# PICARD OPERATORS ON ORDERED METRIC SPACES 

M. DERAFSHPOUR AND SH. REZAPOUR

Department of Mathematics
Azarbaijan Shahid Madani University
Azarshahr, Tabriz, Iran
E-mail: sh.rezapour@azaruniv.edu, rezapourshahram@yahoo.ca


#### Abstract

In this paper, we shall give some results about Picard operators on ordered metric spaces. In fact, we shall prove that some contractive-like mappings satisfying some conditions on ordered metric spaces are Picard operators. We shall also present an application of our results. Key Words and Phrases: Fixed point, Picard operator, orbitally continuous. 2010 Mathematics Subject Classification: 47H10, 54H25.


## 1. Introduction

As we know, there are many papers on fixed points of contractive mappings which introduced in 1962 ([7, 18]). In 1997, Runge introduced the notion of Picard modular forms [22]. By using this notion, Weikard introduced the notion of Picard operators in 1998 [27]. Also, Rus and Muresan reviewed data dependence of the fixed points set of weakly Picard operators in 1998 [23]. Later, Rus provided some results about fiber Picard operators [24]. In 2003 by using a distinct view, Rus defined the concept of Picard operators ([25]) and we use the notion of Picard operators in the sense of Rus. For applications of the Picard operators technique see [26]. There are many works on fixed point theory in partially ordered metric spaces (for example, $[1,2,3$, $4,5,6,8,9,12,13,14,15,16,17,19,20])$. Note that, not only a contractive map in ordered metric spaces is not continuous necessarily but also it is not a contraction map necessarily ( $[11,21]$ ). In this paper, we shall give some results about Picard operators on ordered metric spaces. In fact, we shall prove that some contractive-like mappings satisfying some conditions on ordered metric spaces are Picard operators.

Let $T: X \longrightarrow X$ be an operator. We denote the set of all non-empty invariant subsets by $I(T)$, that is $I(T)=\{Y \subset X \mid T(Y) \subseteq Y\}$. Also, we denote the fixed point set of $T$ by $F_{T}=\{x \in X: x=T(x)\}$. Let $(X, \leqslant)$ be a partially ordered set, that is $X$ is a nonempty set and $\leqslant$ is a reflexive, transitive and anti-symmetric relation on $X$. Denote the set of comparable elements of $X$ by $X_{\leqslant}$. If $x, y \in X$ with $x \leqslant y$, then by $[x, y] \leqslant$ we shall denote the ordered segment joining $x$ and $y$. For a mapping $T: X \rightarrow X$, we denote the lower fixed point set of $T$ by $(L F)_{T}:=\{x \in X \mid x \leqslant T(x)\}$ while we denote the upper fixed point set of $T$ by $(U F)_{T}:=\{x \in X \mid x \geqslant T(x)\}$. Also, for the mappings $T: X \rightarrow X$ and $S: Y \rightarrow Y$, the cartesian product of $T$ and $S$ is
denoted by $T \times S: X \times Y \rightarrow X \times Y$ and defined by $(T \times S)(x, y)=(T(x), S(x))$. We appeal next well-known relation in the following.
$(*)$ If $x_{n} \rightarrow x, z_{n} \rightarrow x$ and $x_{n} \leqslant y_{n} \leqslant z_{n}$ for all $n$, then $y_{n} \rightarrow x$.
In the literature, an ordered metric space is a metric space endowed with an order that, in addition, satisfy the compatibility condition $(*)$. In this paper, we use only the terminology ordered metric space and we denote it by $(X, d, \leq)$.

Here, we recall the notion of Picard operators. Let ( $X, d, \leq$ ) be an ordered metric space. An operator $T: X \rightarrow X$ is called a Picard operator (briefly PO) whenever $F_{T}=\left\{x^{*}\right\}$ and $\left(T^{n}(x)\right)_{n \geq 1} \rightarrow x^{*}$ for all $x \in X$. Also, we say that a selfmap $T: X \rightarrow X$ is orbitally continuous whenever for each $x \in X$ and sequence $\{n(i)\}_{i \geq 1}$ with $T^{n(i)} x \rightarrow a$ for some $a \in X$, we have $T^{n(i)+1} x \rightarrow T a$. Here, $T^{m+1}=T\left(T^{m}\right)$.

