

$$d(x^*, f(x^*)) \leq \frac{\alpha}{1-\alpha} [d(x^*, x_{n+1}) + \alpha d(x_n, x_{n+1})] \rightarrow 0, \text{ as } n \rightarrow \infty.$$

- 4) the uniqueness of the fixed point follows by contradiction.  $\square$

**Exercise.** *Let  $f : [0, 1] \rightarrow [0, 1]$  be defined by*

$$f(x) := \begin{cases} \frac{x}{4}, & x \in [0, \frac{1}{2}[ \\ \frac{x}{5}, & x \in [\frac{1}{2}, 1], \end{cases}$$

Show that  $f$  is not a contraction, but  $f$  is a Kannan type contraction with  $\alpha = \frac{4}{9}$ .

**Exercise.** Show that  $f : [0, 1] \rightarrow [0, 1]$   $f(x) = \frac{x}{3}$  is a  $\frac{1}{3}$ -contraction, but it is not a Kannan type contraction (Take  $x = \frac{1}{3}$  and  $y = 0$ ).

**Exercise.** Under the assumptions of Kannan's fixed point theorem show that the fixed point problem  $x = f(x)$  is well-posed and has the Ulam-Hyers property.

A generalization of both Contraction Principle and Kannan's fixed point theorem is the following result proved by L. Ćirić.

### Ćirić's fixed point theorem

**Theorem.** Let  $(X, d)$  be a complete metric space and  $f : Y \rightarrow Y$  be a Ćirić-type contraction, i.e. there exists  $\alpha \in ]0, 1[$  such that for each  $x, y \in X$  we have:

$$d(f(x), f(y)) \leq \alpha \cdot \max\{d(x, y), d(x, f(x)), d(y, f(y)), \frac{1}{2}[d(x, f(y)) + d(y, f(x))]\}.$$

Then we have the following conclusions:

- (i)  $Fix(f) = \{x^*\}$ ;
- (ii) for each  $x \in Y$  the sequence of successive approximations (i.e.  $x_0 = x$ ,  $x_n := f^n(x_0)$ ,  $n \geq 1$ ) for  $f$  starting from  $x$  converges to  $x^*$ .

## 1.4 The Nemitki-Edelstein fixed point principle

Recall that if  $(X, d)$  is a metric space, then an operator  $f : X \rightarrow X$  is called contractive if:

$$x, y \in X, x \neq y \text{ implies } d(f(x), f(y)) < d(x, y).$$

### Theorem.

Let  $(X, d)$  be a compact metric space and  $f : X \rightarrow X$  be a contractive operator. Then  $\text{Fix}(f) = \{x^*\}$  and for each  $x \in X$  the sequence of successive approximations (i.e.  $x_0 = x$ ,  $x_n := f^n(x_0)$ ,  $n \geq 1$ ) for  $f$  starting from  $x$  converges to  $x^*$ .

**Sketch of the proof.** Since  $X$  is compact and the functional  $h(x) = d(x, f(x))$  is continuous from  $X$  to  $\mathbb{R}$  there exists  $x^* \in X$  such that  $h(x^*) = \inf_{x \in X} h(x)$ . Next, show, by reductio ad absurdum, that  $x^* \in \text{Fix}(f)$ . Indeed, suppose  $x^* \neq f(x^*)$ . Then,  $h(f(x^*)) = d(f(x^*), f^2(x^*)) < d(x^*, f(x^*)) = h(x^*)$ , which is a contradiction. The uniqueness is an easy consequence of the contractive condition. Hence  $\text{Fix}(f) = \{x^*\}$ .

For the convergence property, notice first that  $x_{n+1} = f(x_n)$ . Since  $X$  is compact, there exists a convergent subsequence  $x_{n_k}$ . Moreover, since  $x_{n_k+1} = f(x_{n_k})$ , using the continuity of  $f$ , we get (by passing to limit) that  $x_{n_k}$  converges to  $x^* \in \text{Fix}(f)$ .

Let us consider now any convergent subsequence  $(x_{n_p})$  of  $x_n$ . Suppose  $(x_{n_p})$  converges to some  $l \in X$ . Then, since  $x_{n_p+1} = f(x_{n_p})$ , we obtain again that  $l \in \text{Fix}(f)$  and so  $l = x^*$ . Thus  $x_{n_p}$  converges to  $x^*$ , as  $p \rightarrow +\infty$ . Now, since each convergent subsequence of  $(x_n)$  has the fixed point  $x^*$  of  $f$  as the limit point, it follows (by a well-known result in functional analysis) that the whole sequence  $(x_n)$  converges to  $x^*$ .  $\square$

**Exercise.** Show that even  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f(x) = \ln(1+e^x)$  is contractive, nevertheless  $\text{Fix}(f) = \emptyset$ . Why ?

## 1.5 Meir-Keeler Fixed Point Theorem

Let  $(X, d)$  be a metric space. An operator  $f : X \rightarrow X$  is called a Meir-Keeler operator if for each  $\epsilon > 0$  there exists  $\delta > 0$  such that the following implication holds:

$$x, y \in X \quad \epsilon \leq d(x, y) < \epsilon + \delta \Rightarrow d(f(x), f(y)) < \epsilon.$$

**Remark.** Any Meir-Keeler operator is contractive and, hence, continuous. Indeed, if we chose  $x, y \in X$  with  $x \neq y$ , then, by taking  $\epsilon := d(x, y) > 0$  we obtain that  $d(f(x), f(y)) < \epsilon = d(x, y)$ .

**Meir-Keeler Theorem.** *Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$  be a Meir-Keeler operator. Then:*

- (i)  $F_f = \{x^*\}$ ;
- (ii) the sequence  $(f^n(x))_{n \in \mathbb{N}}$  converges to  $x^*$ , for each  $x \in X$ .

**Proof.**

**Step 1.** The Meir-Keeler condition implies that  $d(x_n, x_{n+1}) \rightarrow 0$  as  $n \rightarrow +\infty$ , where  $x_n := f^n(x)$ ,  $x \in X$ .

Indeed, if we denote  $c_n := d(x_n, x_{n+1})$ ,  $n \in \mathbb{N}$ , then, since  $(c_n)$  is decreasing and positive, it is convergent to a certain  $\eta \geq 0$ . Suppose that  $\eta > 0$ . Then there exists  $\delta > 0$  such that the following implication holds:

$$\eta \leq c_n < \eta + \delta \text{ implies } c_{n+1} < \eta.$$

This is a contradiction with the fact that  $(c_n)$  is decreasing to  $\eta$ . Hence Step 1 is proved.

**Step 2.** The sequence  $x_n := f^n(x)$ ,  $x \in X$  is Cauchy.

Indeed, suppose by contradiction that there exists  $x_0 \in X$  such that the sequence  $x_n := f^n(x_0)$  is not Cauchy. Then, there exists  $\epsilon > 0$  such that  $\lim_{n, m \rightarrow +\infty} d(x_m, x_n) > 2\epsilon$ . By Meir-Keeler condition, there exists  $\delta > 0$  such that

$$x, y \in X \quad \epsilon \leq d(x, y) < \epsilon + \delta \Rightarrow d(f(x), f(y)) < \epsilon.$$

Choose  $\delta' := \min\{\delta, \epsilon\}$ . By Step 1, we get that there exists  $M \in \mathbb{N}^*$  such that  $c_M < \frac{\delta'}{\epsilon}$ . Let  $m, n > M, n > m$  be such that  $d(x_m, x_n) > 2\epsilon$ . For any  $j \in [m, n]$  we have

$$|d(x_m, x_j) - d(x_m, x_{j+1})| \leq c_j = d(x_j, x_{j+1}) < \frac{\delta'}{3}.$$

Now, since  $d(x_m, x_{m+1}) < \epsilon$  and  $d(x_m, x_n) > 2\epsilon = \epsilon + \epsilon \geq \epsilon + \delta'$ , there exists  $j \in [m, n]$  such that

$$\epsilon + \frac{2\delta'}{3} < d(x_m, x_j) < \epsilon + \delta'.$$

Thus,

$$\epsilon \leq \epsilon + \frac{2\delta'}{3} < d(x_m, x_j) < \epsilon + \delta' < \epsilon + \delta.$$

For all  $m$  and  $j$  we have that  $d(x_m, x_j) \leq d(x_m, x_{m+1}) + d(x_{m+1}, x_{j+1}) + d(x_{j+1}, x_j)$  and, therefore, by the above estimations we get that  $d(x_m, x_j) \leq d(x_m, x_{m+1}) + d(f(x_m), f(x_j)) + d(x_{j+1}, x_j) \leq c_m + \epsilon + c_j < \frac{\delta'}{3} + \epsilon + \frac{\delta'}{3} = \frac{2\delta'}{3} + \epsilon$ , a contradiction.

**Step 3.**  $Fix(f) = \{x^*\}$  and  $\lim_{n \rightarrow +\infty} f^n(x) = x^*$  for each  $x \in X$ .

Indeed, denote first  $x^*(x) := \lim_{n \rightarrow +\infty} f^n(x)$  for  $x \in X$ . Next, by the above Remark we know that  $f$  is contractive and hence continuous. Thus  $x^*(x) \in Fix(f)$ . By the contractive condition we obtain the uniqueness of the fixed point.

The proof is now complete.

## 1.6 Krasnoselskii's Theorem

**Theorem.** (Cantor) *Let  $(X, d)$  be a complete metric space and  $Y_n, n \in \mathbb{N}$  be nonempty closed subsets of  $X$  such that  $Y_{n+1} \subset Y_n, n \in \mathbb{N}$  and  $\delta(Y_n) \rightarrow 0$  as  $n \rightarrow \infty$ .*

*Then,  $\bigcap_{n \in \mathbb{N}} Y_n = \{x^*\}$ .*

Using Cantor's theorem we have:

**Theorem (1972)** *Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$  be an operator. Suppose that for each  $0 < a \leq b < +\infty$  there is  $l(a, b) \in [0, 1[$  such that*

$$x, y \in X, a \leq d(x, y) \leq b \text{ implies } d(f(x), f(y)) \leq l(a, b)d(x, y).$$

Then we have:

(i)  $\text{Fix } f = \text{Fix } f^n = \{x^*\}$ ;

(ii) the sequence  $(f^n(x))_{n \in \mathbb{N}}$  converges to  $x^*$ , for each  $x \in X$ .

**Proof.** STEP 1. We prove that for each  $r > 0$  there exists  $\tilde{B}(x; r) \subset X$  such that  $\tilde{B}(x; r) \in I(f)$ .

We will use the "reductio ad absurdum" method: suppose there exists  $r > 0$  such that for each  $x \in X$  one has  $\tilde{B}(x; r) \notin I(f)$ . Then, there exists  $x_1 \in X$  such that  $d(x, x_1) \leq r$  and  $d(x, f(x_1)) > r$ . We have two cases:

a)  $d(x, x_1) \leq \frac{r}{2}$ . Then  $d(x, x_1) \leq d(x, x_1) \leq \frac{r}{2}$  implies  $d(f(x), f(x_1)) \leq l(d(x, x_1), \frac{r}{2})d(x, x_1) < \frac{r}{2}$ . Thus,  $d(x, f(x)) \geq d(x, f(x_1)) - d(f(x_1), f(x)) \geq r - \frac{r}{2} = \frac{r}{2}$ .

b)  $d(x, x_1) > \frac{r}{2}$ . Then  $\frac{r}{2} < d(x, x_1) \leq r$  implies  $d(f(x), f(x_1)) \leq l(\frac{r}{2}, r)d(x, x_1)$ . Hence  $d(x, f(x)) \geq d(x, f(x_1)) - d(f(x_1), f(x)) \geq r - l(\frac{r}{2}, r)d(x, x_1) \geq r - l(\frac{r}{2}, r) \cdot r = r[1 - l(\frac{r}{2}, r)]$ .

Thus, in both cases we have:

$$(*) \quad d(x, f(x)) \geq \min\left\{\frac{r}{2}, r[1 - l(\frac{r}{2}, r)]\right\} := a.$$

On the other hand, for each  $x_0 \in \tilde{B}(x; r)$  we have that  $a \leq d(x_0, f(x_0)) \leq d(x_0, f(x_0)) := b$  implies  $d(f(x_0), f^2(x_0)) \leq l(a, b)d(x_0, f(x_0)) < d(x_0, f(x_0))$ . Thus

$$a \leq d(f^k(x_0), f^{k+1}(x_0)) \leq l^k(a, b) \cdot d(x_0, f(x_0)) \rightarrow 0, \text{ as } k \rightarrow +\infty.$$

Hence  $u_k := d(f^k(x_0), f^{k+1}(x_0)) \rightarrow 0, k \rightarrow +\infty$ . As consequence, for each  $\epsilon > 0$  there is  $k(\epsilon) \in \mathbb{N}^*$  such that for each  $k \geq k(\epsilon)$  one has that  $u_k < a$ .

In particular, for  $\epsilon := a$  there is a  $k^* \in \mathbb{N}^*$  such that for each  $k \geq k^*$  we have  $u_{k^*} < a$ . Hence,  $u_{k^*} = d(f^{k^*}(x_0), f^{k^*+1}(x_0)) = d(x, f(x)) < a$  (where  $x := f^{k^*}(x_0)$ ). The contradiction shows that Step 1 is proved.

STEP 2. There exists a decreasing sequence  $B_1, B_2, \dots, B_n, \dots$  of closed balls such that  $\text{diam}B_n \rightarrow 0$ , as  $n \rightarrow +\infty$ .

Indeed, let  $B_1 := \tilde{B}(x, 1) \in I(f)$ . For  $f : B_1 \rightarrow B_1$  we can apply Step 1 and we get that there exists  $B_2 \in B_1$  ( $B_2 := \tilde{B}(x, \frac{1}{2})$ ) such that  $B_2 \in I(f)$ . By this procedure we also get  $B_n := \tilde{B}(x, \frac{1}{n}) \in I(f), \dots$ . Since  $\text{diam}B_n \rightarrow 0$  as  $n \rightarrow +\infty$ , we obtain, by Cantor's theorem, that  $\bigcap_{n \in \mathbb{N}^*} B_n = \{x^*\} \in I(f)$ . Thus  $x^* \in \text{Fix}(f)$ .

STEP 3. The uniqueness of the fixed point.

Suppose that  $x^*, y^* \in \text{Fix}f$ . Then  $d(x^*, y^*) = d(f(x^*), f(y^*)) \leq l(d(x^*, y^*), d(x^*, y^*))d(x^*, y^*) < d(x^*, y^*)$ , which represents a contradiction.

STEP 4. Let  $x \in X$  with  $x \neq x^*$ . We have  $d(f^n(x), x^*) \rightarrow 0$ , as  $n \rightarrow +\infty$ .

Indeed, since the sequence  $(d(f^n(x), x^*))_{n \in \mathbb{N}}$  is decreasing, it is convergent too. If, by contradiction  $d(f^n(x), x^*) \rightarrow u > 0$  as  $n \rightarrow +\infty$ , then  $d(f^n(x), x^*) \leq l(u, d(x, x^*))^n \cdot d(x, x^*) \rightarrow 0$  as  $n \rightarrow +\infty$ . Thus  $d(f^n(x), x^*) \rightarrow 0$  as  $n \rightarrow +\infty$ .

