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## SOLUTIONS OF A CLASS OF INTERNAL NONLOCAL CAUCHY PROBLEMS FOR THE DIFFERENTIAL EQUATION x'(t) = f(t, x(t), x'(t))

A.M.A. EL-SAYED\*, E.M. HAMDALLAH\*\* AND KH. W. ELKADEKY\*\*\*

\*Faculty of Science, Alexandria University, Alexandria, Egypt E-mail: amasayed@hotmail.com

\*\*Faculty of Science, Alexandria University, Alexandria, Egypt E-mail: emanhamdalla@hotmail.com

\*\*\*Faculty of Science, Garyounis University, Benghazi, Libya E-mail: k-welkadeky@yahoo.com

**Abstract.** In this work, we study the existence of solutions for the Cauchy problem of the differential equation x'(t) = f(t, x(t), x'(t)) with some general class of internal nonlocal and integral conditions. **Key Words and Phrases**: Internal nonlocal conditions, integral conditions, functional integral equation, fixed-point theorem.

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## 1. INTRODUCTION

Problems with non-local conditions have been extensively studied by several authors in the last two decades. The reader is referred to [1]-[6] and [9]-[19] and references therein.

Here we are concerning with the Cauchy problem of the differential equation

$$x'(t) = f(t, x(t), x'(t)), \text{ for } a.e. \ t \in (0, 1)$$
(1.1)

with the general internal nonlocal condition

$$\sum_{k=1}^{m} a_k x(\tau_k) = \alpha \sum_{j=1}^{n} b_j x(\eta_j)$$
(1.2)

where  $\tau_k \in (a, c), \ \eta_j \in (d, b), \ 0 < a < c \leq d < b < 1 and \alpha$  is parameter.

Our aim here is to study the existence of at least one absolutely continuous solution  $x \in AC[0,1]$  for the problem (1.1)-(1.2) when the function f is measurable in  $t \in [0,1]$  for any  $(u_1, u_2) \in \mathbb{R}^2$  and continuous in  $(u_1, u_2) \in \mathbb{R}^2$  for almost all  $t \in [0,1]$ . Also we deduce the existence of solutions for the Cauchy problem of equation (1) with the nonlocal integral condition

$$\int_{a}^{c} x(s) \, ds = \alpha \int_{d}^{b} x(s) \, ds.$$
(1.3)
  
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It must be noticed that the following nonlocal and integral conditions are special cases of our nonlocal and integral conditions

$$x(\tau) = \beta x(\eta), \ \tau \in (a,c) \text{ and } \eta \in (d,b), \tag{1.4}$$

$$\sum_{k=1}^{m} a_k x(\tau_k) = \beta x(\eta), \ \tau_k \in (a,c) \text{ and } \eta \in (d,b),$$
(1.5)

$$\sum_{k=1}^{m} a_k x(\tau_k) = 0, \ \tau_k \in (a, c),$$
(1.6)

$$\int_{a}^{c} x(s) ds = \beta x(\eta), \ \eta \in (d, b),$$

$$(1.7)$$

and

$$\int_{a}^{c} x(s) \, ds = 0, \ (a,c). \tag{1.8}$$

The following theorems will be needed.

Theorem. (Kolmogorov Compactness Criterion) (see [8])

- Let  $\Omega \subseteq L^P(0,1), \ 1 \leq P < \infty$ . If
  - (i)  $\Omega$  is bounded  $L^p(0,1)$ ,
- (ii)  $x_h \to x$  as  $h \to 0$  uniformly with respect to  $x \in \Omega$ , then  $\Omega$  is relatively compact in  $L^P(0,1)$ , where

$$x_h(t) = \frac{1}{h} \int_t^{t+h} x(s) \, ds.$$

Theorem. (Schauder) (see 
$$[14]$$
)

Let U be a convex subset of a Banach space X, and  $T: U \to U$  is compact, continuous map. Then T has at least one fixed point in U.

