# MULTIPLE POSITIVE SOLUTIONS OF BOUNDARY VALUE PROBLEMS FOR P-LAPLACIAN IMPULSIVE DYNAMIC EQUATIONS ON TIME SCALES 

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#### Abstract

In this paper, by using the classical fixed-point index theorem for compact maps and Leggett-Williams fixed point theorem, some sufficient conditions for the existence of multiple positive solutions for a class of second-order $p$-Laplacian boundary value problem with impulse on time scales are established. We also give an example to illustrate our results Key Words and Phrases: Impulsive dynamic equation, p-Laplacian, positive solutions, fixed point theorems, time scales. 2010 Mathematics Subject Classification: 34B18, 34B37, 34K10, 47H10.


## 1. Introduction

It is known that the theory of impulsive differential equations have become more important in recent years in some mathematical models of real processes and phenomena. For the introduction of the basic theory of impulsive equations, see [1, 12] and the references therein.

The theory of dynamic equations on time scales has been developing rapidly and have received much attention in recent years. The study unifies existing results from the theory of differential and finite difference equations and provides powerful new tools for exploring connections between the traditionally separated fields. We refer to the books by Bohner and Peterson [3, 4].

Recently, the boundary value problems for impulsive differential equations have been studied extensively. To identify a few, we refer to the reader to see $[7,8,9,11$, 18, 20]. However, the corresponding theory of such equations is still in the beginning stages of its development, especially the impulsive dynamic equations on time scales, see $[2,15,19]$. There is not so much work on impulsive boundary value problems
with p-Laplacian on time scales except that in $[5,6,10,16,17]$. To our knowledge, no paper has considered the second-order BVP with integral boundary conditions for p-Laplacian impulsive dynamic equations on time scales. This paper fills this gap in the literature.

In this paper, we are concerned with the existence of many positive solutions of the following boundary value problem for p-Laplacian impulsive dynamic equations on time scales

$$
\begin{align*}
& -\left(\phi_{p}\left(u^{\triangle}\right)\right)^{\nabla}(t)=f(t, u(t)), \quad t \in[0,1]_{\mathbb{T}}, \quad t \neq t_{k}, \quad k=1,2, \ldots, m  \tag{1.1}\\
& u\left(t_{k}^{+}\right)-u\left(t_{k}^{-}\right)=I_{k}\left(u\left(t_{k}\right)\right), \quad k=1,2, \ldots, m  \tag{1.2}\\
& \alpha u(0)-\beta u^{\triangle}(0)=\int_{0}^{1} u(s) \triangle s, \quad u^{\triangle}(1)=0 \tag{1.3}
\end{align*}
$$

where $\mathbb{T}$ is a time scale, $0,1 \in \mathbb{T},[0,1]_{\mathbb{T}}=[0,1] \cap \mathbb{T}, t_{k} \in(0,1) \cap \mathbb{T}, k=1,2, \ldots, m$ with $0<t_{1}<t_{2}<\ldots<t_{m}<1, \alpha>1, \beta>0, \phi_{p}(s)$ is a p-Laplacian function, i.e., $\phi_{p}(s)=|s|^{p-2} s$ for $p>1,\left(\phi_{p}\right)^{-1}(s)=\phi_{q}(s)$ where $\frac{1}{p}+\frac{1}{q}=1$.

We assume that the following conditions are satisfied:
$(H 1) f \in \mathcal{C}([0,1] \times[0, \infty),[0, \infty))$;
(H2) $I_{k} \in \mathcal{C}([0, \infty),[0, \infty)), t_{k} \in[0,1]_{\mathbb{T}}$ and $u\left(t_{k}^{+}\right)=\lim _{h \rightarrow 0} u\left(t_{k}+h\right), u\left(t_{k}^{-}\right)=$ $\lim _{h \rightarrow 0} u\left(t_{k}-h\right)$ represent the right and left limits of $u(t)$ at $t=t_{k}, k=$ $1,2, \ldots, m$.
We remark that by a solution $u$ of (1.1)-(1.3) we mean $u: \mathbb{T} \rightarrow \mathbb{R}$ is delta differentiable, $u^{\triangle}: \mathbb{T}^{k} \rightarrow \mathbb{R}$ is nabla differentiable on $\mathbb{T}^{k} \cap \mathbb{T}_{k}$ and $u^{\Delta \nabla}: \mathbb{T}^{k} \cap \mathbb{T}_{k} \rightarrow \mathbb{R}$ is continuous, and satisfies the impulsive and boundary value conditions (1.2)-(1.3).

By using the fixed point index theory in the cone [13], we get the existence of at least two or more positive solutions for the BVP (1.1)-(1.3). By using LeggettWilliams fixed point theorem [14], we also establish the existence of triple positive solutions for BVP (1.1)-(1.3).