Finally, notice that from (ii) we obtain  $\text{Fix}f^n = \text{Fix}f = \{x^*\}$ .

The proof is now complete.  $\square$

**Remark.** *i) Let  $(X, d)$  be a compact metric space and  $f : X \rightarrow X$  be a contractive operator. Then  $f$  is a generalized contraction in Krasnoselskii' sense.*

*ii) Let  $(X, d)$  be a metric space,  $f : X \rightarrow X$  and  $\gamma : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  be a continuous mapping such that  $\gamma(t) > 0$  and for each  $t > 0$ . Suppose that for each  $x, y \in X$  the following assertion is satisfied:*

$$d(f(x), f(y)) \leq d(x, y) - \gamma(d(x, y)).$$

*Then  $f$  is a generalized contraction in Krasnoselskii' sense.*

A local result is the following:

**Theorem.** *Let  $E$  be a Banach space and  $f : B := \tilde{B}(0; r) \rightarrow E$  be a generalized contraction in Krasnoselskii' sense. Suppose  $f(\partial B) \subset B$ . Then  $\text{Fix} f = \{x^*\}$ .*



## 1.7 Graphic Contraction Principle

Let  $(X, d)$  be a metric space and  $f : X \rightarrow X$  be an operator. We denote by

$$\text{Graph}(f) := \{(x, f(x)) : x \in X\}$$

the graph of the operator  $f$ .

The contraction condition means that there exists  $\alpha \in ]0, 1[$  such that

$$d(f(x), f(y)) \leq \alpha d(x, y), \text{ for every } (x, y) \in X \times X.$$

If the above condition is assumed not for all  $(x, y) \in X \times X$ , but only for  $(x, y) \in \text{Graph}(f) := \{(x, f(x)) : x \in X\}$ , then we obtain a weaker assumption on  $f$ . The problem is now if we can obtain existence, uniqueness, data dependence of the fixed points of  $f$  under this weaker assumption on  $f$ . The following result is an existence theorem for the solution of the fixed point equation  $x = f(x)$  under the assumption that  $f$  is a graphic  $\alpha$ -contraction.

**Theorem (1972).** *Let  $(X, d)$  be a complete metric space,  $f : X \rightarrow X$  and  $\alpha \in [0, 1[$ . We suppose that:*

(a)  *$f$  is a graphic  $\alpha$ -contraction, i.e.,  $d(f(x), f^2(x)) \leq \alpha d(x, f(x))$ , for all  $x \in X$ ;*

(b) *the operator  $f$  has closed graph, i.e., the set  $\text{Graph}(f)$  is closed in  $X \times X$ .*

*Then:*

(i)  *$\text{Fix}(f) \neq \emptyset$ ;*

(ii)  *$f^n(x) \rightarrow f^\infty(x)$  as  $n \rightarrow \infty$ , and  $f^\infty(x) \in \text{Fix}(f)$ ,  $\forall x \in X$ ;*

(iii)  *$d(x, f^\infty(x)) \leq \frac{1}{1-\alpha} d(x, f(x))$ , for all  $x \in X$ .*

**Proof.** (i)+(ii). Let  $x \in X$  be arbitrary chosen. By (a), we have that  $x_n := f^n(x)$ , for  $n \in \mathbb{N}$  is a Cauchy sequence. Indeed, for any  $x \in X$ , we have

$$d(x_n, x_{n+1}) = d(f^n(x), f^{n+1}(x)) \leq \alpha d(f^{n-1}(x), f^n(x)) \leq \cdots \leq \alpha^n d(x, f(x)).$$

Then

$$d(x_n, x_{n+p}) \leq \frac{\alpha^n}{1-\alpha} \cdot d(x, f(x)), \text{ for each } n \in \mathbb{N} \text{ and each } p \in \mathbb{N}^*.$$

Thus,  $d(x_n, x_{n+p}) \rightarrow 0$  as  $n, p \rightarrow \infty$ . This shows that  $(x_n)$  is Cauchy.

Since  $(X, d)$  is a complete metric space it follows that  $(f^n(x))_{n \in \mathbb{N}}$  is convergent and we denote by  $f^\infty(x)$  its limit. By (b), since  $x_{n+1} = f(x_n)$  for each  $n \in \mathbb{N}$ , we have that  $f^\infty(x) \in \text{Fix}(f)$ , i.e.,  $\text{Fix}(f) \neq \emptyset$ .

(iii) We can write that

$$\begin{aligned} d(x, f^{n+1}(x)) &\leq d(x, f(x)) + d(f(x), f^2(x)) + \cdots + d(f^n(x), f^{n+1}(x)) \\ &\leq (1 + \alpha + \alpha^2 + \cdots + \alpha^n)d(x, f(x)). \end{aligned}$$

Then, letting  $n \rightarrow \infty$ , we have

$$d(x, f^\infty(x)) \leq \frac{1}{1-\alpha}d(x, f(x)), \text{ for all } x \in X.$$

□

**Exercise.** Show that, in the conditions of the Graphic Contraction Principle, we have that  $\text{Fix}(f^n) = \text{Fix}(f)$ , for every  $n \in \mathbb{N}$ .

**Exercise.** Let  $f : [0, 1] \rightarrow [0, 1]$  be defined by

$$f(x) := \begin{cases} 0, & x \in [0, \frac{1}{2}[ \\ 1, & x \in [\frac{1}{2}, 1], \end{cases}$$

Show that  $f$  is not a contraction, but  $f$  is a discontinuous graphic  $k$ -contraction (with any  $k \in ]0, 1[$ ) and  $\text{Fix}(f) = \{0, 1\}$ . Moreover, show that  $f^n(x) \rightarrow 0$  as  $n \rightarrow \infty$ , for every  $x \in [0, \frac{1}{2}[$  and  $f^n(x) \rightarrow 1$  as  $n \rightarrow \infty$ , for every  $x \in [\frac{1}{2}, 1]$ .

**Exercise.** Let  $X := [0, 1] \cup [2, 3]$  and  $f : X \rightarrow X$  be defined by

$$f(x) := \begin{cases} \frac{1}{2}x, & x \in [0, 1] \\ \frac{1}{2}x + \frac{3}{2}, & x \in [2, 3]. \end{cases}$$

Show that  $f$  is a continuous graphic  $\frac{1}{2}$ -contraction and  $\text{Fix}(f) = \{0, 3\}$ .

**Exercise.** Let  $f : [-1, 1] \rightarrow [-1, 1]$  be defined by

$$f(x) := \begin{cases} \frac{x}{2}, & x \neq 0 \\ \frac{1}{2}, & x = 0, \end{cases}$$

Show that  $f$  is a graphic  $\frac{1}{2}$ -contraction,  $f^n(x) \rightarrow 0$  as  $n \rightarrow \infty$ , for every  $x \in [-1, 1]$  and  $\text{Fix}(f) = \emptyset$ . Why it happens this ?

## 1.8 Caristi-Browder's Theorem

**Theorem (1976).** *Let  $(X, d)$  be a complete metric space,  $f : X \rightarrow X$  be an operator and  $\varphi : X \rightarrow \mathbb{R}_+$  be a functional. We suppose that:*

- (a)  $d(x, f(x)) \leq \varphi(x) - \varphi(f(x))$ , for all  $x \in X$ ;
- (b) the operator  $f$  has closed graph.

*Then:*

- (i)  $\text{Fix}(f) \neq \emptyset$ ;
- (ii)  $f^n(x) \rightarrow f^\infty(x)$  as  $n \rightarrow \infty$ , and  $f^\infty(x) \in \text{Fix}(f)$ ,  $\forall x \in X$ ;
- (iii) if there is  $\alpha \in \mathbb{R}_+^*$  such that  $\varphi(x) \leq \alpha d(x, f(x))$ , then

$$d(x, f^\infty(x)) \leq \alpha d(x, f(x)), \quad \text{for all } x \in X.$$

**Proof.** (i)+(ii). Let  $x \in X$  be arbitrary chosen. For  $n \in \mathbb{N}$ , let us denote  $a_{n+1} := \sum_{k=0}^n d(f^k(x), f^{k+1}(x))$ ,  $n \in \mathbb{N}$ . From (a) it follows that, for every  $n \in \mathbb{N}$ , we have

$$a_{n+1} = \sum_{k=0}^n d(f^k(x), f^{k+1}(x)) \leq \varphi(x) - \varphi(f^{n+1}(x)) \leq \varphi(x).$$

On the other hand,

$$a_{n+1} - a_n = d(f^n(x), f^{n+1}(x)) \geq 0, \quad \text{for every } n \in \mathbb{N}.$$

By the above two relation, we get that the sequence  $(a_n)_{n \in \mathbb{N}}$  is convergent. Hence,  $(a_n)_{n \in \mathbb{N}}$  is also Cauchy. Thus, for every  $\varepsilon > 0$  there exists  $n(\varepsilon) \in \mathbb{N}$  such that, for every  $n, m \geq n(\varepsilon)$ , we have that  $|a_m - a_n| < \varepsilon$ . On the other hand, for every  $n, m \geq n(\varepsilon)$  with  $m > n$  we have

$$\begin{aligned} d(f^n(x), f^m(x)) &\leq \sum_{k=0}^{m-1} d(f^k(x), f^{k+1}(x)) - \sum_{k=0}^{n-1} d(f^k(x), f^{k+1}(x)) = \\ &= a_m - a_n < \varepsilon. \end{aligned}$$

This implies that  $(f^n(x))_{n \in \mathbb{N}}$  is a Cauchy sequence and, hence, it is convergent in  $X$ . Let us denote by  $f^\infty(x)$  its limit. From (b) we have that  $f^\infty(x) \in \text{Fix}(f)$ .

$$(iii) \quad d(x, f^{n+1}(x)) \leq \sum_{k=0}^n d(f^k(x), f^{k+1}(x)) \leq \varphi(x) \leq \alpha d(x, f(x)).$$

So,  $d(x, f^\infty(x)) \leq \alpha d(x, f(x))$ , for all  $x \in X$ .  $\square$

**Exercise.** Show that, under the conditions of the above theorem, we have  $\text{Fix}(f) = \text{Fix}(f^n)$ , for every  $n \in \mathbb{N}$ .

**Exercise.** Let  $(X, d)$  be a complete metric space and  $f : X \rightarrow X$  be an  $\alpha$ -contraction. Show that  $f$  satisfies the Caristi condition:

$$d(x, f(x)) \leq \varphi(x) - \varphi(f(x)), \text{ for all } x \in X,$$

with a function  $\varphi$  which should be indicated.

## 1.9 Picard and weakly Picard operators

Let  $(X, d)$  be a metric space. An operator  $f : X \rightarrow X$  is called weakly Picard operator (*WPO*) if the sequence of successive approximations  $\{f^n(x)\}_{n \in \mathbb{N}}$  converges for all  $x \in X$  and its limit (which generally depend on  $x$ ) is a fixed point of  $f$ . If an operator  $f$  is *WPO* with a unique fixed point, i.e.,  $Fix(f) = \{x^*\}$ , then, by definition,  $f$  is called Picard operator (*PO*).

If  $f : X \rightarrow X$  is a *WPO*, we can define the operator

$$f^\infty : X \rightarrow Fix(f), \text{ given by } f^\infty(x) := \lim_{n \rightarrow \infty} f^n(x).$$

Notice that,  $f^\infty(X) = Fix(f)$  and the restriction of  $f^\infty$  to  $Fix(f)$  is the identity, i.e.,  $f^\infty$  is a set retraction of  $X$  on  $Fix(f)$ . Notice that in the case of a Picard operator with  $Fix(f) = \{x^*\}$ , then  $f^\infty(x) = x^*$ , for every  $x \in X$ .

In this context, if  $(X, d)$  is a metric space,  $f : X \rightarrow X$  is a *WPO* and  $\psi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is a function, then by definition  $f$  is a  $\psi$ -*WPO* if the following conditions hold:

- (a)  $\psi$  is increasing, continuous at 0 and  $\psi(0) = 0$ ;
- (b)  $d(x, f^\infty(x)) \leq \psi(d(x, f(x))), \forall x \in X$ .

In particular, if  $\psi(t) = ct$  for all  $t \in \mathbb{R}_+$  (for some  $c > 0$ ), then  $f$  is called a  $c$ -*WPO*.

**Exercise.** (i) Show that any  $\alpha$ -contraction and any Kannan type contraction on a complete metric space are  $c$ -*PO*; Find the corresponding value of  $c$  in each case.

(ii) Show that any graphic contraction with closed graph and any Caristi-Browder operator on a complete metric spaces are *WPO*. In this context, is a graphic contraction or a Caristi-Browder operator a  $\psi$ -*WPO*? Motivation. Find  $\psi$  if the answer is positive.

## 1.10 Gronwall type inequalities

Let  $X$  be a nonempty set,  $d : X \times X \rightarrow \mathbb{R}_+$  and  $\preceq$  be a binary relation on  $X$ . Then the triple  $(X, d, \preceq)$  is called an ordered metric space if:

- (i)  $(X, d)$  is a metric space;
- (ii)  $(X, \preceq)$  is an ordered set, i.e.,  $\preceq$  is an order relation (reflexive, transitive and antisymmetric) on  $X$ ;
- (iii) If  $(x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}}$  are sequences in  $X$  such that  $x_n \preceq y_n$  for every  $n \in \mathbb{N}$ ,  $x_n \rightarrow x, y_n \rightarrow y$  as  $n \rightarrow \infty$ , then  $x \preceq y$ .

**Theorem.** (Gronwall type lemma for Picard operators) *Let  $(X, d, \preceq)$  be an ordered metric space and  $f : X \rightarrow X$  be an operator. We suppose:*

- (a)  *$f$  is increasing;*
- (b)  *$f$  is a Picard operator (we denote by  $x^*$  its unique fixed point).*

*Then the following conclusions hold:*

- (1) *if  $x \in X$  with  $x \preceq f(x)$  then  $x \preceq x^*$ ;*
- (2) *if  $x \in X$  with  $x \succeq f(x)$  then  $x \succeq x^*$ .*

**Proof.** (1) Let  $x \in X$  such that  $x \preceq f(x)$ . Then, by (a), we have

$$x \preceq f(x) \preceq f^2(x) \preceq \cdots \preceq f^n(x), \forall n \in \mathbb{N}.$$

Passing to the limit as  $n \rightarrow \infty$  and using (iii) from the above definition and the fact that  $f$  is a Picard operator, we get that  $x \preceq x^*$ .

**Corollary.** (Gronwall type lemma for contractions) *Let  $(X, d, \preceq)$  be a complete ordered metric space and  $f : X \rightarrow X$  be an operator. We suppose:*

- (a)  *$f$  is increasing;*
- (b)  *$f$  is a contraction (we denote by  $x^*$  its unique fixed point).*

*Then the following conclusions hold:*

- (1) *if  $x \in X$  with  $x \preceq f(x)$ , then  $x \preceq x^*$ ;*
- (2) *if  $x \in X$  with  $x \succeq f(x)$ , then  $x \succeq x^*$ .*

## 1.11 Comparison theorems for weakly Picard operators

In the case of weakly Picard operators we have the following result.