2. EXISTENCE OF SOLUTION

Consider the nonlocal problem (1)-(2). Let 
$$\frac{dx(t)}{dt} = y(t)$$
, then  
 $y(t) = f(t, x(t), y(t))$  (2.1)

and

$$x(t) = x(0) + \int_0^t y(s) \, ds.$$
(2.2)

Let  $t = \tau_k$  in (2.2), we obtain

$$x(\tau_k) = x(0) + \int_0^{\tau_k} y(s) \, ds,$$

than

$$\sum_{k=1}^{m} a_k x(\tau_k) = \sum_{k=1}^{m} a_k x(0) + \sum_{k=1}^{m} a_k \int_0^{\tau_k} y(s) \, ds.$$
(2.3)

Let  $t = \eta_j$  in (2.2), we can obtain

$$\alpha \sum_{j=1}^{n} b_j x(\eta_j) = \alpha \sum_{j=1}^{n} b_j x(0) + \alpha \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) \, ds.$$
(2.4)

From (2.3) and (2.4), we obtain

$$x(0) = A(\sum_{k=1}^{m} a_k \int_0^{\tau_k} y(s) \, ds - \alpha \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) \, ds).$$
(2.5)

Substitute from (2.5) into (2.2), we get

$$x(t) = A(\sum_{k=1}^{m} a_k \int_0^{\tau_k} y(s) \, ds - \alpha \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) \, ds) + \int_0^t y(s) \, ds, \qquad (2.6)$$

where y is the solution of the functional integral equation

$$y(t) = f(t, \{A(\sum_{k=1}^{m} a_k \int_0^{\tau_k} y(s) \, ds - \alpha \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) \, ds) + \int_0^t y(s) \, ds\}, \ y(t)).$$
(2.7)

Then we proved the following lemma.

**Lemma 2.1.** Let  $\alpha \sum_{j=1}^{n} b_j \neq -\sum_{k=1}^{m} a_k$ . Then the solution of the nonlocal problem (1)-(2) can be expressed by the integral equation (2.6) where y is the solution of the functional integral equation (2.7).

Consider the functional equation (2.7) with the following assumptions

- (i)  $f: [0,1] \times \mathbb{R}^2 \to \mathbb{R}$  is measurable in  $t \in [0,1]$ , for any  $(u_1, u_2) \in \mathbb{R}^2$  and continuous in  $(u_1, u_2) \in \mathbb{R}^2$ , for almost all  $t \in [0,1]$ .
- (ii) There exists a function  $a \in L_1[0,1]$  and constant  $b_i > 0$ ; i = 1,2 such that

$$|f(t, u_1, u_2)| \le |a(t)| + \sum_{i=1}^{2} b_i |u_i|; \ \forall (t, u_1, u_2) \in [0, 1] \times \mathbb{R}^2.$$

(iii) 
$$(Ab_1(\sum_{k=1}^m a_k + \alpha \sum_{j=1}^n b_j) + b_1 + b_2) < 1.$$

Now, we have the following theorem.

**Theorem 2.1.** Assume that the assumptions (i) - (iii) are satisfied. Then the functional integral equation (2.7) has at least one solution  $y \in L_1[0, 1]$ . *Proof.* Define the operator H by

$$Hy(t) = f(t, \{A(\sum_{k=1}^{m} a_k \int_0^{\tau_k} y(s) \, ds - \alpha \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) \, ds) + \int_0^t y(s) \, ds\}, \ y(t)).$$

$$(2.8)$$

Let

$$B_r = \{y : ||y||_{L_1} \le r, \ r > 0\},\$$
  
$$r = ||a||(1 - (Ab_1(\sum_{k=1}^m a_k + \alpha \sum_{j=1}^n b_j) + b_1 + b_2))^{-1}.$$