Let $\mathcal{S}$ denote the class of functions $\beta:[0, \infty) \rightarrow[0,1)$ which satisfy the condition $\beta\left(t_{n}\right) \rightarrow 1$ implies that $t_{n} \rightarrow 0$. An altering function is a non-decreasing continuous function $\psi:[0, \infty) \rightarrow[0, \infty)$ such that $\psi(t)=0$ if and only if $t=0$.

## 2. Main Results

Now, we are ready to state and prove our main results.
Theorem 2.1. Let $(X, d, \leqslant)$ be an ordered metric space and $T$ an operator. Suppose that
(i) for each $x, y \in X$ with $(x, y) \notin X_{\leqslant}$there exists $z \in X$ such that $(x, z) \in X_{\leqslant}$and $(y, z) \in X_{\leqslant} ;$
(ii) $X_{\leqslant} \in I(T \times T)$;
(iii) if $(x, y) \in X_{\leqslant}$and $(y, z) \in X_{\leqslant}$, then $(x, z) \in X_{\leqslant}$;
(iv) there exists $x_{0} \in X$ such that $\left(x_{0}, T\left(x_{0}\right)\right) \in X_{\leqslant}$;
(v) $T$ is orbitally continuous
(vi) there exists $\beta \in \mathcal{S}$ such that $d(T x, T y) \leqslant \beta(d(x, y)) d(x, y)$ for all $(x, y) \in X_{\leqslant}$;
(vii) the metric $d$ is complete.

Then $T$ is a $\mathbf{P O}$.
Proof. Choose $x_{0} \in X$ such that $\left(x_{0}, T\left(x_{0}\right)\right) \in X_{\leqslant}$. Suppose first that $x_{0} \neq T\left(x_{0}\right)$. By using (ii), $\left(T^{n}\left(x_{0}\right), T^{n+1}\left(x_{0}\right)\right) \in X_{\leqslant}$for all $n \geq 1$. Put $x_{n+1}=T\left(x_{n}\right)$. Since $\beta \in S$ and $\left(x_{n}, x_{n+1}\right) \in X_{\leqslant}$for all $n \geq 1$, by using (vi) we get

$$
d\left(x_{n+1}, x_{n}\right) \leqslant \beta\left(d\left(x_{n}, x_{n-1}\right)\right) d\left(x_{n}, x_{n-1}\right) \leqslant d\left(x_{n}, x_{n-1}\right)
$$

that is, for each $n \geq 1$ we have

$$
\begin{equation*}
d\left(x_{n+1}, x_{n}\right) \leqslant d\left(x_{n}, x_{n-1}\right) \tag{1}
\end{equation*}
$$

If there exists a natural number $n_{0}$ such that $d\left(x_{n_{0}}, x_{n_{0}-1}\right)=0$, then

$$
x_{n_{0}}=T\left(x_{n_{0}-1}\right)=x_{n_{0}-1}
$$

and so $x_{n_{0}-1}$ is a fixed point of $T$. Suppose that $d\left(x_{n+1}, x_{n}\right) \neq 0$ for all $n \geq 1$. Then taking into account (1), the sequence $\left\{d\left(x_{n+1}, x_{n}\right)\right\}$ is decreasing and bounded below, so we can suppose that $\lim _{n \rightarrow \infty} d\left(x_{n+1}, x_{n}\right)=r \geqslant 0$. Assume $r>0$. Then, we have

$$
\frac{d\left(x_{n+1}, x_{n}\right)}{d\left(x_{n}, x_{n-1}\right)} \leqslant \beta\left(d\left(x_{n}, x_{n-1}\right)\right) \leqslant 1
$$

Letting $n \rightarrow \infty$ in the last inequality, we get $1 \leqslant \lim _{n \rightarrow \infty} \beta\left(d\left(x_{n}, x_{n-1}\right)\right) \leqslant 1$ and so $\lim _{n \rightarrow \infty} \beta\left(d\left(x_{n}, x_{n-1}\right)\right)=1$. Since $\beta \in S, \lim _{n \rightarrow \infty}\left(d\left(x_{n+1}, x_{n}\right)\right)=0$ which is a contradiction. Hence,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} d\left(x_{n+1}, x_{n}\right)=0 \tag{2}
\end{equation*}
$$