**Theorem.** (Comparison theorem for two weakly Picard operators)  
 Let  $(X, d, \preceq)$  be an ordered metric space and  $f, g : X \rightarrow X$  be two given operators. We suppose:

- (a)  $g$  is increasing;
  - (b)  $f(x) \preceq g(x)$ , for every  $x \in X$ ;
  - (c)  $f, g$  are weakly Picard operators.
- Then, if  $x \preceq y$  then  $f^\infty(x) \preceq g^\infty(y)$ .

**Proof.** Let  $x, y \in X$  such that  $x \preceq y$ . Then, by (b) and (a), we have  $f(x) \preceq g(x) \preceq g(y)$ . Then, we have

$$f^2(x) \preceq g(f(x)) \preceq g(g(x)) = g^2(x) \preceq g(g(y)) = g^2(y).$$

Inductively, we have

$$f^n(x) \preceq g^n(x) \preceq g^n(y), \forall n \in \mathbb{N}.$$

Passing to the limit as  $n \rightarrow \infty$  and using (iii) from the definition of a ordered metric space and the fact that  $f$  is a weakly Picard operator, we get that  $f^\infty(x) \preceq g^\infty(y)$ .

**Exercise.** Write and prove a comparison theorem for the case of a graphic contraction.

**Theorem.** (Comparison theorem for three weakly Picard operators)  
 Let  $(X, d, \preceq)$  be an ordered metric space and  $f, g, h : X \rightarrow X$  be three given operators. We suppose:

- (a)  $g$  is increasing;
  - (b)  $f(x) \preceq g(x) \preceq h(x)$ , for every  $x \in X$ ;
  - (c)  $f, g, h$  are weakly Picard operators.
- Then, if  $x \preceq y \preceq z$  then  $f^\infty(x) \preceq g^\infty(y) \preceq h^\infty(z)$ .



## 1.12 Maia-Rus's fixed point theorem

The following result was proved by Maia in the paper M.G. Maia: *Un'osservazione sulle contrazioni metriche*, Rend. Sem. Mat. Univ. Padova, 40(1968), 139-143.

**Theorem (Maia).** *Let  $X$  be a nonempty set,  $d$  and  $\rho$  be two metrics on  $X$  and  $f : X \rightarrow X$  be an operator. We suppose that:*

- (1) *there exists  $c > 0$  such that,  $d(x, y) \leq c\rho(x, y)$ ,  $\forall x, y \in X$ ;*
- (2)  *$(X, d)$  is a complete metric space;*
- (3)  *$f : (X, d) \rightarrow (X, d)$  is continuous;*
- (4)  *$f : (X, \rho) \rightarrow (X, \rho)$  is an  $\alpha$ -contraction.*

*Then:*

- (i)  *$\text{Fix}(f) = \{x^*\}$ ;*
- (ii)  *$f : (X, d) \rightarrow (X, d)$  is a PO.*

**Proof.** Let  $x_0 \in X$  be arbitrary, and consider the sequence of successive approximations starting from  $x_0$ , i.e.,  $x_n := f^n(x_0)$ , for  $n \in \mathbb{N}^*$ . Then  $x_{n+1} = f(x_n)$ , for every  $n \in \mathbb{N}$ . The proof is organized in some steps:

I. By (4), it follows (in a similar way to the Contraction Principle) that the sequence  $(x_n)$  is Cauchy in  $(X, \rho)$ .

II. By (1) and I. it follows that the sequence  $(x_n)$  is Cauchy in  $(X, d)$  too, since  $d(x_n, x_{n+p}) \leq c\rho(x_n, x_{n+p}) \rightarrow 0$  as  $n, p \rightarrow \infty$ .

III. By (2) and II. it follows that the sequence  $(x_n)$  is convergent in  $(X, d)$ . We denote by  $x^*$  its limit, i.e.,  $x_n \rightarrow x^*$  with respect to  $d$ , as  $n \rightarrow \infty$ .

IV. By (3) and III., using the fact that  $x_{n+1} = f(x_n)$ , for every  $n \in \mathbb{N}$ , we obtain that  $x^* = f(x^*)$ .

V. By (4) and IV. we obtain (by reductio ad absurdum) that the fixed point is unique. This complete the proof.  $\square$

**Remark.** *Maia's Theorem remains true (see the paper I.A. Rus: On a fixed point theorem of Maia, *Studia Univ. Babeş-Bolyai Math.*, 22(1977), 40-42) if we replace the condition (1) with the following one:*

(1') *there exists  $c > 0$  such that,  $d(f(x), f(y)) \leq c\rho(x, y)$ ,  $\forall x, y \in X$ .*

*Hence, we obtain the so-called Rus's variant of Maia's fixed point theorem or Maia-Rus's Theorem.*

**Exercise.** Suppose that all the conditions in Maia's theorem are satisfied. Is  $f$  a  $\psi$ -PO with respect to  $d$  or with respect to  $\rho$ ? Motivation. Find  $\psi$  if the answer is positive.

## 1.13 Applications to operatorial equations

### 1.13.1 Integral equations

Let us consider first the following system of Volterra integral equations:

$$x(t) = \int_a^t K(t, s, x(s))ds + g(t), \quad t \in [a, b],$$

where  $g \in C([a, b], \mathbb{R}^n)$  and  $K \in C([a, b] \times [a, b] \times \mathbb{R}^n, \mathbb{R}^n)$ .

By a solution of the system we understand a map  $x \in C([a, b], \mathbb{R}^n)$  which satisfies the system for every  $t \in [a, b]$ .

We also suppose that the following Lipschitz condition holds: there exists  $L_K > 0$  such that

$$\|K(t, s, u) - K(t, s, v)\| \leq L_K \cdot \|u - v\|,$$

for each  $(t, s, u), (t, s, v) \in [a, b] \times [a, b] \times \mathbb{R}^n$ , where  $\|\cdot\|$  denotes a norm in  $\mathbb{R}^n$ .

Notice first that, if we introduce the operator

$$A : C([a, b], \mathbb{R}^n) \rightarrow C([a, b], \mathbb{R}^n), \quad x \longmapsto Ax,$$

defined by

$$Ax(t) := \int_a^t K(t, s, x(s))ds + g(t), \quad t \in [a, b],$$

then the above system of Volterra integral equations can be written as a fixed point equation of the form

$$x = Ax, \quad x \in X,$$

where  $X := C([a, b], \mathbb{R}^n)$  will be endowed by the following Bielecki type norm

$$\|x\|_B := \max_{t \in [a, b]} (\|x(t)\| e^{-\tau(t-a)}), \quad \text{where } \tau > 0.$$

Since  $(C([a, b], \mathbb{R}^n), \|\cdot\|_B)$  is a Banach space, in order to apply the Contraction principle for the above fixed point problem, we need to prove that  $A$  is a contraction. Indeed, we have:

$$\begin{aligned} \|Ax(t) - Ay(t)\| &\leq \int_a^t \|K(t, s, x(s)) - K(t, s, y(s))\| ds \leq L_K \int_a^t \|x(s) - y(s)\| ds \\ &= L_K \int_a^t \|x(s) - y(s)\| e^{-\tau(s-a)} e^{\tau(s-a)} ds \leq L_K \|x - y\|_B \int_a^t e^{\tau(s-a)} ds \\ &\leq \frac{L_K}{\tau} \|x - y\|_B e^{\tau(t-a)}, \text{ for each } t \in [a, b]. \end{aligned}$$

Thus, after multiplying with  $e^{-\tau(t-a)}$  and taking  $\max_{t \in [a, b]}$  we obtain that

$$\|Ax - Ay\|_B \leq \frac{L_K}{\tau} \|x - y\|_B, \text{ for every } x, y \in X.$$

Since  $\tau$  is arbitrary, we can choose  $\tau > L_K$  and thus  $L_A := \frac{L_K}{\tau} < 1$ . This shows that  $A$  is a contraction (with constant  $L_A$ ) on the Banach space  $X$ . By the Contraction Principle, the fixed point equation  $x = Ax$  has a unique solution  $x^* \in X$ . Moreover, this solution can be approximate by the sequence of successive approximations of  $A$ .

Hence, we proved the following result.

**Theorem.** (existence, uniqueness and approximation for the solution of a system of Volterra integral equations)

*Let us consider the following system of Volterra integral equations:*

$$x(t) = \int_a^t K(t, s, x(s)) ds + g(t), \quad t \in [a, b].$$

*We suppose:*

- (i)  $g \in C([a, b], \mathbb{R}^n)$  and  $K \in C([a, b] \times [a, b] \times \mathbb{R}^n, \mathbb{R}^n)$ ;
- (ii) there exists  $L_K > 0$  such that

$$\|K(t, s, u) - K(t, s, v)\| \leq L_K \cdot \|u - v\|,$$

for each  $(t, s, u), (t, s, v) \in [a, b] \times [a, b] \times \mathbb{R}^n$ , where  $\|\cdot\|$  denotes a norm in  $\mathbb{R}^n$ .

Then, the above system has a unique solution  $x^* \in C([a, b], \mathbb{R}^n)$  and the sequence  $(x_n)_{n \in \mathbb{N}}$  defined by

$$x_0 \in C([a, b], \mathbb{R}^n), x_{n+1}(t) := \int_a^t K(t, s, x_n(s)) ds + g(t), \quad t \in [a, b], n \in \mathbb{N}$$

converges (uniformly) in  $C([a, b], \mathbb{R}^n)$  to  $x^*$ .

**Exercise.** Let us consider the following system of Fredholm integral equations:

$$x(t) = \int_a^b K(t, s, x(s)) ds + g(t), \quad t \in [a, b],$$

where  $g \in C([a, b], \mathbb{R}^n)$  and  $K \in C([a, b] \times [a, b] \times \mathbb{R}^n, \mathbb{R}^n)$ .

By a solution of the above system we understand  $x \in C([a, b], \mathbb{R}^n)$  which satisfies the system for every  $t \in [a, b]$ .

We also suppose that the following Lipschitz condition holds: there exists  $L_K > 0$  such that

$$\|K(t, s, u) - K(t, s, v)\| \leq L_K \cdot \|u - v\|,$$

for each  $(t, s, u), (t, s, v) \in [a, b] \times [a, b] \times \mathbb{R}^n$ , where  $\|\cdot\|$  denotes a norm in  $\mathbb{R}^n$ .

Prove an existence, uniqueness and approximation result for the above system of Fredholm integral equations, working in the Banach space  $X := C([a, b], \mathbb{R}^n)$  endowed by the following Cebîsev type norm

$$\|x\|_C := \max_{t \in [a, b]} \|x(t)\|.$$

### 1.13.2 The Cauchy problem for a system of differential equations

Consider the following initial value problem (Cauchy problem):

$$(1) \quad x'(t) = f(t, x(t)), t \in [a, b]$$

$$(2) \quad x(t_0) = x^0,$$

where  $t_0 \in [a, b]$ ,  $x^0 \in \mathbb{R}^n$  are given and  $f : [a, b] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  is a continuous function such that  $f(t, \cdot) : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is  $L_f$ -Lipschitz.

By a solution of the above Cauchy problem we understand a map  $x \in C^1([a, b], \mathbb{R}^n)$  which satisfies (1) for every  $t \in [a, b]$  and (2).

**Lemma.** *Let us consider the Cauchy problem (1) + (2). We suppose that  $f : [a, b] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  is a continuous function. Then (1) + (2) is equivalent with the following Volterra integral equation*

$$(3) \quad x(t) = \int_{t_0}^t f(s, x(s))ds + x^0, \quad t \in [a, b].$$

By the main theorem of the above section, we have:

**Theorem** (existence, uniqueness and approximation result for the solution of the Cauchy problem (1) + (2))

*Let us consider the Cauchy problem (1) + (2). We suppose:*

$$(i) \quad f \in C([a, b] \times \mathbb{R}^n, \mathbb{R}^n);$$

(ii) *there exists  $L_f > 0$  such that*

$$\|f(t, u) - f(t, v)\| \leq L_f \|u - v\|, \quad \text{for every } t \in [a, b], u, v \in \mathbb{R}^n,$$

where  $\|\cdot\|$  denotes a norm in  $\mathbb{R}^n$ .

*Then, the Cauchy problem (1)+(2) has a unique solution  $x^*$  and the sequence  $(x_n)_{n \in \mathbb{N}} \subset C([a, b], \mathbb{R}^n)$ , given by*

$$x_{n+1}(t) = \int_{t_0}^t f(s, x_n(s))ds + x^0, \quad t \in [a, b], \quad n \in \mathbb{N}$$

*converges (uniformly) to  $x^*$ , for every  $x_0 \in C([a, b], \mathbb{R}^n)$ .*

**Proof.** The result follows by applying the existence, uniqueness and approximation for the solution of the following system of Volterra integral equations

$$(3) \quad x(t) = \int_{t_0}^t f(s, x(s))ds + x^0, \quad t \in [a, b].$$

Here the operator which must be considered is

$$Ax(t) := \int_{t_0}^t f(s, x(s))ds + x^0, \quad t \in [a, b].$$

### 1.13.3 The Dirichlet problem for a differential equation of second order

Consider the following boundary value problem (Dirichlet problem):

$$(1) \quad x''(t) = f(t, x(t)), \quad t \in [a, b]$$

$$(2) \quad x(a) = x(b) = 0,$$

where  $f : [a, b] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  is a continuous function such that the map  $f(t, \cdot) : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is  $L_f$ -Lipschitz.

By a solution of the above Dirichlet problem we understand a map  $x \in C^2([a, b], \mathbb{R}^n)$  which satisfies (1) for every  $t \in [a, b]$  and (2).

The following result is important in our approach.

**Lemma.** *Let us consider the Dirichlet problem (1) + (2). We suppose that  $f : [a, b] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  is a continuous function. Then (1) + (2) is equivalent with the following Fredholm integral equation*

$$(3) \quad x(t) = - \int_a^b G(t, s)f(s, x(s))ds, \quad t \in [a, b],$$

where  $G : [a, b] \times [a, b] \rightarrow \mathbb{R}_+$  is the following Green function associated to this problem

$$G(t, s) := \begin{cases} \frac{(b-t)(s-a)}{b-a}, & a \leq s \leq t \leq b \\ \frac{(b-s)(t-a)}{b-a}, & a \leq t < s \leq b. \end{cases}$$

**Remark.** We have the following properties of  $G$ :

- (a)  $G$  is continuous on  $[a, b] \times [a, b]$ ;
- (b)  $G$  is positive and symmetric;
- (c)  $G(t, s) \in [0, \frac{b-a}{4}]$ , for every  $t, s \in [a, b]$ ;
- (d)  $\int_a^b G(t, s) ds \in [0, \frac{(b-a)^2}{8}]$ , for every  $t \in [a, b]$ ;
- (e)  $\int_a^b |\frac{\partial G(t, s)}{\partial t}| ds \in [0, \frac{b-a}{2}]$ , for every  $t \in [a, b]$ .