Clearly  $B_r$  is nonempty, convex and closed. Let  $y \in B_r$ , then from assumptions (i) and (iii), we obtain

$$||Hy||_{L_1} = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds) + \int_0^t y(s)ds\}, y(t))|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds) + \int_0^t y(s)ds\}, y(t))|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds) + \int_0^t y(s)ds\}, y(t))|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds) + \int_0^t y(s)ds\}, y(t))|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds) + \int_0^t y(s)ds\}, y(t))|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds) + \int_0^t y(s)ds\}, y(t))|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds) + \int_0^t y(s)ds\}, y(t))|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds) + \int_0^t y(s)ds\}, y(t))|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds] + \int_0^t y(s)ds\}, y(t)|dt| = \int_0^1 |f(t, \{A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s)ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s)ds] + \int_0^t y(s)ds\}$$

$$\leq \int_{0}^{1} (|a(t)| + b_{1}|A\sum_{k=1}^{m} a_{k} \int_{0}^{\tau_{k}} y(s)ds - A\alpha \sum_{j=1}^{n} b_{j} \int_{0}^{\eta_{j}} y(s)ds + \int_{0}^{t} y(s)ds| + b_{2}|y(t)|)dt$$

$$\leq \int_{0}^{1} (|a(t)| + Ab_{1}\sum_{k=1}^{m} a_{k} \int_{0}^{\tau_{k}} |y(s)| + Ab_{1}\alpha \sum_{j=1}^{n} \int_{0}^{\eta_{j}} |y(s)|ds + b_{1} \int_{0}^{t} |y(s)|ds + b_{2}|y(t)|)dt$$

$$\leq ||a|| + Ab_{1}\sum_{k=1}^{m} a_{k}||y|| + Ab_{1}\alpha \sum_{j=1}^{n} b_{j}||y|| + b_{1}||y|| + b_{2}||y||$$

$$\leq ||a|| + (Ab_{1}\sum_{k=1}^{m} a_{k} + Ab_{1}\alpha \sum_{j=1}^{n} b_{j} + b_{1} + b_{2})||y||$$

$$\leq ||a|| + (Ab_{1}(\sum_{k=1}^{m} a_{k} + \alpha \sum_{j=1}^{n} b_{j}) + b_{1} + b_{2})||y||$$

$$\leq ||a|| + (Ab_{1}(\sum_{k=1}^{m} a_{k} + \alpha \sum_{j=1}^{n} b_{j}) + b_{1} + b_{2})||y||$$

Then  $||Hy||_{L_1} \leq r$ , which implies that the operator H maps  $B_r$  into itself, *i.e*  $H: B_r \to B_r$ .

Assumption (ii) implies  $f \in L_1 \to L_1$  and assumption (i) implies that H is continuous. To apply Schauder fixed point theorem it remains to show that H is compact Now, let  $\Omega$  be a bounded subset of  $B_r$ , therefore  $H(\Omega)$  is bounded in  $L_1[0,1]$ , *i.e* condition (i) of Kolmogorov compactness criterion is satisfied, it remains to show that

$$(Hy)_h \to (Hy), \text{ in } L_1[0,1].$$

Let  $y \in \Omega \subset L_1[0,1]$ , we have the following estimation

$$\begin{aligned} ||(Hy)_{h} - (Hy)||_{L_{1}} &= \int_{0}^{1} |(Hy)_{h}(t) - (Hy)(t)| \ dt \\ &= \int_{0}^{1} |\frac{1}{h} \int_{t}^{t+h} (Hy)(s) \ ds - (Hy)(t)| \ dt \ \leq \int_{0}^{1} (\frac{1}{h} \int_{t}^{t+h} |(Hy)(s) - (Hy)(t)| \ ds) \ dt \\ &\leq \int_{0}^{1} \frac{1}{h} \int_{t}^{t+h} |f(s, A\sum_{k=1}^{m} a_{k} \int_{0}^{\tau_{k}} y(\tau) d\tau - \alpha A \sum_{j=1}^{n} b_{j} \int_{0}^{\eta_{j}} y(\tau) d\tau + \int_{0}^{s} y(\tau) d\tau, \ y(s)) \\ &- f(t, A\sum_{k=1}^{m} a_{k} \int_{0}^{\tau_{k}} y(s) ds - \alpha A \sum_{j=1}^{n} b_{j} \int_{0}^{\eta_{j}} y(s) ds + \int_{0}^{t} y(s) ds, \ y(t))| \ ds \ dt. \end{aligned}$$