Now, we show that $\left\{x_{n}\right\}$ is a Cauchy sequence. If $\left\{x_{n}\right\}$ is not a Cauchy sequence, then there exist $\varepsilon>0$ and subsequences $\left\{x_{m(k)}\right\}$ and $\left\{x_{n(k)}\right\}$ of $\left\{x_{n}\right\}$ with $n(k)>m(k)>k$ such that

$$
\begin{equation*}
d\left(x_{n(k)}, x_{m(k)}\right) \geqslant \varepsilon . \tag{3}
\end{equation*}
$$

Further, corresponding to $m(k)$, we can choose $n(k)$ in such a way that it is the smallest integer with $n(k)>m(k)$ and satisfying (3). Thus,

$$
\begin{equation*}
d\left(x_{n(k)-1}, x_{m(k)}\right)<\varepsilon . \tag{4}
\end{equation*}
$$

Now, by using (3), (4) and triangular inequality, we get

$$
\varepsilon \leqslant d\left(x_{n(k)}, x_{m(k)}\right) \leqslant d\left(x_{n(k)-1}, x_{m(k)}\right)+d\left(x_{n(k)-1}, x_{m(k)}\right)<d\left(x_{n(k)}, x_{n(k)-1}\right)+\varepsilon .
$$

If $k \rightarrow \infty$, then by using (2) we get

$$
\begin{equation*}
\lim _{k \rightarrow \infty} d\left(x_{n(k)}, x_{m(k)}\right)=\varepsilon . \tag{5}
\end{equation*}
$$

Again, the triangular inequality gives us

$$
\begin{aligned}
& \quad d\left(x_{n(k)}, x_{m(k)}\right) \leqslant d\left(x_{n(k)}, x_{n(k)-1}\right)+d\left(x_{n(k)-1}, x_{m(k)-1}\right)+d\left(x_{m(k)-1}, x_{m(k)}\right), \\
& d\left(x_{n(k)}, x_{m(k)-1}\right) \leqslant d\left(x_{n(k)}, x_{n(k)-1}\right)+d\left(x_{n(k)-1}, x_{m(k)}\right)+d\left(x_{m(k)-1}, x_{m(k)}\right) . \\
& \text { If } k \rightarrow \infty, \text { then by using (2) and (5) and above inequalities, we obtain }
\end{aligned}
$$

$$
\begin{equation*}
\lim _{k \rightarrow \infty} d\left(x_{n(k)-1}, x_{m(k)-1}\right)=\varepsilon \tag{6}
\end{equation*}
$$

Since $n(k)>m(k)$ and $\left(x_{n(k)-1}, x_{m(k)-1}\right) \in X_{\leqslant}$, we have

$$
\begin{gather*}
d\left(x_{n(k)}, x_{m(k)}\right)=d\left(T\left(x_{n(k)-1}\right), T\left(x_{m(k)-1}\right)\right) \\
\leqslant \beta\left(d\left(x_{n(k)-1}, x_{m(k)-1}\right)\right) d\left(x_{n(k)-1}, x_{m(k)-1}\right) \leqslant d\left(x_{n(k)-1}, x_{m(k)-1}\right) . \tag{7}
\end{gather*}
$$

If $k \rightarrow \infty$ in (7), then by using (5) and (6), we get

$$
\lim _{k \rightarrow \infty} \beta\left(d\left(x_{n(k)-1}, x_{m(k)-1}\right)\right)=1
$$

Since $\beta \in S$,

$$
\lim _{k \rightarrow \infty} d\left(x_{n(k)-1}, x_{m(k)-1}\right)=0
$$

The relation (6) shows that this is a contradiction. Thus, $\left\{x_{n}\right\}$ is a Cauchy sequence. Since $(X, d)$ is a complete metric space, there exists $x^{*} \in X$ such that

$$
\lim _{n \rightarrow \infty} x_{n}=x^{*}
$$

Since $T$ is orbitally continuous, $x^{*}$ is a fixed point of $T$. By using (vi), it is easy to see that $x^{*}$ is unique. Now, let $x \in X$ be given. Then we have the following cases:
(a) If $\left(x, x_{0}\right) \in X_{\leqslant}$, then $\left(T^{n}(x), T^{n}\left(x_{0}\right)\right) \in X_{\leqslant}$and so by using (vi) we get that