Let us consider the operator

$$B : (C([a, b], \mathbb{R}^n), \|\cdot\|_C) \rightarrow (C([a, b], \mathbb{R}^n), \|\cdot\|_C), \quad x \mapsto Bx,$$

defined by

$$Bx(t) := - \int_a^b G(t, s) f(s, x(s)) ds, \quad t \in [a, b].$$

Then, the above Fredholm integral equation (3) (and, as a consequence of the Lemma, the Dirichlet problem (1) + (2)) is equivalent to the fixed point equation

$$x = Bx, \quad x \in X,$$

where  $X := (C([a, b], \mathbb{R}^n), \|\cdot\|_C)$  is a Banach space. The main problem now is to prove that (under some additional assumptions)  $B$  is a contraction.

We have the following existence, uniqueness and approximation result for the solution of the above Dirichlet problem.

**Theorem.** (existence, uniqueness and approximation result for the solution of the Dirichlet problem (1) + (2))

Consider the above Dirichlet problem (1) + (2). We suppose:

- (i)  $f : [a, b] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  is continuous;
- (ii) there exists  $L_f > 0$  such that

$$\|f(t, u) - f(t, v)\| \leq L_f \|u - v\|, \quad \text{for every } t \in [a, b], u, v \in \mathbb{R}^n,$$

where  $\|\cdot\|$  denotes a norm in  $\mathbb{R}^n$ ;

- (iii)  $\frac{L_f(b-a)^2}{8} < 1$ .



Then, the Dirichlet problem has a unique solution  $x^*$  which can be approximated by the following sequence of successive approximations

$$x_0 \in C([a, b], \mathbb{R}^n), \quad x_{n+1}(t) = - \int_a^b G(t, s) f(s, x_n(s)) ds, \quad t \in [a, b], n \in \mathbb{N}.$$

**Proof.** Under the above assumption the operator

$$B : (C([a, b], \mathbb{R}^n), \|\cdot\|_C) \rightarrow (C([a, b], \mathbb{R}^n), \|\cdot\|_C), \quad x \mapsto Bx,$$

defined by

$$Bx(t) := - \int_a^b G(t, s) f(s, x(s)) ds, \quad t \in [a, b]$$

is a contraction with constant  $L_B := \frac{L_f(b-a)^2}{8}$ . The conclusion follows by the Contraction Principle.  $\square$

### 1.13.4 Nonlinear alternative with an application to a Cauchy problem

By the Continuation Theorem we can obtain the following result which is useful in applications.

**Theorem.** (Nonlinear Alternative for Contractions) *Let  $E$  be a Banach space,  $X \in P_{cl,cv}(E)$  and  $U$  an open subset of  $X$  such that  $0 \in U$ . Let  $f : \bar{U} \rightarrow X$  be an  $\alpha$ -contraction such that  $f(\bar{U})$  is bounded. Then  $f$  has at least one of the following properties:*

(i)  $f$  has a unique fixed point

(ii) there exist  $y_0 \in \partial U$  and  $\lambda_0 \in ]0, 1[$  such that  $y_0 = \lambda_0 f(y_0)$ .

**Proof.** For  $(\lambda, x) \in [0, 1] \times \bar{U}$  we define:  $H_\lambda(x) := \lambda \cdot f(x)$ . Then,  $(H_\lambda)_{\lambda \in [0,1]}$  is an  $\alpha$ -contractive family of contractions with  $p = 1$ . Hence  $(H_\lambda)_{\lambda \in [0,1]} \subset CR(\bar{U}, X)$ .

a) if  $(H_\lambda)_{\lambda \in [0,1]} \subset CR_{\partial U}(\bar{U}, X)$  then, since  $H_0(0) = 0$ , we can apply the continuation theorem for contractions and we get that  $H_1 = f$  has a fixed point in  $U$ .

b) if  $(H_\lambda)_{\lambda \in [0,1]}$  is not in  $CR_{\partial U}(\bar{U}, X)$  then,  $H_\lambda = \lambda \cdot f$  has a fixed point in  $\partial U$  for some  $\lambda \in [0, 1]$ . Of course,  $\lambda \neq 0$  (since, if  $\lambda = 0$  then, because  $0 = H_0(0)$  we have  $0 \in \partial U$ , a contradiction with  $0 \in U$ ). Hence, in this case,  $f$  has a fixed point in  $\partial U$  (for  $\lambda = 1$ ) or (ii) holds.  $\square$

Consider the following initial value problem:

- (1)  $x'(t) = f(t, x(t)), t \in [0, T]$
- (2)  $x(0) = 0,$

where  $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$  is a continuous function.

Suppose that:

- (a) for each  $r > 0$  there is  $a_r \in \mathbb{R}$  such that  $|f(t, x) - f(t, y)| \leq a_r|x - y|$ , for each  $t \in [0, T]$  and each  $x, y \in [-r, r]$ ;
- (b) There exists a monotone increasing function  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+^*$  such that  $|f(t, x)| \leq \varphi(|x|)$ , for each  $t \in [0, T]$  and each  $x \in \mathbb{R}$ ;
- (c)  $T < \int_0^{+\infty} \frac{ds}{\varphi(s)}$ ;

Then the problem (1) + (2) has a unique solution  $x \in C^1[0, T]$ .

**Proof.** Consider, for  $\lambda \in [0, 1]$ , the following family of initial value problems:

- (1 $_\lambda$ )  $x'(t) = \lambda f(t, x(t)), t \in [0, T]$
- (2 $_\lambda$ )  $x(0) = 0,$

Let  $M > 0$  such that  $T < \int_0^M \frac{ds}{\varphi(s)} < \int_0^{+\infty} \frac{ds}{\varphi(s)}$ .

*Step 1.* For each solution  $x$  of (1 $_\lambda$ ) + (2 $_\lambda$ ) we have  $|x(t)| < M$ , for each  $t \in [0, T]$ .

Since  $|x'(t)| \leq |\lambda| \varphi(|x(t)|)$ , for each  $t \in [0, T]$ , we obtain, by integrating from 0 to  $t$  that

$$\int_0^t \frac{|x'(s)|}{\varphi(|x(s)|)} ds \leq \int_0^t \lambda ds.$$

If we change variables ( $v := |x(s)|$ ) then

$$\int_0^{|x(t)|} \frac{1}{\varphi(v)} dv \leq \lambda t \leq \lambda T \leq T < \int_0^M \frac{ds}{\varphi(s)}.$$

Thus  $|x(t)| < M$ , for each  $t \in [0, T]$ .

Let  $L := a_M > 0$ . Consider on  $C[0, T]$  the Bielecki type norm:

$$\|x\|_B := \max_{t \in [0, T]} (|x(t)| e^{-Lt}).$$

Define

$$U := \{x \in C[0, T] \mid |x(t)| < M, \forall t \in [0, T]\}.$$

Then  $0 \in U$  and  $U$  is open in  $C[0, T]$ .

Define  $G : \bar{U} \rightarrow C[0, T]$ ,  $x \mapsto Gx$ , where

$$Gx(t) := \int_0^t f(s, x(s)) ds.$$

*Step 2.* We show that  $G$  is a contraction.

Let  $x, y \in \bar{U}$ . Then:

$$\begin{aligned} |Gx(t) - Gy(t)| &\leq \int_0^t |f(s, x(s)) - f(s, y(s))| ds \leq \\ &L \int_0^t |x(s) - y(s)| e^{-Ls} e^{Ls} ds \leq (e^{Lt} - 1) \|x - y\|_B. \end{aligned}$$

Choose  $\alpha < 1$  such that  $e^{Lt} - 1 \leq \alpha e^{Lt}$ , for each  $t \in [0, T]$  (for example any  $\alpha \geq 1 - e^{-LT}$ ). Then:

$$\begin{aligned} |Gx(t) - Gy(t)| &\leq \alpha \|x - y\|_B e^{Lt}, \text{ for any } t \in [0, T]. \text{ As consequence,} \\ \|Gx - Gy\|_B &\leq \alpha \|x - y\|_B. \end{aligned}$$

*Step 3.* We prove that  $\lambda G$  is fixed point free on  $\partial U$ , i.e.,  $\nexists x \in \partial U$  such that  $x = \lambda Gx$ .

By contradiction, suppose that there is  $x \in \partial U$  such that  $x = \lambda Gx$ . Then

$$x(t) = \lambda \int_0^t f(s, x(s)) ds, \quad t \in [0, T].$$

Hence  $x'(t) = \lambda f(t, x(t))$ ,  $t \in [0, T]$  and  $x(0) = 0$ , showing that  $x$  is a solution for  $(1_\lambda) + (2_\lambda)$ . Then, by Step 1, we get that  $|x(t)| < M$ , for all  $t \in [0, T]$ . Thus  $x \in U$ , which is a contradiction with  $x \in \partial U$ .

*Step 4.* We prove that  $G(\bar{U})$  is bounded.

We have:

$$|Gx(t)| \leq \int_0^t |f(s, x(s))| ds \leq \int_0^t \varphi(|x(s)|) ds \leq \varphi(M) \cdot T,$$

for each  $t \in [0, T]$ . Hence  $\|G(x)\| \leq \varphi(M) \cdot T$ .

Then from the Nonlinear Alternative we get that  $G$  has a unique fixed point in  $x^* \in \bar{U}$ . This  $x^*$  is a solution of the problem (1) + (2).  $\square$ .

# Chapter 2

## Topological Fixed Point Theorems

### 2.1 Multivalued Analysis

The aim of this section is to present the main properties of some (generalized) functionals defined on the space of all subsets of a metric space. A special attention is paid to gap functional, excess functional and to Pompeiu-Hausdorff functional.

Let  $(X, d)$  be a metric space. Sometimes we will need to consider infinite-valued metrics, also called generalized metrics  $d : X \times X \rightarrow \mathbb{R}_+ \cup \{+\infty\}$ .

We denote by  $\mathcal{P}(X)$  the set of all subsets of a nonempty set  $X$ . Recall that, if  $X$  is a metric space,  $x \in X$  and  $R > 0$ , then  $B(x, R)$  and respectively  $\tilde{B}(x, R)$  denote the open, respectively the closed ball of radius  $R$  centered in  $x$ . Also, if  $X$  is a topological space and  $Y$  is a subset of  $X$ , then we will denote by  $\bar{Y}$  the closure and by  $int(Y)$  the interior of the set  $Y$ . Also, if  $X$  is a normed space and  $Y$  is a nonempty subset of  $X$ , then  $co(Y)$  respectively  $\overline{co}(Y)$  denote the convex hull, respectively the closed convex hull of the set  $Y$ .

We consider, for the beginning, the generalized diameter functional defined on the space of all subsets of a metric space  $X$ .

**Definition.** Let  $(X, d)$  be a metric space. The generalized diameter functional  $diam : \mathcal{P}(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\}$  is defined by:

$$diam(Y) = \begin{cases} \sup\{d(a, b) \mid a \in Y, b \in Y\}, & \text{if } Y \neq \emptyset \\ 0, & \text{if } Y = \emptyset \end{cases}$$

**Definition.** The subset  $Y$  of  $X$  is said to be bounded if and only if  $diam(Y) < \infty$ .

**Lemma.** Let  $(X, d)$  be a metric space and  $Y, Z$  nonempty bounded subsets of  $X$ . Then:

- i)  $diam(Y) = 0$  if and only if  $Y = \{y_0\}$ .
- ii) If  $Y \subset Z$  then  $diam(Y) \leq diam(Z)$ .
- iii)  $diam(\bar{Y}) = diam(Y)$ .
- iv) If  $Y \cap Z \neq \emptyset$  then  $diam(Y \cup Z) \leq diam(Y) + diam(Z)$ .
- v) If  $X$  is a normed space then:
  - a)  $diam(x + Y) = diam(Y)$ , for each  $x \in X$ .
  - b)  $diam(\alpha Y) = |\alpha|diam(Y)$ , where  $\alpha \in \mathbb{R}$ .
  - c)  $diam(Y) = diam(co(Y))$ .
  - d)  $diam(Y) \leq diam(Y + Z) \leq diam(Y) + diam(Z)$ .

**Proof.** iii) Because  $Y \subseteq \bar{Y}$  we have  $diam(Y) \leq diam(\bar{Y})$ . For the reverse inequality, let consider  $x, y \in \bar{Y}$ . Then there exist  $(x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}} \subset Y$  such that  $x_n \rightarrow x$  and  $y_n \rightarrow y$  as  $n \rightarrow \infty$ . It follows that  $d(x_n, y_n) \xrightarrow{\mathbb{R}} d(x, y)$ . Because  $d(x_n, y_n) \leq diam(Y)$ , for all  $n \in \mathbb{N}$  we get by passing to limit  $d(x, y) \leq diam(Y)$ . Hence  $diam(\bar{Y}) \leq diam(Y)$ .

iv) Let  $u, v \in Y \cup Z$ . We have the following cases:

- a) If  $u, v \in Y$  then  $d(u, v) \leq diam(Y) \leq diam(Y) + diam(Z)$  and so  $diam(Y \cup Z) \leq diam(Y) + diam(Z)$ .

b) If  $u, v \in Z$  then by an analogous procedure we have  $d(u, v) \leq \text{diam}(Z) \leq \text{diam}(Y) + \text{diam}(Z)$  and so  $\text{diam}(Y \cup Z) \leq \text{diam}(Y) + \text{diam}(Z)$ .

c) If  $u \in Y$  and  $v \in Z$  then choosing  $t \in Y \cap Z$  we have that  $d(u, v) \leq d(u, t) + d(t, v) \leq \text{diam}(Y) + \text{diam}(Z)$ . Hence,  $\text{diam}(Y \cup Z) \leq \text{diam}(Y) + \text{diam}(Z)$ .

v) c) Let us prove that  $\text{diam}(\text{co}(Y)) \leq \text{diam}(Y)$ . Let  $x, y \in \text{co}(Y)$ . Then there exist  $x_i, y_j \in Y$ ,  $\lambda_i, \mu_j \in \mathbb{R}_+$ , such that

$$x = \sum_{i=1}^n \lambda_i x_i, \quad y = \sum_{j=1}^m \mu_j y_j, \quad \sum_{i=1}^n \lambda_i = 1, \quad \sum_{j=1}^m \mu_j = 1.$$

From these relations we have:

$$\begin{aligned} \|x - y\| &= \left\| \sum_{i=1}^n \lambda_i x_i - \sum_{j=1}^m \mu_j y_j \right\| = \left\| \left( \sum_{j=1}^m \mu_j \right) \sum_{i=1}^n \lambda_i x_i - \left( \sum_{i=1}^n \lambda_i \right) \sum_{j=1}^m \mu_j y_j \right\| \\ &\leq \sum_{j=1}^m \sum_{i=1}^n \lambda_i \mu_j \|x_i - y_j\| \leq \left( \sum_{j=1}^m \sum_{i=1}^n \lambda_i \mu_j \right) \text{diam}(Y) = \text{diam}(Y). \end{aligned}$$

□

Let us consider now the following sets of subsets of a metric space  $(X, d)$ :

$$P(X) = \{Y \in \mathcal{P}(X) \mid Y \neq \emptyset\}; \quad P_b(X) = \{Y \in P(X) \mid \text{diam}(Y) < \infty\};$$

$$P_{op}(X) = \{Y \in P(X) \mid Y \text{ is open}\}; \quad P_{cl}(X) = \{Y \in P(X) \mid Y \text{ is closed}\};$$

$$P_{b,cl}(X) = P_b(X) \cap P_{cl}(X); \quad P_{cp}(X) = \{Y \in P(X) \mid Y \text{ is compact}\};$$

$$P_{cn}(X) = \{Y \in P(X) \mid Y \text{ is connex}\}.$$

If  $X$  is a normed space, then we denote:

$$P_{cv}(X) = \{Y \in P(X) \mid Y \text{ convex}\}; \quad P_{cp,cv}(X) = P_{cp}(X) \cap P_{cv}(X).$$

Let us define the following generalized functionals:

$$(1) D : \mathcal{P}(X) \times \mathcal{P}(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\}$$

$$D(A, B) = \begin{cases} \inf\{d(a, b) \mid a \in A, b \in B\}, & \text{if } A \neq \emptyset \neq B \\ 0, & \text{if } A = \emptyset = B \\ +\infty, & \text{if } A = \emptyset \neq B \text{ or } A \neq \emptyset = B. \end{cases}$$

$D$  is called the gap functional between  $A$  and  $B$ .