The organization of this paper is as follows. In section 2, we provide some necessary background. In section 3, the main results for problem (1.1)-(1.3) are given. In section 4, we give an example.

## 2. Preliminaries

In this section, we list some background material from the theory of cones in Banach spaces.

Definition 2.1. Let $(E,\|\cdot\|)$ be a real Banach space. A nonempty, closed set $K \subset E$ is said to be a cone provided the following are satisfied:
(i) if $x, y \in K$ and $a, b \geq 0$, then $a x+b y \in K$;
(ii)if $y \in K$ and $-y \in K$, then $y=0$.

If $K \subset E$ is a cone, then $K$ can induce a partially order relation $\leq$ on E by $x \leq y$, if and only if $y-x \in K$, for all $x, y \in E$.

Definition 2.2. A function $f: \mathbb{T} \rightarrow \mathbb{R}$ is called concave on $I_{\mathbb{T}}=I \cap \mathbb{T}$, if $f(\lambda t+(1-$ $\lambda) s) \geq \lambda f(t)+(1-\lambda) f(s)$, for all $t, s \in I_{\mathbb{T}}$ and all $\lambda \in[0,1]$ such that $\lambda t+(1-\lambda) s \in I_{\mathbb{T}}$.

Remark 2.3. If $u^{\Delta \nabla} \leq 0$ on $[0,1]_{\mathbb{T}^{k} \cap \mathbb{T}_{k}}$, then we say that $u$ is concave on $[0,1]_{\mathbb{T}}$.
Theorem 2.4. [13] Let K be a cone in a real Banach space $E$. Let D be an open bounded subset of $E$ with $D_{K}=D \cap K \neq \emptyset$ and $\bar{D}_{K} \neq K$. Assume that $T: \bar{D}_{K} \rightarrow K$ is completely continuous such that $x \neq T x$ for $x \in \partial D_{K}$. Then the following results hold:
(i) If $\|T x\| \leq\|x\|, x \in \partial D_{K}$, then $i_{K}\left(T, D_{K}\right)=1$.
(ii) If there exists $e \in K \backslash\{0\}$ such that $x \neq T x+\lambda e$ for all $x \in \partial D_{K}$ and all $\lambda>0$, then $i_{K}\left(T, D_{K}\right)=0$.
(iii) Let U be open in K such that $\bar{U} \subset D_{K}$. If $i_{K}\left(T, D_{K}\right)=1$ and $i_{K}\left(T, U_{K}\right)=0$, then $T$ has a fixed point in $D_{K} \backslash \bar{U}_{K}$. The same result holds if $i_{K}\left(T, D_{K}\right)=0$ and $i_{K}\left(T, U_{K}\right)=1$.
Let $E$ be a real Banach space with cone $K$, a map $\theta: K \rightarrow[0, \infty)$ is said to be nonnegative continuous concave functional on $K$ if $\theta$ is continuous and

$$
\theta(t x+(1-t) y) \geq t \theta(x)+(1-t) \theta(y)
$$

for all $x, y \in K$ and $t \in[0,1]_{\mathbb{T}}$. Let $a, b$ be two numbers such that $0<a<b$ and $\theta$ a nonnegative continuous concave functional on $K$. We define the following convex sets:

$$
\begin{gathered}
K_{a}=\{x \in K:\|x\|<a\}, \\
K(\theta, a, b)=\{x \in K: a \leq \theta(x),\|x\|<b\} .
\end{gathered}
$$

Theorem 2.5. [14] (Leggett-Williams fixed point theorem) Let $T: \bar{K}_{c} \rightarrow \bar{K}_{c}$ be completely continuous and $\theta$ be a nonnegative continuous concave functional on P such that $\theta(x) \leq\|x\|$ for all $x \in \bar{K}_{c}$. Suppose there exists $0<d<a<b \leq c$ such that
(i) $\{x \in K(\theta, a, b): \theta(x)>a\} \neq \emptyset$ and $\theta(T x)>a$ for $x \in K(\theta, a, b)$,
(ii) $\|T x\|<d$ for $\|x\| \leq d$,
(iii) $\theta(T x)>a$ for $x \in K(\theta, a, c)$ with $\|T x\|>b$.

Then T has at least three fixed points $x_{1}, x_{2}, x_{3}$ in $\bar{K}_{c}$ such that $\left\|x_{1}\right\|<d, a<\theta\left(x_{2}\right)$ and $\left\|x_{3}\right\|>d$ with $\theta\left(x_{3}\right)<a$.

## 3. Main Results

In this section, by defining an appropriate Banach space and cone, we impose the growth conditions on $f, I_{k}$ which allow us to apply the theorems in section 2 to establish the existence results of the positive solutions for the BVP (1.1)-(1.3).