$$
u_{n}=d\left(T^{n}(x), T^{n}\left(x_{0}\right)\right)
$$

is a non-negative decreasing sequence. Thus, there exists $u \geq 0$ such that $u_{n} \rightarrow u$. If $u=0$, then $T^{n}(x) \rightarrow x^{*}$ because $T^{n}\left(x_{0}\right)=x_{n} \rightarrow x^{*}$. Let $u \neq 0$. In this case, by using (vi) for each $n \geq 1$ we obtain

$$
d\left(T^{n}(x), T^{n}\left(x_{0}\right)\right) \leqslant \beta\left(d\left(T^{n-1}(x), x_{n-1}\right)\right) d\left(T^{n-1}(x), x_{n-1}\right)
$$

Therefore,

$$
\liminf _{n \rightarrow \infty} \beta\left(d\left(T^{n-1}(x), x_{n-1}\right)\right)=\limsup _{n \rightarrow \infty} \beta\left(d\left(T^{n-1}(x), x_{n-1}\right)\right)=1
$$

Hence,

$$
\lim _{n \rightarrow \infty} d\left(T^{n-1}(x), x_{n-1}\right)=\lim _{n \rightarrow \infty} d\left(T^{n-1}(x), x^{*}\right)=0
$$

because $\beta \in \mathcal{S}$. Thus, $T^{n}(x) \rightarrow x^{*}$.
(b) If $\left(x, x_{0}\right) \notin X_{\leqslant}$, then by using (i) there exists $z_{0} \in X_{\leqslant}$such that $\left(x, z_{0}\right) \in X_{\leqslant}$ and $\left(z_{0}, x_{0}\right) \in X_{\leqslant}$. By using the part (a) we know that $T^{n}\left(z_{0}\right) \rightarrow x^{*}$. Now, put $z_{n+1}=T z_{n}$ for all $n \geq 0$. Since $\left(x, z_{0}\right) \in X_{\leqslant},\left(T^{n}(x), T^{n}\left(z_{0}\right)\right) \in X_{\leqslant}$for all $n \geq 1$. Thus by using (ii) we get $w_{n}=d\left(T^{n}(x), T^{n}\left(z_{0}\right)\right) \leqslant d\left(T^{n-1}(x), T^{n-1}\left(z_{0}\right)\right)=w_{n-1}$ for all $n \geq 1$. Therefore, $\left\{w_{n}\right\}_{n \in \mathbb{N}}$ is a non-increasing and non-negative sequence. Hence, there exists $w \geq 0$ such that $w_{n} \rightarrow w$. If $w=0$, then $T^{n}(x) \rightarrow x^{*}$. Let $w \neq 0$. In this case, by using $(v)$ for each $n \geq 1$ we obtain
$d\left(T^{n}(x), T^{n}\left(z_{0}\right)\right)=d\left(T\left(T^{n-1}(x)\right), T\left(z_{n-1}\right)\right) \leqslant \beta\left(d\left(T^{n-1}(x), z_{n-1}\right)\right) d\left(T^{n-1}(x), z_{n-1}\right)$.
Hence,

$$
\lim _{n \rightarrow \infty} \beta\left(d\left(T^{n-1}(x), z_{n-1}\right)\right)=1
$$