In particular,  $D(x_0, B) = D(\{x_0\}, B)$  (where  $x_0 \in X$ ) is called the distance from the point  $x_0$  to the set  $B$ .

$$(2) \delta : \mathcal{P}(X) \times \mathcal{P}(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\},$$

$$\delta(A, B) = \begin{cases} \sup\{d(a, b) \mid a \in A, b \in B\}, & \text{if } A \neq \emptyset \neq B \\ 0, & \text{otherwise} \end{cases}$$

$$(3) \rho : \mathcal{P}(X) \times \mathcal{P}(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\},$$

$$\rho(A, B) = \begin{cases} \sup\{D(a, B) \mid a \in A\}, & \text{if } A \neq \emptyset \neq B \\ 0, & \text{if } A = \emptyset \\ +\infty, & \text{if } B = \emptyset \neq A \end{cases}$$

$\rho$  is called the excess functional of  $A$  over  $B$ .

$$(4) H : \mathcal{P}(X) \times \mathcal{P}(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\},$$

$$H(A, B) = \begin{cases} \max\{\rho(A, B), \rho(B, A)\}, & \text{if } A \neq \emptyset \neq B \\ 0, & \text{if } A = \emptyset = B \\ +\infty, & \text{if } A = \emptyset \neq B \text{ or } A \neq \emptyset = B. \end{cases}$$

$H$  is called the generalized Pompeiu-Hausdorff functional of  $A$  and  $B$ .

Let us prove now that the functional  $H$  is a metric on the space  $P_{b,cl}(X)$ . First we will prove the following auxiliary result:

**Lemma.**  $D(b, A) = 0$  if and only if  $b \in \overline{A}$ .



**Proof.** We shall prove that  $\bar{A} = \{x \in X \mid D(x, A) = 0\}$ . For this aim, let  $x \in \bar{A}$  be arbitrarily. It follows that for each  $r > 0$  and for each  $B(x, r) \subset X$  we have  $A \cap B(x, r) \neq \emptyset$ . Then for each  $r > 0$  there exists  $a_r \in A$  such that  $d(x, a) < r$ . It follows that for each  $r > 0$  we have  $D(x, A) < r$  and hence  $D(x, A) = 0$ .  $\square$

**Theorem.** *Let  $(X, d)$  be a metric space. Then the pair  $(P_{b,cl}(X), H)$  is a metric space.*

**Proof.** We shall prove that the three axioms of the metric hold:

a)  $H(A, B) \geq 0$ , for all  $A, B \in P_{b,cl}(X)$  is obviously.

$H(A, B) = 0$  is equivalent with  $\rho(A, B) = 0$  and  $\rho(B, A) = 0$ , that means  $\sup_{a \in A} D(a, B) = 0$  and  $\sup_{b \in B} D(b, A) = 0$ . Hence  $D(a, B) = 0$ , for each  $a \in A$  and  $D(b, A) = 0$ , for each  $b \in B$ . Using Lemma 1.4. we obtain that  $a \in B$ , for all  $a \in A$  and  $b \in A$ , for all  $b \in B$ , proving that  $A \subseteq B$  and  $B \subseteq A$ .

b)  $H(A, B) = H(B, A)$  is quite obviously.

c) For the third axiom of the metric, let consider  $A, B, C \in P_{b,cl}(X)$ . For each  $a \in A$ ,  $b \in B$  and  $c \in C$  we have  $d(a, c) \leq d(a, b) + d(b, c)$ . It follows that  $\inf_{c \in C} d(a, c) \leq d(a, b) + \inf_{c \in C} d(b, c)$ , for all  $a \in A$  and  $b \in B$ . We get  $D(a, C) \leq d(a, b) + D(b, C)$ , for all  $a \in A$ ,  $b \in B$ . Hence  $D(a, C) \leq D(a, B) + H(B, C)$ , for all  $a \in A$  and so  $D(a, C) \leq H(A, B) + H(B, C)$ , for all  $a \in A$ . In conclusion, we have proved that  $\rho(A, C) \leq H(A, B) + H(B, C)$ . Similarly, we get  $\rho(C, A) \leq H(A, B) + H(B, C)$ , and so  $H(A, C) \leq H(A, B) + H(B, C)$ .  $\square$

**Remark.**  $H$  (or  $H_d$  if necessary) is called the Pompeiu- Hausdorff metric induced by the metric  $d$  on  $P_{b,cl}(X)$ . Notice also that  $H$  is a generalized metric (in the sense that  $H(A, B) \in \mathbb{R}_+ \cup +\infty$ ) on  $P_{cl}(X)$ .

**Lemma.** *Let the open balls  $A := B(x_0; r), B := B(y_0; s) \subset \mathbb{R}^n$ , where  $x_0, y_0 \in \mathbb{R}^n$  and  $r, s > 0$ . Then*

$$H(A, B) = \|x_0 - y_0\|_E + |r - s|,$$

where  $\|\cdot\|_E$  denotes the Euclidean norm in  $\mathbb{R}^n$ .

**Lemma.** *Let  $(X, d)$  a metric space. Then we have:*

i)  $D(\cdot, Y) : (X, d) \rightarrow \mathbb{R}_+$ ,  $x \mapsto D(x, Y)$ , (where  $Y \in P(X)$ ) is nonexpansive.

ii)  $D(x, \cdot) : (P_{cl}(X), H) \rightarrow \mathbb{R}_+$ ,  $Y \mapsto D(x, Y)$ , (where  $x \in X$ ) is nonexpansive.

**Proof.** i) We shall prove that for each  $Y \in P(X)$  we have

$$|D(x_1, Y) - D(x_2, Y)| \leq d(x_1, x_2), \text{ for all } x_1, x_2 \in X.$$

Let  $x_1, x_2 \in X$  be arbitrarily. Then for all  $y \in Y$  we have  $d(x_1, y) \leq d(x_1, x_2) + d(x_2, y)$ . Then  $\inf_{y \in Y} d(x_1, y) \leq d(x_1, x_2) + \inf_{y \in Y} d(x_2, y)$  and so  $D(x_1, Y) \leq d(x_1, x_2) + D(x_2, Y)$ . We have proved that  $D(x_1, Y) - D(x_2, Y) \leq d(x_1, x_2)$ . Interchanging the roles of  $x_1$  and  $x_2$  we obtain  $D(x_2, Y) - D(x_1, Y) \leq d(x_1, x_2)$ , proving the conclusion.

ii) We shall prove that for each  $x \in X$  we have:

$$|D(x, A) - D(x, B)| \leq H(A, B), \text{ for all } A, B \in P_{cl}(X).$$

Let  $A, B \in P_{cl}(X)$  be arbitrarily. Let  $a \in A$  and  $b \in B$ . Then we have  $d(x, a) \leq d(x, b) + d(b, a)$ . It follows  $D(x, A) \leq d(x, b) + D(b, A) \leq d(x, b) + H(B, A)$  and hence  $D(x, A) - D(x, B) \leq H(A, B)$ . By a similar procedure we get  $D(x, B) - D(x, A) \leq H(A, B)$  and so  $|D(x, A) - D(x, B)| \leq H(A, B)$ , for all  $A, B \in P_{cl}(X)$ .  $\square$

**Lemma.** *Let  $(X, d)$  be a metric space. Then the generalized functional  $\text{diam} : (P_{cl}(X), H) \rightarrow \mathbb{R}_+ \cup \{+\infty\}$  is continuous.*

Let us define now the notion of neighborhood for a nonempty set.

**Definition.** Let  $(X, d)$  be a metric space,  $Y \in P(X)$  and  $\varepsilon > 0$ . An open neighborhood of radius  $\varepsilon$  for the set  $Y$  is the set denoted  $V^0(Y, \varepsilon)$  and defined by  $V^0(Y, \varepsilon) = \{x \in X \mid D(x, Y) < \varepsilon\}$ . We also

consider the closed neighborhood for the set  $Y$ , defined by  $V(Y, \varepsilon) = \{x \in X \mid D(x, Y) \leq \varepsilon\}$ .

**Remark.** From the above definition we have that, if  $(X, d)$  is a metric space,  $Y \in P(X)$  then:

- a)  $\bigcup\{B(y, r) : y \in Y\} = V^0(Y, r)$ , where  $r > 0$ .
- b)  $\bigcup\{\tilde{B}(y, r) : y \in Y\} \subset V(Y, r)$ , where  $r > 0$ .
- c)  $V^0(Y, r + s) \supset V^0(V^0(Y, s), r)$ , where  $r, s > 0$ .
- d)  $V^0(Y, r)$  is an open set, while  $V(A, r)$  is a closed set.
- e) If  $(X, d)$  is a normed space, then:
  - i)  $V^0(Y, r + s) = V^0(V^0(Y, s), r)$ , where  $r, s > 0$
  - ii)  $V^0(Y, r) = Y + \text{int}(r\tilde{B}(0, 1))$ .

**Proof.** d)  $V^0(Y, r) = f^{-1}(]-\infty, r])$  and  $V(Y, r) = f^{-1}([0, r])$ , where  $f(x) = D(x, Y)$ ,  $x \in X$  is a continuous function.

**Lemma.** Let  $(X, d)$  a metric space. Then we have:

- i) If  $Y, Z \in P(X)$  then  $\delta(Y, Z) = 0$  if and only if  $Y = Z = \{x_0\}$
- ii)  $\delta(Y, Z) \leq \delta(Y, W) + \delta(W, Z)$ , for all  $Y, Z, W \in P_b(X)$ .
- iii) Let  $Y \in P_b(X)$  and  $q \in ]0, 1[$ . Then, for each  $x \in X$  there exists  $y \in Y$  such that  $q\delta(x, Y) \leq d(x, y)$ .

**Proof.** ii) Let  $Y, Z, W \in P_b(X)$ . Then we have:

$d(y, z) \leq d(y, w) + d(w, z)$ , for all  $y \in Y, z \in Z, w \in W$ . Then  $\sup_{z \in Z} d(y, z) \leq d(y, w) + \sup_{z \in Z} d(w, z)$ , for all  $y \in Y, w \in W$ . So  $\delta(y, Z) \leq \delta(y, w) + \delta(w, Z) \leq \delta(y, W) + \delta(W, Z)$  and hence  $\delta(Y, Z) \leq \delta(Y, W) + \delta(W, Z)$ .

iii) Suppose, by reductio ad absurdum, that there exists  $x \in X$  and there exists  $q \in ]0, 1[$  such that for all  $y \in Y$  to have  $q\delta(x, Y) > d(x, y)$ . It follows that  $q\delta(x, Y) \geq \sup_{y \in Y} d(x, y)$  and hence  $q\delta(x, Y) \geq \delta(x, Y)$ . In conclusion,  $q \geq 1$ , a contradiction.  $\square$

**Lemma.** Let  $(X, d)$  a metric space. Let  $Y, Z \in P(X)$  and  $q > 1$ . Then, for each  $y \in Y$  there exists  $z \in Z$  such that  $d(y, z) \leq qH(Y, Z)$ .

Some very important properties of the metric space  $(P_d(X), H_d)$  are contained in the following result:

**Theorem.** *i) If  $(X, d)$  is a complete metric space, then  $(P_d(X), H_d)$  is a complete metric space.*

*ii) If  $(X, d)$  is a totally bounded metric space, then  $(P_d(X), H_d)$  is a totally bounded metric space.*

*iii) If  $(X, d)$  is a compact metric space, then  $(P_d(X), H_d)$  is a compact metric space.*

*iv) If  $(X, d)$  is a separable metric space, then  $(P_{cp}(X), H_d)$  is a separable metric space.*

*v) If  $(X, d)$  is a  $\varepsilon$ -chainable metric space, then  $(P_{cp}(X), H_d)$  is also an  $\varepsilon$ -chainable metric space.*

**Proof.** i) We will prove that each Cauchy sequence in  $(P_d(X), H_d)$  is convergent. Let  $(A_n)_{n \in \mathbb{N}}$  be a Cauchy sequence in  $(P_d(X), H_d)$ . Let us consider the set  $A$  defined as follows:

$$A = \bigcap_{n=1}^{\infty} \left( \overline{\bigcup_{m=n}^{\infty} A_m} \right).$$

We have two steps in the proof:

1)  $A \neq \emptyset$ .

In this respect, consider  $\varepsilon > 0$ . Then for each  $k \in \mathbb{N}$  there is  $N_k \in \mathbb{N}$  such that for all  $n, m \geq N_k$  we have  $H(A_n, A_m) < \frac{\varepsilon}{2^{k+1}}$ . Let  $(n_k)_{k \in \mathbb{N}}$  be an increasing sequence of natural numbers such that  $n_k \geq N_k$ . Let  $x_0 \in A_{n_0}$ . Let us construct inductively a sequence  $(x_k)_{k \in \mathbb{N}}$  having the following properties:

$\alpha)$   $x_k \in A_{n_k}$ , for each  $k \in \mathbb{N}$

$\beta)$   $d(x_k, x_{k+1}) < \frac{\varepsilon}{2^{k+1}}$ , for each  $k \in \mathbb{N}$ .

Suppose that we have  $x_0, x_1, \dots, x_k$  satisfying  $\alpha)$  and  $\beta)$  and we will generate  $x_{k+1}$  in the following way.

We have:

$$D(x_k, A_{n_{k+1}}) \leq H(A_{n_k}, A_{n_{k+1}}) < \frac{\varepsilon}{2^{k+1}}.$$

It follows that there exists  $x_{k+1} \in A_{n_{k+1}}$  such that  $d(x_k, x_{k+1}) < \frac{\varepsilon}{2^{k+1}}$ .

Hence, we have proved that there exist a sequence  $(x_k)_{k \in \mathbb{N}}$  satisfying  $\alpha$ ) and  $\beta$ ).

From  $\beta$ ) we get that  $(x_k)_{k \in \mathbb{N}}$  is Cauchy in  $(X, d)$ . Because  $(X, d)$  is complete it follows that there exists  $x \in X$  such that  $x = \lim_{k \rightarrow \infty} x_k$ . I need to show now that  $x \in A$ . Since  $(n_k)_{k \in \mathbb{N}}$  is an increasing sequence it follows that for  $n \in \mathbb{N}^*$  there exists  $k_n \in \mathbb{N}^*$  such that  $n_{k_n} \geq n$ . Then  $x_k \in \bigcup_{m \geq n} A_m$ , for  $k \geq k_n$ ,  $n \in \mathbb{N}^*$  implies that  $x \in \bigcup_{m \geq n} A_m$ ,  $n \in \mathbb{N}^*$ . Hence  $x \in A$ .