Now  $f \in L_1 \to L_1$  and  $y \in \Omega \subset L_1$  implies that  $f \in L_1[0,1]$  and

$$\frac{1}{h} \int_{t}^{t+h} |f(s, A \sum_{k=1}^{m} a_{k} \int_{0}^{\tau_{k}} y(\tau) d\tau$$
$$- \alpha A \sum_{j=1}^{n} b_{j} \int_{0}^{\eta_{j}} y(\tau) d\tau + \int_{0}^{s} y(\tau) d\tau, \ y(s)) - f(t, A \sum_{k=1}^{m} a_{k} \int_{0}^{\tau_{k}} y(s) ds$$

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$$-\alpha A \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) ds + \int_0^t y(s) ds, \ y(t)) | \ ds \to 0 \ as \ h \to 0, \ for \ t \in [0,1].$$

Therefore  $(Hy)_h \to (Hy)$ , uniformly as  $h \to 0$ . Then by Kolmogorov compactness criterion,  $H(\Omega)$  is relatively compact. Hence H has a fixed point in  $B_r$ , then there exists at least one solution  $y \in L_1[0,1]$  such that  $y(t) = f(t, x(t), y(t)), t \in [0,1]$ .  $\Box$ **Theorem 2.2.** Let the assumptions (i) - (iii) are satisfied. Then the nonlocal problem (1)-(2) has at least one an absolutely continuous solution  $x \in AC[0,1]$ .

*Proof.* Form Theorem 2.1 and the integral equation (2.6) we deduce that there exists at least one absolutely continuous solution  $x \in AC(0, 1)$  of the integral equation (2.6). Therefore the integral equation (2.6) has at least one absolutely continuous solution  $x \in AC(0, 1)$ . Now,

$$\lim_{t \to 0} x(t) = A(\sum_{k=1}^{m} a_k \int_0^{\tau_k} y(s) \, ds - \alpha \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) \, ds) + \lim_{t \to 0} \int_0^t y(s) \, ds = x(0),$$

$$\lim_{t \to 1} x(t) = A(\sum_{k=1}^{m} a_k \int_0^{\tau_k} y(s) \, ds - \alpha \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) \, ds) + \int_0^1 y(s) \, ds = x(1).$$

Then the integral equation (2.6) has at least one an absolutely continuous solution  $x \in AC[0,1]$  .

To complete the proof, we prove that the integral equation (2.6) satisfies nonlocal problem (1)-(2). Differentiating (2.6), we get

$$\frac{dx}{dt} = y(t) = f(t, x(t), \frac{dx}{dt}).$$

Let  $t = \tau_k$  in (2.6), we obtain

$$x(\tau_k) = A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s) \, ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s) \, ds) + \int_0^{\tau_k} y(s) \, ds$$
$$= (A \sum_{k=1}^m a_k + 1) \int_0^{\tau_k} y(s) \, ds - \alpha a \sum_{j=1}^n b_j \int_0^{\eta_j} y(s) \, ds.$$

Then

$$\sum_{k=1}^{m} a_k x(\tau_k) = \sum_{k=1}^{m} a_k (A \sum_{k=1}^{m} a_k + 1) \int_0^{\tau_k} y(s) ds - \alpha A \sum_{k=1}^{m} a_k \sum_{j=1}^{n} b_j \int_0^{\eta_j} y(s) ds.$$
(2.9)