Let $J^{\prime}=[0,1]_{\mathbb{T}} \backslash\left\{t_{1}, t_{2}, \ldots, t_{m}\right\}$. We define
$E=\left\{u:[0,1]_{\mathbb{T}} \rightarrow \mathbb{R}\right.$ is continuous at $t \neq t_{k}$, there exist $u\left(t_{k}^{-}\right)$and

$$
\left.u\left(t_{k}^{+}\right) \text {with } u\left(t_{k}^{-}\right)=u\left(t_{k}\right) \text { for } k=1,2, \ldots, m\right\}
$$

which is a Banach space with the norm $\|u\|=\sup _{t \in[0,1]_{\mathbb{T}}}|u(t)|$.

By a solution of (1.1)-(1.3), we mean a function $u \in E \cap \mathcal{C}^{2}\left(J^{\prime}\right)$ which satisfies (1.1)-(1.3). We define a cone $K \subset E$ as

$$
\begin{aligned}
K= & \{u \in E: u \text { is a concave, nonnegative and nondecreasing function, } \\
& \left.\alpha u(0)-\beta u^{\triangle}(0)=\int_{0}^{1} u(s) \triangle s\right\}
\end{aligned}
$$

Lemma 3.1. Suppose that (H1) and (H2) are satisfied. Then $u \in E \cap \mathcal{C}^{2}\left(J^{\prime}\right)$ is a positive solution of the impulsive boundary value problem (1.1)-(1.3) if and only if $u(t)$ is a solution of the following integral equation

$$
\begin{align*}
& u(t)=\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\frac{1}{\alpha-1} \int_{0}^{1}(1-\sigma(\tau)) \phi_{q}\left(\int_{\tau}^{1} f(r, u(r)) \nabla r\right) \Delta \tau \\
& \quad+\int_{0}^{t} \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s+\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u_{t_{k}}\right)\left(1-t_{k}\right)+\sum_{t_{k}<t} I_{k}\left(u_{t_{k}}\right) . \tag{3.1}
\end{align*}
$$

Proof. Integrating of (1.1) from $t$ to 1 , one has

$$
-\phi_{p}\left(u^{\triangle}(1)\right)+\phi_{p}\left(u^{\triangle}(t)\right)=\int_{t}^{1} f(s, u(s)) \nabla s
$$

By the boundary condition (1.3), we have

$$
u^{\triangle}(t)=\phi_{q}\left(\int_{t}^{1} f(s, u(s)) \nabla s\right)
$$

Integrating the differential equation above from 0 to $t$, we get

$$
\begin{equation*}
u(t)=u(0)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s+\sum_{t_{k}<t} I_{k}\left(u_{t_{k}}\right) . \tag{3.2}
\end{equation*}
$$

Applying the boundary condition (1.3), one has

$$
\begin{align*}
u(0)= & \frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\frac{1}{\alpha-1} \int_{0}^{1}(1-\sigma(\tau)) \phi_{q}\left(\int_{\tau}^{1} f(r, u(r)) \nabla r\right) \Delta \tau \\
& +\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u_{t_{k}}\right)\left(1-t_{k}\right) \tag{3.3}
\end{align*}
$$

Therefore, by (3.2) and (3.3), we have

$$
\begin{aligned}
u(t)= & \frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\frac{1}{\alpha-1} \int_{0}^{1}(1-\sigma(\tau)) \phi_{q}\left(\int_{\tau}^{1} f(r, u(r)) \nabla r\right) \Delta \tau \\
& +\int_{0}^{t} \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s+\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u_{t_{k}}\right)\left(1-t_{k}\right)+\sum_{t_{k}<t} I_{k}\left(u_{t_{k}}\right)
\end{aligned}
$$

Then, sufficient proof is complete.

Conversely, let $u$ be as in (3.1). If we take the delta derivative of both sides of (3.1), then

$$
\begin{array}{r}
\quad u^{\triangle}(t)=\phi_{q}\left(\int_{t}^{1} f(s, u(s)) \nabla s\right), \\
\text { i.e., } \quad \phi_{p}\left(u^{\triangle}(t)\right)=\int_{t}^{1} f(s, u(s)) \nabla s .
\end{array}
$$

So $u^{\triangle}(1)=0$. It is easy to see that $u(t)$ satisfy (1.2) and (1.3). Furthermore, from $(H 1),(H 2)$ and (3.1), it is clear that $u(t) \geq 0$. The proof is complete.