2) In the second step of the proof, we will establish that  $H(A_n, A) \rightarrow 0$  as  $n \rightarrow \infty$ .

The following inequalities hold:

$$\begin{aligned} d(x_k, x_{k+p}) &\leq d(x_k, x_{k+1}) + \cdots + d(x_{k+p-1}, x_{k+p}) < \\ &< \frac{\varepsilon}{2^{k+1}} + \frac{\varepsilon}{2^{k+2}} + \cdots + \frac{\varepsilon}{2^{k+p}} < \varepsilon \left( 1 + \frac{1}{2} + \cdots + \frac{1}{2^k} + \cdots \right) = \\ &= \varepsilon \frac{1}{1 - \frac{1}{2}} = 2\varepsilon, \text{ for all } p \in \mathbb{N}^*. \end{aligned}$$

If in  $d(x_k, x_{k+p}) < 2\varepsilon$  we are letting  $p \rightarrow \infty$  we obtain  $d(x_k, x) < 2\varepsilon$ , for each  $k \in \mathbb{N}$ . In particular  $d(x_0, x) < 2\varepsilon$ . So, for each  $n_0 \in \mathbb{N}$ ,  $n_0 \geq N_0$  and for  $x_0 \in A_{n_0}$  there exists  $x \in A$  such that  $d(x_0, x) \leq 2\varepsilon$ , which imply

$$\rho(A_{n_0}, A) \leq 2\varepsilon, \text{ for all } n_0 \geq N_0 \quad (1).$$

On the other side, because the sequence  $(A_n)_{n \in \mathbb{N}}$  is Cauchy, it follows that there exists  $N_\varepsilon \in \mathbb{N}$  such that for  $\underline{m, n} \geq N_\varepsilon$  we have  $H(A_n, A_m) < \varepsilon$ . Let  $x \in A$  be arbitrarily. Then  $x \in \bigcup_{m=n}^{\infty} A_m$ , for  $n \in \mathbb{N}^*$ , which implies that there exist  $n_0 \in \mathbb{N}$ ,  $n_0 \geq N_\varepsilon$  and  $y \in A_{n_0}$  such that  $d(x, y) < \varepsilon$ .

Hence, there exists  $m \in \mathbb{N}$ ,  $m \geq N_\varepsilon$  and there is  $y \in A_m$  such that  $d(x, y) < \varepsilon$ .

Then, for  $n \in \mathbb{N}^*$ , with  $n \geq N_\varepsilon$  we have:

$$D(x, A_n) \leq d(x, y) + D(y, A_n) \leq d(x, y) + H(A_m, A_n) < \varepsilon + \varepsilon = 2\varepsilon.$$

So,

$$\rho(A, A_n) < 2\varepsilon, \text{ for each } n \in \mathbb{N} \text{ with } n \geq N_\varepsilon. \quad (2)$$

From (1) and (2) and choosing  $n_\varepsilon := \max\{N_0, N_\varepsilon\}$  it follows that  $H(A_n, A) < 2\varepsilon$ , for each  $n \geq n_\varepsilon$ . Hence  $H(A_n, A) \rightarrow 0$  as  $n \rightarrow \infty$ .

v)  $(X, d)$  being an  $\varepsilon$ -chainable metric space (where  $\varepsilon > 0$ ) it follows, by definition, that for all  $x, y \in X$  there exists a finite subset (the so-called  $\varepsilon$ -net) of  $X$ , let say  $x = x_0, x_1, \dots, x_n = y$  such that  $d(x_{k-1}, x_k) < \varepsilon$ , for all  $k = 1, 2, \dots, n$ .

Let  $y \in X$  arbitrary and  $Y = \{y\}$ . Obviously,  $Y \in P_{cp}(X)$ . Because the  $\varepsilon$ -chainability property is transitive, it is sufficient to prove that for all  $A \in P_{cp}(X)$  there exist an  $\varepsilon$ -net in  $P_{cp}(X)$  linking  $Y$  with  $A$ . We have two steps in our proof:

a) Let suppose first that  $A$  is a finite set, let say  $A = \{a_1, a_2, \dots, a_n\}$ . We will use the induction method after the number of elements of  $A$ . If  $n = 1$  then  $A = \{a\}$  and the conclusion follows from the  $\varepsilon$ -chainability of  $(X, d)$ . Let suppose now that the conclusion holds for each subsets of  $X$  consisting of at most  $n$  elements. Let  $A$  be a subset of  $X$  with  $n+1$  points,  $A = \{x_1, x_2, \dots, x_{n+1}\}$ . Using the  $\varepsilon$ -chainability of the space  $(X, d)$  it follows that there exist an  $\varepsilon$ -net in  $X$ , namely  $x_1 = u_0, u_1, \dots, u_m = x_2$  linking the points  $x_1$  and  $x_2$ . We obtain that the following finite set:  $A, \{u_1, x_2, \dots, x_{n+1}\}, \dots, \{u_{m-1}, x_2, \dots, x_{n+1}, \{x_2, \dots, x_{n+1}\}$  is an  $\varepsilon$ -net in  $P_{cp}(X)$  from  $A$  to  $B := \{x_2, \dots, x_{n+1}\}$ . But, from the hypothesis  $B$  is  $\varepsilon$ -chainable with  $Y$ , and hence  $A$  is  $\varepsilon$ -chainable with  $Y$  in  $P_{cp}(X)$ .

b) Let consider now  $A \in P_{cp}(X)$  be arbitrary.

$A$  being compact, there exists a finite family of nonempty compact subsets of  $A$ , namely  $\{A_k\}_{k=1}^n$ , having  $\text{diam}(A_k) < \varepsilon$  such that  $A =$

$\bigcup_{k=1}^n A_k$ . For each  $k = 1, 2, \dots, n$  we can choose  $x_k \in A_k$  and define  $C = \{x_1, \dots, x_n\}$ . Then for all  $z \in A$  there exists  $k \in \{1, 2, \dots, n\}$  such that  $D(z, C) \leq \delta(A_k)$ . We obtain:

$$\begin{aligned} H(A, C) &= \max \left\{ \sup_{z \in A} D(z, C), \sup_{y \in C} D(y, A) \right\} = \\ &= \sup_{z \in A} D(z, C) \leq \max_{1 \leq k \leq n} \delta(A_k) < \varepsilon, \end{aligned}$$

meaning that  $A$  is  $\varepsilon$ -chainable by  $C$  in  $P_{cp}(X)$ . Using the conclusion a) of this proof, we get that  $C$  is  $\varepsilon$ -chainable by  $Y$  in  $P_{cp}(X)$  and so we have proved that  $A$  is  $\varepsilon$ -chainable by  $Y$  in  $P_{cp}(X)$ .  $\square$

**Exercise.** 1) Let  $A = [0, 3]$ ,  $B = [1, 5]$  and  $C = [4, \infty[$ . Find:

- $diam(A)$ ,  $diam(C)$ ;
- $D(0, B)$ ,  $D(B, C)$ ,  $D(A, C)$ ;
- $\rho(A, C)$ ,  $\rho(C, A)$ ,  $\rho(A, B)$ ;
- $H(A, B)$ ,  $H(A, C)$ ,  $H(B, C)$ .

2) Let us consider the closed balls  $A := \tilde{B}((0, 1); 2)$ ,  $B := \tilde{B}((1, 3); 1)$  in  $\mathbb{R}^2$ . Find  $H(A, B)$  and  $D((3, 4); A)$ .

## 2.2 Nadler's Contraction Principle for Multi-valued Operators

Let  $X, Y$  be two nonempty sets. By a multivalued operator  $F : X \multimap Y$  we understand an operator  $F : X \rightarrow \mathcal{P}(Y)$  which assign (by a given rule) to every point  $x \in X$  a set  $F(x) \subset Y$ . Usually, we are working with multi-valued operators with nonempty values, i.e.,  $F : X \rightarrow P(Y)$ .

The graph of the multi-valued operator  $F$  is the set

$$Graph(F) := \{(x, y) \in X \times Y : y \in F(x)\}.$$

If  $Y = X$ , then a fixed point for  $F$  is an element  $x^* \in X$  with  $x^* \in F(x^*)$ , while a strict fixed point for  $F$  is an  $x^* \in X$  with  $F(x^*) = \{x^*\}$ . We denote by  $Fix(F)$  the fixed point set and by  $SFix(F)$  the strict fixed point set of  $F$ .

For a multi-valued operator  $F : X \rightarrow P(X)$ , the sequence of the successive approximations starting from  $x_0 \in X$  is a sequence  $(x_n)_{n \in \mathbb{N}}$  with  $x_{n+1} \in F(x_n)$ , for every  $n \in \mathbb{N}$ .

The following theorem was proved by Nadler in 1969 for multi-valued operators with nonempty, bounded and closed values and it was improved by Covitz and Nadler in 1970, for the case of multi-valued operators with closed values.

**Theorem.** (Nadler's Contraction Principle) *Let  $(X, d)$  be a complete metric space and  $F : X \rightarrow P_{cl}(X)$  be a multi-valued  $k$ -contraction, i.e.,  $k \in [0, 1[$  and*

$$H(F(x), F(y)) \leq kd(x, y), \text{ for every } x, y \in X.$$

*Then, the following conclusions hold:*

- (a)  $Fix(F) \neq \emptyset$ ;
- (b) for every  $(x_0, x_1) \in Graph(F)$  there exists a sequence  $(x_n)_{n \in \mathbb{N}}$  of successive approximations starting from  $x_0 \in X$  which converges to a fixed point of  $F$ .

**Proof.** Let  $x_0 \in X$  be arbitrary and choose  $x_1 \in F(x_0)$  also arbitrary. Let  $1 < q < \frac{1}{k}$ . Then, by the second Lemma on page 51, for  $x_1 \in F(x_0)$  there exists  $x_2 \in F(x_1)$  such that

$$d(x_1, x_2) \leq qH(F(x_0), F(x_1)).$$

Thus, by the contraction condition, we obtain

$$d(x_1, x_2) \leq qH(F(x_0), F(x_1)) \leq qkd(x_0, x_1).$$

let us denote by  $K := qk < 1$ . By an iterative procedure, we obtain a sequence  $(x_n)_{n \in \mathbb{N}}$  of successive approximations for  $F$  starting from  $x_0 \in X$



such that

$$d(x_n, x_{n+1}) \leq K^n d(x_0, x_1), \text{ for every } n \in \mathbb{N}.$$

By a standard procedure we can show that the sequence  $(x_n)_{n \in \mathbb{N}}$  is Cauchy in  $(X, d)$ . Thus, by the completeness of the space  $(X, d)$  the sequence  $(x_n)_{n \in \mathbb{N}}$  is convergent to an element  $x^* = x^*(x_0) \in X$ . We will show now that  $x^*$  is a fixed point of  $F$ . We can estimate

$$0 \leq D(x^*, F(x^*)) \leq d(x^*, x_{n+1}) + D(x_{n+1}, F(x^*)) \leq$$

$$d(x^*, x_{n+1}) + H(F(x_n), F(x^*)) \leq d(x^*, x_{n+1}) + kd(x_n, x^*), \text{ for every } n \in \mathbb{N}.$$

Letting  $n \rightarrow \infty$  we obtain that  $D(x^*, F(x^*)) = 0$ , so using the fact that  $F$  has closed values and Lemma on page 48 we get that  $x^* \in F(x^*)$ .  $\square$

**Exercise.** Let  $(X, d)$  be a complete metric space and  $F : X \rightarrow P_{cl}(X)$  be a multi-valued  $k$ -contraction. We suppose that  $SFix(F) \neq \emptyset$ . Show that  $Fix(F) = SFix(F) = \{x^*\}$ .

## 2.3 Schauder's Fixed Point Theorems

### 2.3.1 $K^2M$ operators

Let  $X$  be a linear space over  $\mathbb{R}$ . A subset  $A$  of  $X$  is called a linear subspace if for all  $x, y \in A$  we have that  $x + y \in A$  and for all  $x \in X$  and each  $\lambda \in \mathbb{R}$  we have  $\lambda \cdot x \in A$ .

Let  $A$  be a nonempty subset of  $X$ .

Then, the linear hull (or the span) of  $A$ , denoted by  $span(A)$  is, by definition, the intersection of all subspaces which contains  $A$ , i.e., the smallest linear subspace containing  $A$ . We have the following characterization of the linear hull.

$$span(A) = \left\{ x \in X \mid x = \sum_{i=1}^n \lambda_i \cdot x_i, \text{ with } x_i \in A, \lambda_i \in \mathbb{R}, n \in \mathbb{N} \right\}.$$

If  $A \subset \mathbb{R}^2$  and  $A = \{p\}$  with  $p \neq 0$ , then  $span(A)$  is the line through  $p$  and the origin.

Similarly, the affine hull, denoted by  $aff(A)$  is defined by

$$aff(A) = \{x \in X \mid x = \sum_{i=1}^n \lambda_i \cdot x_i, \sum_{i=1}^n \lambda_i = 1, x_i \in A, \lambda_i \in \mathbb{R}, n \in \mathbb{N}\}.$$

If  $A = \{x_1, x_2\} \subset \mathbb{R}^2$ , then  $aff(A)$  is the line through  $x_1$  and  $x_2$ .

Finally, we define the convex hull of  $A$ , denoted by  $co(A)$ , as the intersection of all convex subsets of  $X$  which contains  $A$ , i.e.,  $co(A)$  is the smallest convex set which contains  $A$ . We have the following characterization of  $coA$ .

$$co(A) = \{x \in X \mid x = \sum_{i=1}^n \lambda_i \cdot x_i, \sum_{i=1}^n \lambda_i = 1, x_i \in A, \lambda_i \in [0, 1], n \in \mathbb{N}\}.$$

Of course,  $co(A) \subset aff(A) \subset span(A)$ .

Similarly, we denote by  $\overline{co}(A)$  is the intersection of all convex and closed subsets of  $X$  which contains  $A$ , i.e.,  $\overline{co}(A)$  is the smallest convex and closed set which contains  $A$ .

Also, a  $k$ -dimensional flat (or a linear  $k$ -variety) in  $X$  is a subset  $L$  of  $X$  with  $dimL = k$  such that for each  $x, y \in L$ , with  $x \neq y$ , the whole line joining  $x$  and  $y$  is included in  $L$ , i.e.,

$$(1 - \lambda) \cdot x + \lambda \cdot y \in L, \text{ for each } \lambda \in \mathbb{R}.$$

The basic fixed point theorem in a topological setting was given by Bohl-Brouwer-Hadamard in 1904-1909-1910.

**Brouwer's Fixed Point Theorem.** *Let  $Y$  be a compact convex subset of a finite dimensional Banach space  $X$  and  $f : Y \rightarrow Y$  be a continuous operator. Then there exists at least one fixed point for  $f$ .*

**Definition.** A subset  $A$  of a linear space  $X$  is said to be finitely closed if its intersection with any finite-dimensional flat  $L \subset X$  is closed in the Euclidean topology of  $L$ .