Thus,

$$
\lim _{n \rightarrow \infty} d\left(T^{n-1}(x), z_{n-1}\right)=0
$$

because $\beta \in \mathcal{S}$. Since $T^{n}\left(z_{0}\right) \rightarrow x^{*}, T^{n}(x) \rightarrow x^{*}$.
Now by using Theorem 7 in [10], we can replace the following conditions instead the condition (vi) of Theorem 2.1. A similar cases hold for another results of this paper.
(a)- There exists a continuous function $\eta:[0, \infty) \rightarrow[0, \infty)$ such that $\eta^{-1}(\{0\})=\{0\}$ and $d(T x, T y) \leqslant d(x, y)-\eta(d(x, y))$ holds for all $(x, y) \in X_{\leqslant}$.
(b)- There exists a continuous and nondecreasing function $\varphi:[0, \infty) \rightarrow[0, \infty)$ such that $\varphi(t)<t$ for all $t>0$ and $d(T x, T y) \leqslant \varphi(d(x, y))$ holds for all $(x, y) \in X_{\leqslant}$.
(c)- There exist a continuous and nondecreasing function $\psi:[0, \infty) \rightarrow[0, \infty)$ with $\psi^{-1}(\{0\})=\{0\}$ and a nondecreasing, right continuous function $\varphi:[0, \infty) \rightarrow[0, \infty)$ such that $\varphi(t)<t$ for all $t>0$ and $\psi(d(T x, T y)) \leqslant \varphi(\psi(d(x, y)))$ holds for all $(x, y) \in X_{\leqslant}$.
(d)- There exist continuous and nondecreasing functions $\mu, \nu:[0, \infty) \rightarrow[0, \infty)$ with $\mu^{-1}(\{0\})=\{0\}, \nu^{-1}(\{0\})=\{0\}$ and $\mu(d(T x, T y)) \leqslant \mu(d(x, y))-\nu(d(x, y))$ holds for all $(x, y) \in X_{\leqslant}$.

Remark 2.1. A new theorem can be obtained replacing condition (vi) in Theorem 2.1 with the following condition:
there exists a $\beta \in \mathcal{S}$ such that $\psi(d(T x, T y)) \leqslant \beta(d(x, y)) \psi(d(x, y))$ for all $(x, y) \in X_{\leqslant}$, where $\psi$ is an altering function.

Remark 2.2. A new theorem can be obtained replacing condition (vi) in Theorem 2.1 with the following condition:
there exists a $\beta \in \mathcal{S}$ such that $\psi(d(T x, T y)) \leqslant \beta(d(x, y)) \psi(d(x, y))$ for all $(x, y) \in X_{\leqslant}$, where $\psi$ is an altering function.

Remark 2.3. A new theorem can be obtained replacing condition (vi) in Theorem 2.1 with the following condition:
there exists $\beta \in \mathcal{S}$ such that

$$
d(T x, T y) \leqslant \beta\left(\max \left\{d(x, y), d(x, T x), d(y, T y), \frac{1}{2}[d(x, T y)+d(y, T x)]\right\}\right) d(x, y)
$$

for all $(x, y) \in X_{\leqslant}$.

## 3. An Application

In this section, we present an application of our abstract results. We will study the existence of solution for the following first-order periodic problem

$$
\left\{\begin{array}{l}
u^{\prime}(t)=f(t, u(t)), \quad t \in[0, T]  \tag{8}\\
u(0)=u(T),
\end{array}\right.
$$

where $T>0$ and $f: I \times \mathbb{R} \longrightarrow \mathbb{R}$ is a continuous function. Consider the complete metric space $\mathcal{C}(I)(I=[0, T])$ via the sup norm. The space $\mathcal{C}(I)$ can be equipped with the partial order $x \leq y$ whenever $x(t) \leq y(t)$ for all $t \in I$. It's easy to see that for each $x, y \in \mathcal{C}(I)$ there exists a lower bound $(\min \{x, y\})$ and an upper bound $(\max \{x, y\})$. Suppose that $\mathcal{A}$ denotes the class of functions $\phi:[0, \infty) \rightarrow[0, \infty)$ satisfying
(i) $\phi$ is nondecreasing,
(ii) $\phi(x)<x$ for $x>0$,
(iii) $\beta(x)=\frac{\phi(x)}{x} \in \mathcal{S}$.

In fact,

$$
\phi(t)=\mu \cdot t(0 \leq \mu<1), \phi(t)=\frac{t}{1+t}
$$

and $\phi(t)=\ln (1+t)$ are some examples of such functions. Recall now the following definition.

Definition 3.1. A lower solution for (8) is a function $\alpha \in \mathcal{C}^{1}(I)$ such that

$$
\left\{\begin{array}{l}
\alpha^{\prime}(t) \leq f(t, \alpha(t)), \quad(t \in I) \\
\alpha(0) \leq \alpha(T)
\end{array}\right.
$$

Similarly $\alpha \in \mathcal{C}^{1}(I)$ is an upper solution for (8) whenever

$$
\left\{\begin{array}{l}
\alpha^{\prime}(t) \geq f(t, \alpha(t)), \quad(t \in I) \\
\alpha(0) \geq \alpha(T)
\end{array}\right.
$$

Now, we present the following theorem about the existence of a solution for the problem (8) in presence of a lower or upper solution. The existence of a solution has been proved only for lower solution phase ([5]).