Lemma 3.2. If $u \in K$, then $\min _{t \in[0,1]_{\mathbb{T}}} u(t) \geq \gamma\|u\|$, where $\gamma=\frac{\int_{0}^{1} s \Delta s}{\alpha-1+\int_{0}^{1} s \Delta s}$.
Proof. Since $u \in K$, nonnegative and nondecreasing

$$
\|u\|=u(1), \quad \min _{t \in[0,1]_{\mathrm{T}}} u(t)=u(0) .
$$

On the other hand, $u(t)$ is concave on $[0,1]_{\mathbb{T}} \backslash\left\{t_{1}, \ldots, t_{m}\right\}$. So, for every $t \in[0,1]_{\mathbb{T}}$, we have

$$
u(1)-u(0) \leq \frac{u(t)-u(0)}{t}
$$

i.e.,

$$
t u(1)+(1-t) u(0) \leq u(t)
$$

Therefore,

$$
\int_{0}^{1} s u(1) \triangle s+\int_{0}^{1}(1-s) u(0) \triangle s \leq \int_{0}^{1} u(s) \triangle s
$$

This together with $\alpha u(0)-\beta u^{\triangle}(0)=\int_{0}^{1} u(s) \triangle s$, implies that

$$
u(0) \geq \frac{\int_{0}^{1} s \Delta s}{\alpha-1+\int_{0}^{1} s \Delta s} u(1)
$$

The Lemma is proved.
Define $T: K \rightarrow E$ by

$$
\begin{align*}
& (T u)(t)=\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\frac{1}{\alpha-1} \int_{0}^{1}(1-\sigma(\tau)) \phi_{q}\left(\int_{\tau}^{1} f(r, u(r)) \nabla r\right) \Delta \tau \\
+ & \int_{0}^{t} \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s+\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u_{t_{k}}\right)\left(1-t_{k}\right)+\sum_{t_{k}<t} I_{k}\left(u_{t_{k}}\right) . \tag{3.4}
\end{align*}
$$

From (3.4) and Lemma 3.1, it is easy to obtain the following result.
Lemma 3.3. Assume that $(H 1)$ and (H2) hold. Then $T: K \rightarrow K$ is completely continuous.

We define

$$
\begin{aligned}
\Omega_{\rho} & =\left\{u \in K: \min _{t \in[0,1]_{\mathbb{T}}} u(t)<\gamma \rho\right\} \\
& =\left\{u \in K: \gamma\|u\| \leq \min _{t \in[0,1]_{\mathbb{T}}} u(t)<\gamma \rho\right\}
\end{aligned}
$$

and

$$
K_{\rho}=\{u \in K:\|u\|<\rho\} .
$$

Lemma 3.4. [13] $\Omega_{\rho}$ has the following properties:
(a) $\Omega_{\rho}$ is open relative to $K$.
(b) $K_{\gamma \rho} \subset \Omega_{\rho} \subset K_{\rho}$.
(c) $u \in \partial \Omega_{\rho}$ if and only if $\min _{t \in[0,1]_{\mathbb{T}}} u(t)=\gamma \rho$.
(d) If $u \in \partial \Omega_{\rho}$, then $\gamma \rho \leq u(t) \leq \rho$ for $t \in[0,1]_{\mathbb{T}}$.

Now for convenience we introduce the following notations. Let

$$
\begin{gathered}
f_{a}^{b}=\min \left\{\min _{t \in[0,1]_{\mathbb{T}}} \frac{f(t, u)}{\phi_{p}(a)}: u \in[a, b]\right\}, \\
f_{\gamma \rho}^{\rho}=\min \left\{\min _{t \in[0,1]_{\mathrm{T}}} \frac{f(t, u)}{\phi_{p}(\rho)}: u \in[\gamma \rho, \rho]\right\}, \\
f_{0}^{\rho}=\max \left\{\max _{t \in[0,1]_{\mathrm{T}}} \frac{f(t, u)}{\phi_{p}(\rho)}: u \in[0, \rho]\right\}, \\
I_{0}^{\rho}(k)=\max \left\{I_{k}(u): u \in[0, \rho]\right\}, \\
\frac{1}{l}=\frac{\beta+(1+m) \alpha}{\alpha-1}, \quad \frac{1}{L}=\frac{\beta}{\alpha-1} .
\end{gathered}
$$