If  $X$  is a linear topological space, then any closed subset of  $X$  is finitely closed.

**Definition.** A family  $\{A_i \mid i \in I\}$  of sets is said to have the finite intersection property if the intersection of each finite sub-family is not empty.

We present now the concept of KKM operator, using the definition given by Ky Fan.

**Definition.** Let  $X$  be a linear space and  $Y$  be a nonempty subset of  $X$ . The multivalued operator  $G : Y \rightarrow P(X)$  is called a Kuratowski-Knaster-Mazurkiewicz operator (briefly  $K^2M$  operator) if and only if

$$\text{co}\{x_1, \dots, x_n\} \subset \bigcup_{i=1}^n G(x_i),$$

for each finite subset  $\{x_1, \dots, x_n\} \subset Y$ .

The main property of  $K^2M$  operators is given in the following theorem. We have here the Ky Fan variant (1961) of the originally KKM principle (1929).

**Theorem.** ( $K^2M$  principle) *Let  $X$  be a linear space,  $Y$  be a nonempty subset of  $X$  and  $G : Y \rightarrow P(X)$  be a  $K^2M$  operator such that  $G(x)$  is finitely closed (or, in particular, closed), for each  $x \in Y$ . Then the family  $\{G(x) \mid x \in Y\}$  of sets has the finite intersection property.*

**Proof.** We argue by contradiction: assume that there exist  $\{x_1, \dots, x_n\} \subset Y$  such that  $\bigcap_{i=1}^n G(x_i) = \emptyset$ . Denote by  $L$  the finite dimensional flat spanned by  $\{x_1, \dots, x_n\}$ , i.e.,  $L = \text{span}\{x_1, \dots, x_n\}$ . Let us denote by  $d$  the Euclidean metric in  $L$  and by  $C := \text{co}\{x_1, \dots, x_n\} \subset L$ .

Because  $L \cap G(x_i)$  is closed in  $L$ , for all  $i \in \{1, 2, \dots, n\}$  we have that:

$$D_d(x, L \cap G(x_i)) = 0 \Leftrightarrow x \in L \cap G(x_i), \text{ for all } i = \overline{1, n}.$$

Since  $\bigcap_{i=1}^n [L \cap G(x_i)] = \emptyset$  it follows that the map  $\lambda : C \rightarrow \mathbb{R}$  given by

$$\lambda(c) = \sum_{i=1}^n D_d(c, L \cap G(x_i)) \neq 0, \text{ for each } c \in C.$$

Hence we can define the continuous map  $f : C \rightarrow C$  by the formula

$$f(c) = \frac{1}{\lambda(c)} \sum_{i=1}^n D_d(c, L \cap G(x_i))x_i.$$

By Brouwer's fixed point theorem there is a fixed point  $c_0 \in C$  of  $f$ , i.e.,  $f(c_0) = c_0$ . Let

$$I = \{i \mid D_d(c_0, L \cap G(x_i)) \neq 0\}.$$

Then for  $i \in I$  we have  $c_0 \notin L \cap G(x_i)$  which implies

$$c_0 \notin \bigcup_{i \in I} G(x_i).$$

On the other side:

$$c_0 = f(c_0) \in \text{co}\{x_i \mid i \in I\} \subset \bigcup_{i \in I} G(x_i),$$

where last inclusion follows by the  $K^2M$  assumption of  $G$ . This is a contradiction, which proves the result.  $\square$

As an immediate consequence we obtain the following theorem:

**Corollary.** (Ky Fan) *Let  $X$  be a linear topological space,  $Y$  be a nonempty subset of  $X$  and  $G : Y \rightarrow P_{cl}(X)$  be a  $K^2M$  operator. If, for  $x \in X$ , at least one of the sets  $G(x)$  is compact, then*

$$\bigcap_{x \in Y} G(x) \neq \emptyset.$$

### 2.3.2 First Schauder's Fixed Point Theorem

One of the simplest application of  $K^2M$  principle is the well-known best approximation theorem of Ky Fan.

**Lemma.** (Ky Fan-Best approximation theorem) *Let  $X$  be a normed space,  $Y$  be a compact convex subset of  $X$  and  $f : Y \rightarrow X$  be a continuous operator. Then there exists at least one  $y_0 \in Y$  such that*

$$\|y_0 - f(y_0)\| = \inf_{x \in Y} \|x - f(y_0)\|.$$

**Proof.** Define  $G : Y \rightarrow P(X)$  by

$$G(x) = \{y \in Y \mid \|y - f(y)\| \leq \|x - f(y)\|\}.$$

Because  $f$  is continuous, the sets  $G(x)$  are closed in  $Y$  and therefore compact. We verify that  $G$  is a  $K^2M$  operator. For, let  $y \in \text{co}\{x_1, \dots, x_n\} \subset Y$ . Suppose, by contradiction, that  $y \notin \bigcup_{i=1}^n G(x_i)$ . Then  $\|y - f(y)\| > \|x_i - f(y)\|$  for  $i \in \{1, 2, \dots, n\}$ . This shows that all the points  $x_i$  lie in an open ball of radius  $\|y - f(y)\|$  centered at  $f(y)$ . Therefore, the convex hull of it is also there and in particular  $y$ . Thus  $\|y - f(y)\| > \|y - f(y)\|$ , which is a contradiction. By the compactness of  $G(x)$  we find a point  $y_0$  such that  $y_0 \in \bigcap_{x \in Y} G(x)$  and hence  $\|y_0 - f(y_0)\| \leq \|x - f(y_0)\|$ , for all  $x \in Y$ . This clearly implies  $\|y_0 - f(y_0)\| = \inf_{x \in Y} \|x - f(y_0)\|$  and the proof is complete.  $\square$

**Theorem.** *Let  $Y$  be a compact convex subset of a Banach space  $X$ . Let  $f : Y \rightarrow X$  be a continuous operator such that for each  $x \in Y$  with  $x \neq f(x)$ , the line segment  $[x, f(x)]$  contains at least two points of  $Y$ . Then  $f$  has at least a fixed point.*

**Proof.** By the previous Lemma, we obtain an element  $y_0 \in Y$  with  $\|y_0 - f(y_0)\| = \inf_{x \in Y} \|x - f(y_0)\|$ . We will show that  $y_0$  is a fixed point of  $f$ . The segment  $[y_0, f(y_0)]$  must contain a point of  $Y$  other than  $y_0$ , let say  $x$ . Then  $x = ty_0 + (1-t)f(y_0)$ , with some  $t \in ]0, 1[$ . Then  $\|y_0 - f(y_0)\| \leq t\|y_0 - f(y_0)\|$  and since  $t < 1$ , we must have  $\|y_0 - f(y_0)\| = 0$ .  $\square$

**Corollary.** (Schauder I) *Let  $Y$  be a compact convex subset of a Banach space  $X$ . Let  $f : Y \rightarrow Y$  be a continuous operator. Then  $f$  has at least a fixed point.*

### 2.3.3 Second and Third Schauder's Fixed Point Theorem

**Definition.** Let  $X, Y$  be two Banach spaces,  $K \subseteq X$  and  $f : K \rightarrow Y$ . Then  $f$  is called:

- 1) continuous, if  $x_n \in K$ ,  $n \in \mathbb{N}$  with  $x_n \rightarrow x \in K$  as  $n \rightarrow +\infty$  implies  $f(x_n) \rightarrow f(x)$  as  $n \rightarrow +\infty$ ;
- 2) with closed graph, if  $x_n \in K$ ,  $n \in \mathbb{N}$  with  $x_n \rightarrow x$  and  $f(x_n) \rightarrow y$  as  $n \rightarrow +\infty$  implies  $x \in K$  and  $y = f(x)$ ;
- 3) bounded, if for each bounded subset  $A$  of  $K$ , implies  $f(A)$  is bounded in  $Y$ ;
- 4) compact, if for each bounded subset  $A$  of  $K$  the set  $f(A)$  is relatively compact in  $Y$ ;
- 5) completely continuous, if  $f$  is continuous and compact;
- 6) with relatively compact range, if  $f$  is continuous and  $f(K)$  is relatively compact in  $Y$  (i.e.,  $\overline{f(K)}$  is compact);

Two well-known results are:

**Lemma.** a) *Let  $f : K \rightarrow Y$  be a continuous function and  $A \subset K$  be compact. Then  $f(A)$  is compact too.*

b) *If  $M$  is a compact set and  $Z \subseteq M$ , then  $Z$  is relatively compact.*

**Remark.** i) If  $f : K \rightarrow Y$  is with relatively compact range, then  $f$  is completely continuous.

ii) Suppose  $X$  is a finite dimensional space,  $K \subseteq X$  is closed and  $f : K \subset X \rightarrow Y$ . Then  $f$  is completely continuous if and only if  $f$  is continuous.

**Proof.** i) If  $f$  is with relatively compact range, then  $\overline{f(K)}$  is compact in  $Y$ . Let  $A \subset K$  be bounded. Then,  $f(A) \subset f(K) \subset \overline{f(K)}$ . Hence  $f(A)$

is relatively compact.

ii) Let  $A$  be a bounded subset of  $K$ . Then  $\overline{A}$  is a compact set (since the space  $X$  is finite dimensional). Then,  $f(\overline{A})$  is a compact set. From  $f(A) \subset f(\overline{A})$  and by the previous Lemma b), we get that  $f(A)$  is relatively compact.  $\square$

Recall now a very important theorem in functional analysis.

**Mazur's Theorem.** *a) Let  $X$  be a Banach space and  $M$  be a relatively compact subset of it. Then  $\text{co}(M)$  is relatively compact.*

*b) Let  $X$  be a Banach space and  $M$  be a relatively compact subset of it. Then  $\overline{\text{co}}(M)$  is compact.*

*c) If  $X$  is a finite dimensional normed space and  $M \subset X$  is compact, then  $\text{co}(M)$  is compact too.*

The next result (Schauder' second theorem) is very useful for applications.

**Theorem.** (Schauder II) *Let  $Y$  be a bounded closed convex subset of a Banach space  $X$ . Let  $f : Y \rightarrow Y$  be a completely continuous operator. Then  $f$  has at least a fixed point.*

**Proof.** Since  $f$  is completely continuous and  $Y$  is bounded we have that  $f(Y)$  is relatively compact in  $X$ . From Mazur's theorem we know that the closed convex hull of a relatively compact subset of a Banach space is compact. Hence  $K := \overline{\text{co}}(f(Y))$  is compact and convex. Since  $Y$  is closed and convex and  $f(Y) \subset Y$  we get that  $K \subset Y$ . Then

$$f(K) \subseteq f(Y) \subseteq K := \overline{\text{co}}(f(Y)).$$

Thus  $f : K \rightarrow K$ . Also,  $K \in P_{cp,cv}(X)$ . By Schauder I, we obtain that  $\text{Fix}(f) \neq \emptyset$ .  $\square$

By Schauder I we immediately obtain the following result.

**Theorem.** (Schauder III) *Let  $Y$  be a closed convex subset of a Banach space  $X$ . Let  $f : Y \rightarrow Y$  be an operator with relatively compact range. Then  $f$  has at least a fixed point.*

**Proof.** Since  $f$  is with relatively compact range, we have that  $f$  is continuous and  $f(Y)$  is relatively compact in  $X$ . From Mazur's theorem we get that  $K := \overline{\text{co}}(f(Y))$  is compact and convex. Since  $Y$  is closed and convex and  $f(Y) \subset Y$  we get that  $K \subset Y$ . Thus  $f : K \rightarrow K$ . By Schauder I we get the conclusion.

## 2.4 Applications

Let  $(X, d)$  be a compact metric space and denote

$$C(X, \mathbb{R}) := \{f : X \rightarrow \mathbb{R} \mid f \text{ continuous}\}.$$

Then  $(C(X, \mathbb{R}), \|\cdot\|_{C,B})$  is a Banach space.

**Definition.** A subset  $Y \subset C(X, \mathbb{R})$  is said called:

i) bounded if there is  $M > 0$  such that  $|u(x)| \leq M$ , for each  $u \in Y$  and each  $x \in X$ ;

ii) echicontinuous if for each  $\epsilon > 0$  there is  $\delta > 0$  such that the following implication holds:

$$d(x_1, x_2) < \delta \quad \Rightarrow \quad |u(x_1) - u(x_2)| < \epsilon, \quad \forall u \in Y.$$

**Theorem.** (Ascoli-Arzela)  $Y \subset C(X, \mathbb{R})$  is relatively compact if and only if  $Y$  is bounded and echicontinuous.

**Theorem.** (The Fredholm integral operator)

Let  $K : [a, b] \times [a, b] \times [-R, R] \rightarrow \mathbb{R}$  continuous. Consider the Fredholm integral operator

$$T : C[a, b] \rightarrow C[a, b], \quad u \longmapsto Tu$$

given by

$$Tu(x) := \int_a^b K(x, s, u(s)) ds, \quad x \in [a, b].$$

Then  $T$  is completely continuous.



**Proof.** 1) The continuity of  $T$ .

Let  $u_0 \in C[a, b]$  be arbitrary and  $\varepsilon > 0$ . We will prove that  $T$  is continuous in  $u_0$ , i.e., for  $\varepsilon > 0$  there exists  $\delta(u_0, \varepsilon) > 0$  such that, if  $u \in C[a, b]$  with  $\|u - u_0\| \leq \delta$  implies  $\|Tu - Tu_0\| \leq \varepsilon$ .

Since  $K$  is continuous on the compact set  $W := [a, b] \times [a, b] \times [-R, R]$ , it is uniformly continuous with respect to the third variable. Hence, there exists  $\delta_1(\varepsilon) > 0$  such that for any  $p, q \in [-R, R]$  with  $|p - q| < \delta_1(\varepsilon)$  implies  $|K(x, s, p) - K(x, s, q)| < \frac{\varepsilon}{b-a}$ , for each  $(x, s) \in [a, b] \times [a, b]$ .

Then, there exists  $\delta(u_0, \varepsilon) := \delta_1(\varepsilon) > 0$  such that for each  $u \in C[a, b]$  with  $\|u - u_0\| \leq \delta$  we have  $|K(x, s, u(s)) - K(x, s, u_0(s))| < \frac{\varepsilon}{b-a}$ , for each  $(x, s) \in [a, b] \times [a, b]$ .

Thus,  $|Tu(x) - Tu_0(x)| \leq \int_a^b |K(x, s, u(s)) - K(x, s, u_0(s))| ds \leq \varepsilon$ , for each  $x \in [a, b]$ . Taking the  $\sup_{x \in [a, b]}$  we get that  $\|Tu - Tu_0\| \leq \varepsilon$ .

2) We will prove now that  $T$  is compact, i.e. for each bounded subset  $Y$  of  $C[a, b]$  the set  $\overline{T(Y)}$  is compact.

By Ascoli-Arzelà, it is enough to prove that  $T(Y)$  is bounded and equicontinuous.

i) We prove first that  $T(Y)$  is bounded, i.e., there exists  $M > 0$  such that  $\|v\| \leq M$ , for every  $v \in T(Y)$ .