Theorem 3.1. Consider the problem (8) with a continuous function $f: I \times \mathbb{R} \rightarrow \mathbb{R}$. Suppose that there exist numbers $\lambda, \alpha$ such that $\alpha \leq\left(\frac{2 \lambda\left(e^{\lambda t}-1\right)}{T\left(e^{\lambda t}+1\right)}\right)^{\frac{1}{2}}$ and for each $x, y \in \mathbb{R}$ we have $f(t, y)+\lambda y-[f(t, x)+\lambda x] \leq \alpha \sqrt{|y-x| \phi(y-x)}$, where $\phi \in \mathcal{A}$. Then the existence of a lower or upper solution for (8) provides the existence of a unique solution for (8).

Proof. The problem (8) can be rewrite as

$$
\left\{\begin{array}{l}
u^{\prime}(t)+\lambda u(t)=f(t, u(t))+\lambda u(t), \quad(t \in[0, T]) \\
u(0)=u(T)
\end{array}\right.
$$

This problem is equivalent to the integral equation

$$
u(t)=\int_{0}^{T} G(t, s)[f(s, u(s))+\lambda u(s)] d s
$$

where $G(t, s)$ is a green function given by

$$
G(t, s)= \begin{cases}\frac{e^{\lambda(T+s-t)}}{\left(e^{\lambda T}-1\right)}, & 0 \leq s<t \leq T \\ \frac{e^{\lambda(s-t)}}{\left(e^{\lambda T}-1\right)} . & 0 \leq t<s \leq T\end{cases}
$$

Define $F: \mathcal{C}(I) \rightarrow \mathcal{C}(I)$ by

$$
F(u)(t)=\int_{0}^{T} G(t, s)[f(s, u(s))+\lambda u(s)] d s
$$

If $u \in \mathcal{C}(I)$ is a fixed point of $F$, then $u \in \mathcal{C}^{1}(I)$ is a solution for (8). We check that $F$ satisfies the conditions of Proposition 2.1. It has been proved that for $(u, v) \in \mathcal{C}(I)_{\leq}$ we have ([5])

$$
d(F u, F v)^{2} \leq \frac{\phi(d(u, v))}{d(u, v)} \cdot d(u, v)^{2}
$$

Define

$$
\psi(x)=x^{2} \text { and } \beta=\frac{\phi(x)}{x}
$$

Since $\phi \in \mathcal{A}, \beta \in \mathcal{S}$. Also, note that $\psi$ is an altering function. Thus,

$$
\psi(d(F u, F v)) \leq \beta(d(u, v)) \dot{\psi}(d(u, v))
$$

for all $(u, v) \in \mathcal{C}(I)_{\leq}$. It is easy to see that $\mathcal{C}(I)_{\leq} \in I(F \times F)$. Also, there exists $x_{0} \in \mathcal{C}(I)$ such that $\left(x_{0}, F\left(x_{0}\right)\right) \in \mathcal{C}(I)_{\leq}$. In fact if $\alpha(t)$ be a lower solution for (8), from [4] we know that $\alpha(t) \leq(F \alpha)(t)$ for all $t \in I$. Similarly, If $\alpha(t)$ is an upper solution for (8), then we have $\alpha(t) \geq(F \alpha)(t)$, for all $t \in I$. Therefore, $F$ satisfies the
conditions of Proposition 2.1. Thus, $F$ is a Picard operator and so the problem (8) has a unique solution.

Acknowledgment. The authors express their gratitude to the referees for their helpful suggestions which improved final version of this paper.

