

ON AN INTEGRAL EQUATION WITH DEVIATING ARGUMENT

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Abstract. Continuous and differentiability dependence of the solution for a class of integral equations with deviating argument is proved.

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1 Introduction

In paper [1] C. Avramescu investigates the following integral equation:

$$x(t) = \int_{-\infty}^{\infty} K(t, s, x(s))F(s, x)ds + f(t) \quad (1)$$

We shall generalize the equation (1) and we shall study it by means of the theory of Picard operators. A generalization of it, is the following equation:

$$x(t) = \int_{-t}^t K(t, s, x(s))ds + g(t), \quad t \in [-T, T], \quad T > 0 \quad (2)$$

We shall obtain a result concerning the existence and uniqueness of the solution by Contraction Principle (see [2]), and also a result concerning the differentiability of the solution with respect to a parameter.

2. In what follows we shall study the equation (2), where $K \in C([-T, T] \times [-T, T] \times \mathbb{R})$ and $g \in C([-T, T])$.

We have:

Theorem 1. *Suppose that:*

(i) *there exists a function $a : \mathbb{R} \rightarrow \mathbb{R}_+^*$ such that*

$$|K(t, s, u) - K(t, s, v)| \leq a(s)|u - v|,$$

for all $t, s \in [-T, T]$, $u, v \in \mathbb{R}$.

(ii) $q := \int_{-T}^T a(s)ds < 1$.

Then:

- a) the equation (2) has a unique solution x^* in $C([-T, T])$
 b) for all $x_0 \in X$, the sequence $(x_n)_{n \in \mathbb{N}}$ defined by:

$$x_{n+1}(t) = \int_{-t}^t K(t, s, x_n(s)) ds + g(t), \quad n \in \mathbb{N}$$

converges uniformly to x^* .

Proof. Let us consider the operator

$$B : C([-T, T]) \rightarrow C([-T, T]), \quad B(x)(t) = \int_{-t}^t K(t, s, x(s)) ds + g(t).$$

We have

$$\begin{aligned} |B(x)(t) - B(y)(t)| &\leq \int_{-t}^t |K(t, s, x(s)) - K(t, s, y(s))| ds \leq \\ &\leq \int_{-t}^t a(s) |x(s) - y(s)| ds \leq q \|x - y\|_C \end{aligned}$$

for all $x, y \in C([-T, T])$ and $t \in [-T, T]$.

Then $\|B(x) - B(y)\|_C \leq q \|x - y\|_C$ which shows that B is a contraction. The proof follows from the Contraction Principle. \square

3. Convenient choosing of the space - comprising the parameter in definition domain of the operator - allows us to establish the continuous dependence of the solution with respect to the parameters. Hence we shall consider the following equation:

$$x(t; \lambda) = \int_{-t}^t K(t, s, x(s; \lambda); \lambda) ds + g(t), \quad t \in [-T, T], \quad T > 0 \quad (3)$$

where $K \in C([-T, T] \times [-T, T] \times \mathbb{R} \times J)$, $\lambda \in J$ and $J \subset \mathbb{R}$ a compact interval.

As above we can prove the following

Theorem 2. Suppose that

- (i) there exists a function $a : \mathbb{R} \rightarrow \mathbb{R}_+^*$ such that:

$$|K(t, s, u; \lambda) - K(t, s, v; \lambda)| \leq a(s) |u - v|, \quad \text{for all } t, s \in [-T, T], \quad u, v \in \mathbb{R}, \quad \lambda \in J.$$

(ii) $q := \int_{-T}^T a(s) ds < 1$.

Then:

- (a) the equation (3) has a unique solution x^* in $C([-T, T] \times J) := X$
 (b) for all $x_0 \in X$, the sequence $(x_n)_{n \in \mathbb{N}}$ defined by:

$$x_{n+1}(t; \lambda) = \int_{-t}^t K(t, s, x_n(s; \lambda); \lambda) ds + g(t), \quad n \in \mathbb{N}$$

converges uniformly to x^* .

Remark 1. In the assumption of Theorem 2, for each fixed λ , the equation (3) has a solution in $C([-T, T] \times J)$ depending continuously on λ .

4. In this section we shall need the following result (see [3], [4], [5]).

Theorem 3. (of fiber contraction principle) *Let be (X, d) be a metric space, (Y, ρ) a complete metric space and $A : X \times Y \rightarrow X \times Y$ - an operator.*

Suppose that:

- (i) $A \in C(X \times Y, X \times Y)$;
- (ii) $A(x, y) = (B(x), C(x, y))$, for all $x \in X, y \in Y$;
- (iii) $B : X \rightarrow X$ is a Picard operator;
- (iv) There exists a number $\alpha \in]0, 1[$ such that:

$$\rho(C(x, y), C(x, z)) \leq \alpha \rho(x, y), \text{ for all } x \in X \text{ and } y, z \in Y.$$

Then A is a Picard operator.