Theorem 3.5. Suppose (H1) and (H2) hold.
(H3) If there exist $\rho_{1}, \rho_{2}, \rho_{3} \in(0, \infty)$ with $\rho_{1}<\gamma \rho_{2}$ and $\rho_{2}<\rho_{3}$ such that
$f_{0}^{\rho_{1}}<\phi_{p}(l), I_{0}^{\rho_{1}}(k)<l \rho_{1}, f_{\gamma \rho_{2}}^{\rho_{2}}>\phi_{p}(L), f_{0}^{\rho_{3}}<\phi_{p}(l), I_{0}^{\rho_{3}}(k)<l \rho_{3}$,
then problem (1.1)-(1.3) has at least two positive solutions $u_{1}, u_{2}$ with $u_{1} \in$ $\Omega_{\rho_{2}} \backslash \bar{K}_{\rho_{1}}, u_{2} \in K_{\rho_{3}} \backslash \bar{\Omega}_{\rho_{2}}$.
(H4) If there exist $\rho_{1}, \rho_{2}, \rho_{3} \in(0, \infty)$ with $\rho_{1}<\rho_{2}<\gamma \rho_{3}<\rho_{3}$ such that

$$
f_{\gamma \rho_{1}}^{\rho_{1}}>\phi_{p}(L), f_{0}^{\rho_{2}}<\phi_{p}(l), I_{0}^{\rho_{2}}(k)<l \rho_{2}, f_{\gamma \rho_{3}}^{\rho_{3}}>\phi_{p}(L),
$$

then problem (1.1)-(1.3) has at least two positive solutions $u_{1}, u_{2}$ with $u_{1} \in$ $K_{\rho_{2}} \backslash \bar{\Omega}_{\rho_{1}}, u_{2} \in \Omega_{\rho_{3}} \backslash \bar{K}_{\rho_{2}}$.

Proof. We only consider the condition (H3). If (H4) holds, then the proof is similar to that of the case when $(H 3)$ holds. By Lemma 3.3, we know that the operator $T: K \rightarrow K$ is completely continuous.

First, we show that $i_{K}\left(T, K_{\rho_{1}}\right)=1$. In fact, by (3.4), $f_{0}^{\rho_{1}}<\phi_{p}(l)$ and $I_{0}^{\rho_{1}}(k)<l \rho_{1}$, we have for $u \in \partial K_{\rho_{1}}$,

$$
\begin{aligned}
& (T u)(t)=\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s \\
& +\frac{1}{\alpha-1} \int_{0}^{1}(1-\sigma(s)) \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s \\
& +\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u\left(t_{k}\right)\right)\left(1-t_{k}\right)+\sum_{t_{k}<t} I_{k}\left(u\left(t_{k}\right)\right) \\
& \leq \frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\int_{0}^{1} \phi_{q}\left(\int_{0}^{1} f(r, u(r)) \nabla r\right) \Delta s \\
& +\frac{1}{\alpha-1} \int_{0}^{1} \phi_{q}\left(\int_{0}^{1} f(r, u(r)) \nabla r\right) \Delta s+\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u\left(t_{k}\right)\right) \\
& +\sum_{k=1}^{m} I_{k}\left(u\left(t_{k}\right)\right) \\
& =\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\phi_{q}\left(\int_{0}^{1} f(r, u(r)) \nabla r\right) \\
& +\frac{1}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(r, u(r)) \nabla r\right)+\frac{\alpha}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u\left(t_{k}\right)\right) \\
& =\frac{\beta+\alpha}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\frac{\alpha}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u\left(t_{k}\right)\right) \\
& <\frac{\beta+\alpha}{\alpha-1} \phi_{q}\left(\int_{0}^{1} \phi_{p}\left(l \rho_{1}\right) \nabla s\right)+\frac{\alpha}{\alpha-1} \sum_{k=1}^{m} l \rho_{1} \\
& =\frac{\beta+\alpha}{\alpha-1} l \rho_{1}+\frac{\alpha}{\alpha-1} l \rho_{1} m \\
& =l \rho_{1}\left[\frac{\beta+(m+1) \alpha}{\alpha-1}\right]=\rho_{1} \text {, }
\end{aligned}
$$

i.e., $\|T u\|<\|u\|$ for $u \in \partial K_{\rho_{1}}$. By $(i)$ of Theorem 2.4, we obtain that $i_{K}\left(T, K_{\rho_{1}}\right)=1$.

Secondly, we show that $i_{K}\left(T, \Omega_{\rho_{2}}\right)=0$. Let $e(t) \equiv 1$. Then $e \in \partial K_{1}$. We claim that

$$
u \neq T u+\lambda e, u \in \partial \Omega_{\rho_{2}}, \lambda>0
$$

Suppose that there exists $u_{0} \in \partial \Omega_{\rho_{2}}$ and $\lambda_{0}>0$ such that

$$
\begin{equation*}
u_{0}=T u_{0}+\lambda_{0} e . \tag{3.5}
\end{equation*}
$$

Then, Lemma 3.2, Lemma 3.4 (d) and (3.5) imply that for $t \in[0,1]_{\mathbb{T}}$

$$
\begin{aligned}
u_{0} & =T u_{0}+\lambda_{0} e \geq \gamma\left\|T u_{0}\right\|+\lambda_{0} \\
& \geq \gamma \frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\lambda_{0} \\
& >\gamma \frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} \phi_{p}\left(L \rho_{2}\right) \nabla s\right)+\lambda_{0} \\
& =\gamma \frac{\beta}{\alpha-1} L \rho_{2}+\lambda_{0}=\gamma \rho_{2}+\lambda_{0},
\end{aligned}
$$

i.e., $\gamma \rho_{2}>\gamma \rho_{2}+\lambda_{0}$, which is a contradiction. Hence by ( $i i$ ) of Theorem 2.4, it follows that $i_{K}\left(T, \Omega_{\rho_{2}}\right)=0$.