## References

[1] R.P. Agarwal, M.A. El-Gebiely, D. O'Regan, Generalized contractions in partially ordered metric spaces, Appl. Analysis, 87(2008), 109-116.
[2] A. Amini-Harandi, H. Emami, A fixed point theorem for contractions in partially ordered metric spaces and application to ordinary differantial equations, Nonlinear Anal., 72(2010), 2238-2242.
[3] T.G. Bhashkar, V. Lakshmikantham, Fixed point theorems in partially ordered metric spaces and applications, Nonlinear Anal., 65(2006), 1379-1393.
[4] D. Burgec, S. Kalabusic, M.R.S. Kulanovic, Global attractivity results for mixed monotone mappings in partially ordered copmlete metric spaces, Fixed Point Theory and Appl., 2009, Article ID 762478.
[5] J. Caballero, J. Harjani, K. Sadarngani, Contractive-like mapping principles in ordered metric spaces and application to ordinary differential equations, Fixed Point Theory and Appl., 2010, Article ID 916064.
[6] L. Ciric, N. Cakid, M. Rjovi, J.S. Ume, Monotone generalized nonlinear contractions in partially ordered metric spaces, Fixed Point Theory and Appl., 2008, Article ID 131294.
[7] M. Edelstein, On fixed and periodic points under contractive mappings, J. London Math. Soc., 37(1962), 74-79.
[8] J. Harjani, K. Sadarangani, Fixed point theorems for weakly contractive mappings in partially ordered sets, Nonlinear Anal., 71(2009), 3403-3410.
[9] J. Harjani, K. Sadarangani, Generalized contractions in partially ordered metric spaces and applications to ordinary differential equations, Nonlinear Anal., 72 (2010), 1188-1197.
[10] J. Jachymski, Equivalent conditions for generalized contractions on (ordered) metric spaces, Nonlinear Analysis, 74(2011), 768-774.
[11] Z. Kadelburg, M. Pavlovic, S. Radenovic, Common fixed point theorems for ordered contractions and quasi-contractions in ordered cone metric spaces, Comput. Math. Appl., 59(2010), No. 9, 3148-3159.
[12] V. Lakshmikantham, L. Ciric, Coupled fixed point theorems for nonlinear contractions in partially ordered metric spaces, Nonlinear Anal., 70(2009), 4341-4349.
[13] J.J. Nieto, R. Rodriguez-Lopez, Contractive mapping theorems in partially ordered sets and applications to ordinary differential equations, Order, 22(2005), 223-239.
[14] J.J. Nieto, R.L. Pous, R. Rodriguez-Lopez, Fixed point theorems in ordered abstract spaces, Proc. Amer. Math. Soc., 135(2007), 2505-2517.
[15] J.J. Nieto, R. Rodriguez-Lopez, Existence and uniqueness of fixed point in partially ordered sets and applications to ordinary differential equations, Acta Math. Sinica, 23(2007), 2205-2212.
[16] D. O'Regan, A. Petrusel, Fixed point theorems for generalized contractions on ordered metric spaces, J. Math. Anal. Appl., 341(2008), 1241-1252.
[17] A. Petrusel, I.A. Rus, Fixed point theorems in ordered L-spaces, Proc. Amer. Math. Soc., 134(2006), 411-418.
[18] E. Rakotch, A note on contractive mappings, Proc. Amer. Math. Soc., 13(1962), 459-465.
[19] A.C.M. Ran, M.C.B. Reurings, A fixed point theorem in partially ordered sets and some applications to matrix equations, Proc. Amer. Math. Soc., 132(2004), 1435-1443.
[20] Sh. Rezapour, P. Amiri, Fixed point of multivalued operators on ordered generalized metric spaces, Fixed Point Theory, 13(2012), 173-179.
[21] Sh. Rezapour, M. Derafshpour, N. Shahzad, Best proximity points of cyclic $\varphi$-contractions in ordered metric spaces, Topol. Methods Nonlinear Analysis, 37(2011), 193-202.
[22] B. Runge, On Picard Modular Forms, Math. Nachr., 184(1997), 259-273.

23] I.A. Rus, S. Muresan, Data dependence of the fixed points set of weakly Picard operators, Studia Univ. Babes-Bolyai Math., 43(1998), No. 1, 79-83.
[24] I.A. Rus, Fiber Picard operators theorem and applications, Studia Univ. Babes-Bolyai Math., 44(1999), No. 3, 89-97.
[25] I.A. Rus, Picard operators and applications, Sci. Math. Jpn., 58(2003), 191-219
[26] I.A. Rus, Some nonlinear functional differential and integral equations via weakly Picard operator theory: A survey, Carpathian J. Math., 26(2010), 230-258.
[27] R. Weikard, Picard operators, Math. Nachr., 195(1998), 251-266.
Received: May 3, 2012; Accepted: June 21, 2012.