We have:  $|Tu(x)| \leq \int_a^b |K(x, s, u(s))| ds \leq M_K(b-a) := M$  (where  $M_K := \max_{(x,s,p) \in W} |K(x, s, p)|$ ). By taking  $\sup_{x \in [a, b]}$ , we get  $v := \|Tu\| \leq M$ , for each  $u \in Y$ .

ii) We prove now that  $T(Y)$  is equicontinuous.

Since  $K$  is uniformly continuous on  $W := [a, b] \times [a, b] \times [-R, R]$  with respect to the first variable we can write that there exists  $\delta_2(\varepsilon) > 0$  such that for any  $x_1, x_2 \in [a, b]$  with  $|x_1 - x_2| < \delta_2(\varepsilon)$  implies  $|K(x_1, s, p) - K(x_2, s, p)| < \frac{\varepsilon}{b-a}$ , for each  $(s, p) \in [a, b] \times [-R, R]$ . Hence there exists  $\delta_2(\varepsilon) > 0$  such that for any  $x_1, x_2 \in [a, b]$  with  $|x_1 - x_2| < \delta_2(\varepsilon)$  and any  $u \in Y$  we have  $|K(x_1, s, u(s)) - K(x_2, s, u(s))| < \frac{\varepsilon}{b-a}$ , for each  $s \in [a, b]$ .

Thus,  $|Tu(x_1) - Tu(x_2)| \leq \int_a^b |K(x_1, s, u(s)) - K(x_2, s, u(s))| \leq \frac{\varepsilon}{b-a}(b-a) = \varepsilon$ . As a conclusion,  $T(Y)$  is equicontinuous.  $\square$

**Remark.** a) Let  $K : [a, b] \times [a, b] \times [-R, R] \rightarrow \mathbb{R}$  and  $g : [a, b] \rightarrow \mathbb{R}$  be continuous. Consider the Fredholm-type integral operator

$$T : C[a, b] \rightarrow C[a, b] \quad u \longmapsto Tu$$

given by

$$Tu(x) := \int_a^b K(x, s, u(s))ds + g(x), \quad x \in [a, b].$$

Then  $T$  is completely continuous.

b) Let  $K : [a, b] \times [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$  be continuous. Consider the Fredholm integral operator

$$T : C[a, b] \rightarrow C[a, b]$$

$$u \longmapsto Tu$$

given by

$$Tu(x) := \int_a^b K(x, s, u(s))ds, \quad x \in [a, b].$$

Then  $T$  is completely continuous.

An existence result for Fredholm integral equation is:

**Theorem.** Let  $K : [a, b] \times [a, b] \times [-R, R] \rightarrow \mathbb{R}$  be continuous. Consider the Fredholm integral equation:

$$u(x) = \lambda \int_a^b K(x, s, u(s))ds, \quad x \in [a, b].$$

Suppose that  $|\lambda| \leq \frac{R}{M_K(b-a)}$ , where  $M_K := \max_{(x,s,p) \in W} |K(x, s, p)|$  (here  $W := [a, b] \times [a, b] \times [-R, R]$ ).

Then there at least one  $u^* \in \tilde{B}(0; R) \subset C[a, b]$  a solution to the above Fredholm integral equation.

**Proof.** Using the previous theorem we have that the Fredholm integral operator

$$\begin{aligned} T : \tilde{B}(0; R) \subset C[a, b] &\rightarrow C[a, b] \\ u &\longmapsto Tu \end{aligned}$$

given by

$$Tu(x) := \lambda \int_a^b K(x, s, u(s)) ds, \quad x \in [a, b]$$

is completely continuous.

We will prove now that the set  $\tilde{B}(0; R)$  is invariant with respect to  $T$ . Indeed, let  $u \in \tilde{B}(0; R)$ . We will show that  $Tu \in \tilde{B}(0; R)$ .

We have:  $|Tu(x)| \leq |\lambda| \int_a^b |K(t, s, u(s))| ds \leq |\lambda| M_K (b - a) \leq R$ . By taking  $\max_{x \in [a, b]}$ , we get that  $\|Tu\| \leq R$ , for each  $u \in \tilde{B}(0; R)$ .

Hence we have that  $T : \tilde{B}(0; R) \subset C[a, b] \rightarrow \tilde{B}(0; R)$  is completely continuous on the bounded, closed and convex subset  $\tilde{B}(0; R)$  of the Banach space  $C[a, b]$ . By Schauder II, there exists at least one fixed point  $u^* \in \tilde{B}(0; R)$  for  $T$ . This fixed point is a solution of the above Fredholm integral equation.  $\square$

**Theorem.** (The Volterra integral operator)

Let  $K : [a, b] \times [a, b] \times [-R, R] \rightarrow \mathbb{R}$  continuous. Consider the Volterra integral operator

$$\begin{aligned} T : C[a, b] &\rightarrow C[a, b] \\ u &\longmapsto Tu \end{aligned}$$

given by

$$Tu(t) := \int_a^t K(t, s, u(s)) ds, \quad t \in [a, b].$$

Then  $T$  is completely continuous.

**Remark.** a) Let  $K : [a, b] \times [a, b] \times [-R, R] \rightarrow \mathbb{R}$  and  $g : [a, b] \rightarrow \mathbb{R}$  be continuous. Consider the Volterra-type integral operator

$$T : C[a, b] \rightarrow C[a, b]$$

$$u \longmapsto Tu$$

given by

$$Tu(t) := \int_a^t K(t, s, u(s))ds + g(t), \quad t \in [a, b].$$

Then  $T$  is completely continuous.

b) Let  $K : [a, b] \times [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$  be continuous. Consider the Volterra integral operator

$$T : C[a, b] \rightarrow C[a, b]$$

$$u \longmapsto Tu$$

given by

$$Tu(x) := \int_a^t K(x, s, u(s))ds, \quad x \in [a, b].$$

Then  $T$  is completely continuous.

An existence result for a Volterra-type equation is:

**Theorem.** Let  $K : [a, b] \times [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$  continuous, such that there exist  $\alpha, \beta > 0$  such that  $|K(t, s, p)| \leq \alpha \cdot |p| + \beta$ , for each  $(t, s) \in [a, b]$  and  $p \in \mathbb{R}$ . Consider  $g \in C[a, b]$ .

Then there exists at least one solution of the following Volterra-type integral equation:

$$u(t) = \int_a^t K(t, s, u(s))ds + g(t), \quad t \in [a, b].$$

**Proof.** Consider on  $C[a, b]$  the Bielecki-type norm, with arbitrary  $\tau > 0$ , i.e.,

$$\|u\|_B := \max_{t \in [a, b]} |u(t)| \cdot e^{-\tau(t-a)}.$$

Let  $R > 0$  be arbitrarily chosen and  $\tilde{B}(0; R) \subset (C[a, b], \|\cdot\|_B)$ .

STEP 1. The operator

$$T : \tilde{B}(0; R) \subset C[a, b] \rightarrow C[a, b]$$

$$u \mapsto Tu$$

given by

$$Tu(t) := \int_a^t K(t, s, u(s))ds + g(t), \quad t \in [a, b]$$

is completely continuous, by the above theorem on Volterra integral operators.

STEP 2. We prove that  $\tilde{B}(0; R) \subset (C[a, b], \|\cdot\|_B)$  is invariant with respect to  $T$ .

Let  $u \in \tilde{B}(0; R)$ . Then, we have:

$$\begin{aligned} |Tu(t)| &\leq \int_a^t |K(t, s, u(s))|ds + \|g\| \leq \alpha \int_a^t |u(s)|ds + \beta(b-a) + \|g\| = \\ &\alpha \int_a^t |u(s)|e^{-\tau(s-a)}e^{\tau(s-a)}ds + \beta(b-a) + \|g\| \leq \alpha\|u\|_B \cdot \frac{1}{\tau}e^{\tau(t-a)} + \beta(b-a) + \|g\|. \end{aligned}$$

Hence,  $|Tu(t)|e^{-\tau(t-a)} \leq \frac{\alpha}{\tau}\|u\|_B + \beta(b-a) + \|g\|$ , for each  $t \in [a, b]$ .

We choose  $\tau > 0$  such that  $\frac{\alpha}{\tau}R + \beta(b-a) + \|g\| \leq R$ . Thus,  $\|Tu\|_B \leq R$  and then  $T : \tilde{B}(0; R) \subset (C[a, b], \|\cdot\|_B) \rightarrow \tilde{B}(0; R) \subset (C[a, b], \|\cdot\|_B)$ .

The conclusion follows now by Schauder II.  $\square$

### Application to differential equations.

#### A. Peano's Theorem.

Consider the Cauchy problem:

$$u'(t) = f(t, u(t)), \quad u(t_0) = u^0,$$

where  $f : D \rightarrow \mathbb{R}$  is continuous.

(here  $D := \{(t, u) \in \mathbb{R}^2 | t \in [t_0 - a, t_0 + a] \times [u^0 - b, u^0 + b]\}$ ).

Then the Cauchy problem has at least one solution in  $C[t_0 - h, t_0 + h]$ , where  $h := \min\{a, \frac{b}{M}\}$  (with  $M = \max_D |f(t, u)|$ ).

**Proof.** Denote

$$X := (C[t_0 - h, t_0 + h], \|\cdot\|) \text{ and } Y := \tilde{B}(u^0; b) \subset X.$$

Define  $T : \tilde{B}(u^0; b) \subset X \rightarrow X$ ,  $x \mapsto Tx$ , where

$$Tu(t) := \int_{t_0}^t f(s, u(s))ds + u^0, \quad \text{for } t \in [t_0 - h, t_0 + h].$$

Notice that the Cauchy problem is now equivalent to the following fixed point problem:  $u = Tu$ .

We have:

$$1) T : Y \rightarrow Y$$

Indeed, we will prove that if  $u \in Y$ , then  $Tu \in Y$ . We have  $|Tu(t) - u^0| \leq \int_{t_0}^t |f(s, u(s))| ds \leq M(t - t_0) \leq Mh \leq M \frac{b}{M} = b$ , for each  $t \in [t_0 - h, t_0 + h]$ . By taking the maximum of  $t \in [t_0 - h, t_0 + h]$ , we get that

$$\|Tu - u^0\| \leq b, \text{ for every } u \in Y.$$

Thus  $T(u) \in Y$ , for every  $u \in Y$ .

2)  $T$  is completely continuous from the above theorem on Volterra operators.

Hence, by Schauder II, we get that  $T$  has at least one fixed point in  $Y$ . This fixed point is a solution for our Cauchy problem.  $\square$

**B. Boundary Value Problem of Dirichlet-type.**

Consider the following boundary value problems of Dirichlet-type:

**I.**

$$(I1) \ x''(t) = 0, \ t \in [a, b]$$

$$(I2) \ x(a) = \alpha, \ x(b) = \beta.$$

**II.**

$$(II1) \ x''(t) = f(t), \ t \in [a, b]$$

$$(II2) \ x(a) = 0, \ x(b) = 0,$$

where  $f : [0, T] \rightarrow \mathbb{R}$  is a continuous function.

**III.**

$$(III1) \ x''(t) = f(t), \ t \in [a, b]$$

$$(III2) \ x(a) = \alpha, \ x(b) = \beta,$$

where  $f : [a, b] \rightarrow \mathbb{R}$  is a continuous function.

**IV.**

$$(IV1) \ x''(t) = f(t, x(t)), \ t \in [a, b]$$

$$(IV2) \ x(a) = 0, \ x(b) = 0,$$

where  $f : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$  is a continuous function.

**V.**

$$(V1) \ x''(t) = f(t, x(t)), \ t \in [a, b]$$

$$(V2) \ x(a) = \alpha, \ x(b) = \beta,$$

where  $f : [a, b] \times \mathbb{R} \rightarrow \mathbb{R}$  is a continuous function.

The purpose is to solve or to give existence results for these problems.

- The unique solution to problem (I1) and (I2) is:

$$x_I(t) = \frac{t-a}{b-a}\beta + \frac{b-t}{b-a}\alpha, \quad t \in [a, b].$$

- The unique solution to problem (II1) and (II2) is:

$$x_{II}(t) = - \int_a^b G(t, s)f(s)ds, \quad t \in [a, b],$$

where  $G : [a, b] \times [a, b] \rightarrow \mathbb{R}$  is the Green function corresponding to the problem (II), i.e.,

$$G(t, s) := \begin{cases} \frac{(s-a)(b-t)}{b-a}, & \text{if } s \leq t \\ \frac{(t-a)(b-s)}{b-a}, & \text{if } s \geq t \end{cases}$$

- The unique solution to problem (III1) and (III2) is:

$$x_{III}(t) = - \int_a^b G(t, s)f(s)ds + \frac{t-a}{b-a}\beta + \frac{b-t}{b-a}\alpha, \quad t \in [a, b].$$

• Problem (IV1) and (IV2) is equivalent to the following Fredholm integral equation:

$$x(t) = - \int_a^b G(t, s)f(s, x(s))ds, \quad t \in [a, b].$$

• Problem (V1) and (V2) is equivalent to the following Fredholm-type integral equation:

$$x(t) = - \int_a^b G(t, s)f(s, x(s))ds + \frac{t-a}{b-a}\beta + \frac{b-t}{b-a}\alpha, \quad t \in [a, b].$$

Consider the problem (IV1) and (IV2).

$$(IV1) \quad x''(t) = f(t, x(t)), \quad t \in [a, b]$$

$$(IV2) \quad x(a) = 0, \quad x(b) = 0.$$



We have the following existence result.

**Theorem.** *Let  $f : [a, b] \times [-R, R] \rightarrow \mathbb{R}$  be a continuous function, where  $R > 0$  is such that if  $x \in \tilde{B}(0; R) \subset C[a, b]$  then  $x(t) \in [-R, R]$ , for each  $t \in [a, b]$ . Suppose  $M(b - a) \leq R$ , where  $M := \max_{(t,u) \in [a,b] \times [-R,R]} |G(t, s)| \cdot |f(t, u)|$ .*

*Then, the problem (IV1) and (IV2) has at least one solution in  $\tilde{B}(0; R) \subset C[a, b]$ .*

**Proof.** STEP 1. The problem (IV1) and (IV2) is equivalent to the following Fredholm integral equation:

$$x(t) = - \int_a^b G(t, s) f(s, x(s)) ds, \quad t \in [a, b].$$

STEP 2. The operator  $T : \tilde{B}(0; R) \subset C[a, b] \rightarrow C[a, b]$ ,  $x \mapsto Tx$ , where

$$Tx(t) := - \int_a^b G(t, s) f(s, x(s)) ds, \quad t \in [a, b]$$

is completely continuous by the corresponding result for Fredholm operators.

STEP 3. We prove that  $T : \tilde{B}(0; R) \subset C[a, b] \rightarrow \tilde{B}(0; R)$ . Indeed, let  $x \in \tilde{B}(0; R) \subset C[a, b]$ . Then  $|Tx(t)| \leq \int_a^b |G(t, s)| \cdot |f(s, x(s))| ds \leq M(b - a) \leq R$ , for each  $t \in [a, b]$ . Hence  $\|Tx\| \leq R$ , for every  $x \in \tilde{B}(0; R)$ .

By Schauder II, we get that  $T$  has at least one fixed point in  $x^* \in \tilde{B}(0; R) \subset C[a, b]$ . This fixed point is clearly a solution to problem (IV1) and (IV2).  $\square$



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