Finally, similar to the proof of $i_{K}\left(T, K_{\rho_{1}}\right)=1$, we can prove that $i_{K}\left(T, K_{\rho_{3}}\right)=1$. Since $\rho_{1}<\gamma \rho_{2}$ and Lemma 3.4 (b), we have $\bar{K}_{\rho_{1}} \subset K_{\gamma \rho_{2}} \subset \Omega_{\rho_{2}}$. Similarly with $\rho_{2}<\rho_{3}$ and Lemma 3.4 (b), we have $\bar{\Omega}_{\rho_{2}} \subset K_{\rho_{2}} \subset K_{\rho_{3}}$. Therefore (iii) of Theorem 2.4 implies that BVP (1.1)-(1.3) has at least two positive solutions $u_{1}, u_{2}$ with $u_{1} \in$ $\Omega_{\rho_{2}} \backslash \bar{K}_{\rho_{1}}, u_{2} \in K_{\rho_{3}} \backslash \bar{\Omega}_{\rho_{2}}$.

Theorem 3.5 can be generalized to obtain many solutions.
Theorem 3.6. Suppose (H1) and (H2) hold. Then we have the following assertions.
(H5) If there exists $\left\{\rho_{i}\right\}_{i=1}^{2 m_{0}+1} \subset(0, \infty)$ with $\rho_{1}<\gamma \rho_{2}<\rho_{2}<\rho_{3}<\gamma \rho_{4}<\ldots<$ $\gamma \rho_{2 m_{0}}<\rho_{2 m_{0}}<\rho_{2 m_{0}+1}$ such that

$$
\begin{gathered}
f_{0}^{\rho_{2 m-1}}<\phi_{p}(l), I_{0}^{\rho_{2 m-1}}<l \rho_{2 m-1},\left(m=1,2, \ldots, m_{0}, m_{0}+1\right), \\
f_{\gamma \rho_{2} m}^{\rho_{2} m}>\phi_{p}(L),\left(m=1,2, \ldots, m_{0}\right),
\end{gathered}
$$

then problem (1.1)-(1.3) has at least $2 m_{0}$ solutions in $K$.
(H6) If there exists $\left\{\rho_{i}\right\}_{i=1}^{2 m_{0}} \subset(0, \infty)$ with $\rho_{1}<\gamma \rho_{2}<\rho_{2}<\rho_{3}<\gamma \rho_{4}<\ldots<$ $\gamma \rho_{2 m_{0}}<\rho_{2 m_{0}}$ such that
$f_{0}^{\rho_{2 m-1}}<\phi_{p}(l), I_{0}^{\rho_{2 m-1}}<l \rho_{2 m-1}, \quad f_{\gamma \rho_{2} m}^{\rho_{2} m}>\phi_{p}(L),\left(m=1,2, \ldots, m_{0}\right)$,
then problem (1.1)-(1.3) has at least $2 m_{0}-1$ solutions in $K$.
Theorem 3.7. Suppose $(H 1)$ and $(H 2)$ hold. Then we have the following assertions.
$(H 7)$ If there exists $\left\{\rho_{i}\right\}_{i=1}^{2 m_{0}+1} \subset(0, \infty)$ with $\rho_{1}<\rho_{2}<\gamma \rho_{3}<\rho_{3}<\ldots<\rho_{2 m_{0}}<$ $\gamma \rho_{2 m_{0}+1}<\rho_{2 m_{0}+1}$ such that

$$
\begin{gathered}
f_{\gamma \rho_{2 m-1}}^{\rho_{2 m-1}}>\phi_{p}(L), \quad\left(m=1,2, \ldots, m_{0}, m_{0}+1\right) \\
f_{0}^{\rho_{2} m}<\phi_{p}(l), I_{0}^{\rho_{2 m}}<l \rho_{2 m}, \quad\left(m=1,2, \ldots, m_{0}\right)
\end{gathered}
$$