Also, let  $t = \eta_j$  in (2.6), we obtain

$$\begin{aligned} x(\eta_j) &= A(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s) \, ds - \alpha \sum_{j=1}^n b_j \int_0^{\eta_j} y(s) \, ds) + \int_0^{\eta_j} y(s) \, ds \\ &= A \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) \, ds + (1 - \alpha A \sum_{j=1}^n b_j) \int_0^{\eta_j} y(s) \, ds \end{aligned}$$

$$\alpha \sum_{j=1}^{n} b_j x(\eta_j) = \alpha A \sum_{j=1}^{n} b_j \sum_{k=1}^{m} a_k \int_0^{\tau_k} y(s) ds + \alpha \sum_{j=1}^{n} b_j (1 - \alpha A \sum_{j=1}^{n} b_j) \int_0^{\eta_j} y(s) ds.$$
(2.10)

Subtraction (2.10) from (2.9), we obtain

$$\sum_{k=1}^{m} a_k x(\tau_k) - \alpha \sum_{j=1}^{n} b_j x(\eta_j) = 0.$$

This completes the proof of the equivalent between the nonlocal problem (1)-(2) and the integral equation (2.6). This implies that there exists at least one absolutely continuous solution  $x \in AC[0, 1]$  of the nonlocal problem (1)-(2).

Now letting  $\alpha = 0$  in (2), then we can easily prove the following corollary. Corollary 2.1. Let the assumptions (i) - (iii) are satisfied. Then the nonlocal problem

$$\frac{dx(t)}{dt} = f(t, x(t), \frac{dx(t)}{dt}), \text{ for a.e. } t \in (0, 1),$$
$$\sum_{k=1}^{m} a_k x(\tau_k) = 0.$$

has at least one an absolutely continuous solution  $x \in AC[0,1]$ .

## 3. Nonlocal integral condition

Let  $x \in [0, 1]$  be a solution of the nonlocal problem (1)-(2). Let  $a_k = t_k - t_{k-1}, \tau_k \in (t_{k-1}, t_k) = (a, c) \subset (0, 1)$  and let  $b_j = t_j - t_{j-1}, \eta_j \in (t_{j-1}, t_j) = (b, d) \subset (0, 1)$ , then the nonlocal condition (2) will be

$$\sum_{k=1}^{m} (t_k - t_{k-1}) x(\tau_k) = \alpha \sum_{j=1}^{n} (t_j - t_{j-1}) x(\eta_j).$$

From the continuity of the solution x of the nonlocal condition (2) we obtain

$$\lim_{m \to \infty} \sum_{k=1}^{m} (t_k - t_{k-1}) \ x(\tau_k) = \lim_{n \to \infty} \alpha \sum_{j=1}^{n} (t_j - t_{j-1}) \ x(\eta_j).$$

*i.e* the nonlocal condition (2) transformed to the integral condition

$$\int_{a}^{c} x(s) \, ds = \alpha \int_{b}^{d} x(s) \, ds \tag{3.1}$$

and the solution of the integral equation (2.6) will be

$$x(t) = A \left( \int_{a}^{c} \int_{0}^{t} y(s) \, ds \, dt - \alpha \int_{d}^{b} \int_{0}^{t} y(s) \, ds \, dt \right) + \int_{0}^{t} y(s) \, ds. \tag{3.2}$$

Now, we have the following corollary.

**Corollary 3.1.** Let the assumptions (i)-(iii) of Theorem 2.1 are satisfied. Then the nonlocal problem with the integral condition

$$\frac{dx(t)}{dt} = f(t, x(t), \frac{dx(t)}{dt}), \text{ for a.e. } t \in (0, 1)$$
$$\int_{a}^{c} x(s) \ ds = \alpha \int_{d}^{b} x(s) \ ds$$

has at least one an absolutely continuous solution  $x \in AC[0,1]$ .

Letting  $\alpha = 0$  in (2.6), the we can easily prove the following corollary. Corollary 3.2. Let the assumptions (i) - (iii) are satisfied. Then the nonlocal problem

$$\frac{dx(t)}{dt} = f(t, x(t), \frac{dx(t)}{dt}), \text{ for a.e. } t \in (0, 1),$$
$$\int_{a}^{c} x(s) \ ds = 0.$$

has at least one an absolutely continuous solution  $x \in AC[0,1]$ .

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