We shall consider the equation (3) and we have:

Theorem 4. *Suppose that:*

- (i) there exists a function $a : \mathbb{R} \rightarrow \mathbb{R}_+^*$ such that:

$$|K(t, s, u; \lambda) - K(t, s, v; \lambda)| \leq a(s)|u - v|, \text{ for all } t, s \in [-T, T], u, v \in \mathbb{R}, \lambda \in J.$$

$$(ii) q := \int_{-T}^T a(s)ds < 1$$

$$(iii) K(t, s, \cdot; \cdot) \in C^1(\mathbb{R} \times J).$$

Then $x^(t; \cdot) \in C^1(J)$.*

Proof. Let us prove that there exists $\frac{\partial x^*}{\partial \lambda}$ and $\frac{\partial x^*}{\partial \lambda} \in C([-T, T] \times J)$.

If we suppose that there exists $\frac{\partial x^*}{\partial \lambda}$, then from relation (3) we have:

$$\frac{\partial x^*}{\partial \lambda}(t; \lambda) = \int_{-t}^t \frac{\partial K(t, s, x^*(s; \lambda); \lambda)}{\partial x^*} \cdot \frac{\partial x^*(s; \lambda)}{\partial \lambda} ds + \int_{-t}^t \frac{\partial K(t, s, x^*(s; \lambda); \lambda)}{\partial \lambda} ds.$$

This relation suggest us to consider the following operator:

$$\begin{aligned} C : X \times X \rightarrow X, \quad C(x, y)(t; \lambda) = \\ = \int_{-t}^t \frac{\partial K(t, s, x(s; \lambda); \lambda)}{\partial x} y(s; \lambda) ds + \int_{-t}^t \frac{\partial K(t, s, x(s; \lambda); \lambda)}{\partial \lambda} ds \end{aligned} \tag{4}$$

where $X = C([-T, T] \times J)$.

Then $A : X \times X \rightarrow X \times X, A(x, y) = (B(x), C(x, y))$, for all $x, y \in X$, where $B : X \rightarrow X$,

$$B(x)(t; \lambda) = \int_{-t}^t K(t, s, x(s; \lambda); \lambda) ds + g(t).$$

From relation (i) we remark that:

$$\left| \frac{\partial K(t, s, u; \lambda)}{\partial x} \right| \leq a(s), \text{ for all } t, s \in [-T, T], u \in \mathbb{R}, \lambda \in J. \tag{5}$$

From relation (4) and (5) results that $C(x, \cdot)$ is a q -contraction. Let us take $F_{C(x^*, \cdot)} = y^*$. Then this satisfies the assumptions of Theorem 3. By this Theorem, results that the operator A is a Picard operator and the sequences $x_{n+1} = B(x_n)$, $y_{n+1} = C(x_n, y_n)$ converges uniformly (with respect to $t \in [-T, T]$, $\lambda \in J$) to $(x^*, y^*) \in F_A$, for all $x_0, y_0 \in X$.

If we take $x_0, y_0 \in X$ such that $y_0 = \frac{\partial x_0}{\partial \lambda}$, then $y_1 = \frac{\partial x_1}{\partial \lambda}$.

By induction, we prove that $y_n = \frac{\partial x_n}{\partial \lambda}$. Thus

$$x_n \xrightarrow{\text{unif}} x^* \text{ as } n \rightarrow \infty,$$

$$\frac{\partial x_n}{\partial \lambda} \xrightarrow{\text{unif}} y^* \text{ as } n \rightarrow \infty.$$

These imply that there exists $\frac{\partial x^*}{\partial \lambda}$ and $\frac{\partial x^*}{\partial \lambda} = y^*$ (see [4]).

The proof is complete. \square

5. We are able to generalize this theorem, considering the following integral equation:

$$x(t; \lambda) = \int_{-t}^t K(t, s, x(s; \lambda); \lambda) ds + g(t, x(t; \lambda); \lambda), \quad t \in [-T, T], \quad T > 0 \quad (6)$$

where $K \in C([-T, T] \times [-T, T] \times \mathbb{R} \times J)$, $g \in C([-T, T] \times \mathbb{R} \times J)$, $\lambda \in J$ and $J \subset \mathbb{R}$ is a compact interval.

We have:

Theorem 5. *Suppose that:*

(i) *there exists a function $a : \mathbb{R} \rightarrow \mathbb{R}_+$ such that:*

$$|K(t, s, u; \lambda) - K(t, s, v; \lambda)| \leq a(s)|u - v|, \text{ for all } t, s \in [-T, T], \quad u, v \in \mathbb{R}, \quad \lambda \in J.$$

(ii) *there exists $L_g > 0$ such that*

$$|g(t, u; \lambda) - g(t, v; \lambda)| \leq L_g|u - v|, \text{ for all } t \in [-T, T], \quad u, v \in \mathbb{R}, \quad \lambda \in J.$$

(iii) $q + L_g < 1$.

Then:

(a) *the equation (6) has a unique solution x^* in X .*

(b) *for all $x_0 \in X$, the sequence $(x_n)_{n \in \mathbb{N}}$ defined by:*

$$x_{n+1}(t; \lambda) = \int_{-t}^t K(t, s, x_n(s; \lambda); \lambda) ds + g(t, x_n(t; \lambda); \lambda)$$

converges uniformly to x^ .*

(c) *if $K(t, s, \cdot; \cdot) \in C^1(\mathbb{R} \times J)$ and $g(t, \cdot; \cdot) \in C^1(\mathbb{R} \times J)$, then $x^*(t; \cdot) \in C^1(J)$.*

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