then problem (1.1)-(1.3) has at least $2 m_{0}$ solutions in $K$.
(H8) If there exists $\left\{\rho_{i}\right\}_{i=1}^{2 m_{0}} \subset(0, \infty)$ with $\rho_{1}<\rho_{2}<\gamma \rho_{3}<\rho_{3}<\ldots<\gamma \rho_{2 m_{0}-1}<$ $\rho_{2 m_{0}-1}<\rho_{2 m_{0}}$ such that

$$
f_{\gamma \rho_{2 m-1}}^{\rho_{2 m-1}}>\phi_{p}(L), f_{0}^{\rho_{2 m}}<\phi_{p}(l), I_{0}^{\rho_{2 m}}<l \rho_{2 m},\left(m=1,2, \ldots, m_{0}\right),
$$

then problem (1.1)-(1.3) has at least $2 m_{0}-1$ solutions in $K$.

Theorem 3.8. Let $0<d<a<\gamma b<b \leq c$ and assume that conditions (H1), (H2) hold, and the following conditions hold:
(H9) There exists a constant $c_{k}$ such that $I_{k}(y) \leq c_{k}$ for $k=1,2, \ldots, m$;
(H10) $f_{a}^{b}>\phi_{p}(L)$;
(H11) $f_{0}^{c} \leq \phi_{p}(R), f_{0}^{d}<\phi_{p}(R)$ where $0<R<\frac{\alpha-1}{\beta+\alpha}, d>\frac{\frac{\alpha}{\alpha-1} \sum_{k=1}^{m} c_{k}}{1-R\left(\frac{\beta+\alpha}{\alpha-1}\right)}$.
Then the BVP (1.1)-(1.3) has at least three nonnegative solutions $u_{1}, u_{2}$, and $u_{3}$ in $\bar{K}_{c}$ such that

$$
\left\|u_{1}\right\|<d, \quad a<\beta\left(u_{2}\right) \text { and }\left\|u_{3}\right\|>d \text { with } \beta\left(u_{3}\right)<a .
$$

Proof. By (H1) and (H2), T:K $\rightarrow K$ is completely continuous. For $u \in K$, let

$$
\theta(u)=\min _{t \in[0,1]_{\mathbb{T}}} u(t),
$$

then it is easy to check that $\theta$ is a nonnegative continuous concave functional on $K$ with $\theta(u) \leq\|u\|$ for $u \in K$.

Let $u \in \bar{K}_{c}$, by (H9) and (H11) we have

$$
\begin{aligned}
\|T u\|= & \max _{t \in[0,1]_{\mathrm{T}}} T u(t) \\
= & \max _{t \in[0,1]_{\mathbb{T}}}\left\{\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s\right. \\
& +\frac{1}{\alpha-1} \int_{0}^{1}(1-\sigma(s)) \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s \\
& \left.+\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u\left(t_{k}\right)\right)\left(1-t_{k}\right)+\sum_{t_{k}<t} I_{k}\left(u\left(t_{k}\right)\right)\right\} \\
\leq & \frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} \phi_{p}(R c) \nabla s\right)+\int_{0}^{1} \phi_{q}\left(\int_{0}^{1} \phi_{p}(R c) \nabla r\right) \triangle s \\
& +\frac{1}{\alpha-1} \int_{0}^{1} \phi_{q}\left(\int_{0}^{1} \phi_{p}(R c) \nabla r\right) \Delta s+\frac{1}{\alpha-1} \sum_{k=1}^{m} c_{k}+\sum_{k=1}^{m} c_{k} \\
= & R c\left(\frac{\beta+\alpha}{\alpha-1}\right)+\frac{\alpha}{\alpha-1} \sum_{k=1}^{m} c_{k} \\
< & c,
\end{aligned}
$$

that is $\|T u\|<c$.

Now, we show condition (ii) of Theorem 2.5 holds. Let $\|u\| \leq d$, it follows from (H11) that

$$
\begin{aligned}
\|T u\|= & \max _{t \in[0,1]_{\mathrm{T}}} T u(t) \\
= & \max _{t \in[0,1]_{\mathbb{T}}}\left\{\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s\right. \\
& +\frac{1}{\alpha-1} \int_{0}^{1}(1-\sigma(s)) \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s \\
& \left.+\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u\left(t_{k}\right)\right)\left(1-t_{k}\right)+\sum_{t_{k}<t} I_{k}\left(u\left(t_{k}\right)\right)\right\} \\
\leq & \frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} \phi_{p}(R d) \nabla s\right)+\int_{0}^{1} \phi_{q}\left(\int_{0}^{1} \phi_{p}(R d) \nabla r\right) \triangle s \\
& +\frac{1}{\alpha-1} \int_{0}^{1} \phi_{q}\left(\int_{0}^{1} \phi_{p}(R d) \nabla r\right) \Delta s+\frac{1}{\alpha-1} \sum_{k=1}^{m} c_{k}+\sum_{k=1}^{m} c_{k} \\
= & R d\left(\frac{\beta+\alpha}{\alpha-1}\right)+\frac{\alpha}{\alpha-1} \sum_{k=1}^{m} c_{k} \\
< & d .
\end{aligned}
$$

So, condition (ii) of Theorem 2.5 holds.
Next, we show that $\{u \in K(\theta, a, b): \theta(u)>a\} \neq \emptyset$ and $\theta(T u)>a$ for $u \in$ $K(\theta, a, b)$. In fact, take $u(t)=\frac{a+b}{2}>a$, so $u \in\{u \in K(\theta, a, b): \theta(u)>a\}$. Also, $u \in K(\theta, a, b)$ and (H10) condition imply that

$$
\begin{aligned}
\theta(T u) & =\min _{t \in[0,1]_{\mathbb{T}}}(T u)(t)=T u(0) \\
& =\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right) \\
& +\frac{1}{\alpha-1} \int_{0}^{1}(1-\sigma(s)) \phi_{q}\left(\int_{s}^{1} f(r, u(r)) \nabla r\right) \Delta s \\
& +\frac{1}{\alpha-1} \sum_{k=1}^{m} I_{k}\left(u\left(t_{k}\right)\right)\left(1-t_{k}\right) \\
& >\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} f(s, u(s)) \nabla s\right) \\
& >\frac{\beta}{\alpha-1} \phi_{q}\left(\int_{0}^{1} \phi_{p}\left(\frac{a(\alpha-1)}{\beta}\right) \nabla s\right)=a .
\end{aligned}
$$

Finally, we show that $\theta(T u)>a$ for $u \in K(\theta, a, c)$ with $\|T u\|>b$. From Lemma 3.2, we have

$$
\theta(T u)=\min _{t \in[0,1]_{\mathrm{T}}}(T u)(t) \geq \gamma\|T u\|>\gamma b>a .
$$

So $\theta(T u)>a$ is satisfied. Therefore all of the conditions of Theorem 2.5 hold. Hence BVP (1.1)-(1.3) has at least three positive solutions $u_{1}, u_{2}$ and $u_{3}$ such that

$$
\left\|u_{1}\right\|<d, \quad a<\theta\left(u_{2}\right) \text { and }\left\|u_{3}\right\|>d \quad \text { with } \quad \theta\left(u_{3}\right)<a .
$$

## 4. Example

Example 4.1. Consider the following second-order impulsive $p$-Laplacian boundary value problem,

$$
\begin{gather*}
-\left(\phi_{2}\left(u^{\triangle}(t)\right)\right)^{\nabla}=f(t, u(t)), \quad t \in[0,1]_{\mathbb{T}} \backslash\left\{\frac{1}{2}\right\},  \tag{4.1}\\
u\left(\frac{1}{2}^{+}\right)-u\left(\frac{1}{2}^{-}\right)=I_{1}\left(u\left(\frac{1}{2}\right)\right),  \tag{4.2}\\
u^{\Delta}(1)=0,2 u(0)-u^{\Delta}(0)=\int_{0}^{1} u(s) \triangle s, \tag{4.3}
\end{gather*}
$$

where

$$
f(t, u)= \begin{cases}\frac{1}{26}(1-u), & u \in[0,1] ; \\ 51(u-1), & u \in(1,4] ; \\ \frac{7}{11}(u-4)+153, & u \in(4, \infty)\end{cases}
$$

and

$$
I_{1}(u)=\frac{u}{10} .
$$

Taking $\rho_{1}=1, \rho_{2}=4, \rho_{3}=70, \alpha=2$ and $\beta=1$, we have $l=\frac{1}{5}, L=1, \gamma=\frac{1}{3}$. We can obtain that

$$
\rho_{1}<\gamma \rho_{2} \quad \text { and } \quad \rho_{2}<\rho_{3} .
$$

Now, we show that (H3) is satisfied:

$$
\begin{aligned}
f_{0}^{1} & =\frac{1}{26}<\phi_{2}\left(\frac{1}{5}\right)=\frac{1}{25}, \quad f_{\frac{4}{3}}^{4}=\frac{51}{48}>\phi_{2}(1)=1 \\
f_{0}^{70} & <0.039<\phi_{2}\left(\frac{1}{5}\right)=0.04, \quad I_{0}^{1}=\left(\frac{1}{10}\right)<l \rho_{1}=\frac{1}{5} \quad \text { and } \quad I_{0}^{70}=7<l \rho_{3}=14
\end{aligned}
$$

Then, all conditions of Theorem 3.5 hold. Hence, we get the BVP (4.1)-(4.3) has at least two positive solutions.

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