

ULAM-HYERS STABILITY OF OPERATORIAL INCLUSIONS IN COMPLETE GAUGE SPACES

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Abstract. Using the weakly Picard operator technique, we will present some Ulam-Hyers stability results for operatorial inclusions using the weakly Picard operator technique. We study the Ulam-Hyers stability of some inclusions, where the multivalued operator satisfies some contraction conditions. We also give an application to integral inclusion.

Key Words and Phrases: Ulam-Hyers stability, multivalued operator, weakly Picard operator, c -weakly Picard operator, fixed point, integral inclusion.

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1. INTRODUCTION

In 1959, G. Marinescu [15] extended the Banach Contraction Principle to locally convex spaces, while I. Colojoară [7] and N. Gheorghiu [12] do the same thing to gauge spaces and R. J. Knill [14] to uniform spaces. In 1971, Cain and Nashed [4] extended the notion of contraction to Hausdorff locally convex linear spaces. They showed that on sequentially complete subset Banach Contraction Principle is still valid. V.G. Angelov [1] introduced in 1987 the notion of generalized φ -contractive single-valued map in gauge spaces, meanwhile the concept for multivalued operators was given in 1998 (see V.G. Angelov [2]). In 2000, M. Frigon [10] introduced the notion of singlevalued generalized contraction in gauge spaces and proved that every generalized contraction on a complete gauge space has a unique fixed point.

Definition 1.1. Let X be any set. A map $p : X \times X \rightarrow \mathbb{R}_+$ is called a pseudometric (a gauge) in X whenever

- (1) $p(x, y) \geq 0$, for all $x, y \in X$;
- (2) If $x = y$, then $p(x, y) = 0$;
- (3) $p(x, y) = p(y, x)$, for all $x, y \in X$;
- (4) $p(x, z) \leq p(x, y) + p(y, z)$, for all $x, y, z \in X$.

Definition 1.2. A family $\mathcal{P} = \{p_\alpha\}_{\alpha \in A}$ of pseudometrics on X (or a gauge structure on X), where A is a directed set, is said to be separating if for each pair of points $x, y \in X$, with $x \neq y$, there is a $p_\alpha \in \mathcal{P}$ such that $p_\alpha(x, y) \neq 0$.

A pair (X, \mathcal{P}) of a nonempty set X and a separating gauge structure \mathcal{P} on X is called a gauge space.

It is well known (see Dugundji [8], pages 198-204) that any family \mathcal{P} of pseudometrics on a set X induces on X a uniform structure \mathcal{U} and conversely, any uniform structure \mathcal{U} on X is induced by a family of pseudometrics on X . In addition, we have that \mathcal{U} is separating (or Hausdorff) if and only if \mathcal{P} is separating. Thus we may identify the gauge spaces and the Hausdorff uniform spaces.

Definition 1.3. A sequence $(x_n)_{n \in \mathbb{N}}$ of elements in X is said to be Cauchy if for every $\varepsilon > 0$ and $\alpha \in A$, there is an N with $p_\alpha(x_n, x_{n+p}) \leq \varepsilon$ for all $n \geq N$ and $p \in \mathbb{N}$.

The sequence $(x_n)_{n \in \mathbb{N}}$ is called convergent if there exists an $x_0 \in X$ such that for every $\varepsilon > 0$ and $\alpha \in A$, there is an N with $p_\alpha(x_0, x_n) \leq \varepsilon$ for all $n \geq N$.

Definition 1.4. A gauge space is called complete if any Cauchy sequence is convergent.

A subset of X is said to be sequentially closed if it contains the limit of any convergent sequence of its elements.

For further details see J. Dugundji [8], A. Granas, J. Dugundji [13], M. Frigon [11], I. A. Rus, A. Petruşel, G. Petruşel [24], T.P. Petru [17].

Let (X, \mathcal{P}) be a gauge space and consider the following families of subsets of X :

$$P(X) := \{Y \in \mathcal{P}(X) \mid Y \neq \emptyset\}, \quad P_b(X) := \{Y \in P(X) \mid Y \text{ is bounded}\},$$

$$P_{cl}(X) := \{Y \in P(X) \mid Y \text{ is closed}\}, \quad P_{cp}(X) := \{Y \in P(X) \mid Y \text{ is compact}\}.$$

If (X, \mathcal{P}) is a gauge space, then the gap functional in $P((X, \mathcal{P}))$ for every $\alpha \in A$ is defined as

$$D_\alpha : P((X, \mathcal{P})) \times P((X, \mathcal{P})) \rightarrow \mathbb{R}_+, \quad D_\alpha(B, C) = \inf\{p_\alpha(b, c) \mid b \in B, c \in C\}.$$

In particular, if $x_0 \in X$ then $D_\alpha(x_0, B) := D_\alpha(\{x_0\}, B)$.

We will denote by H_α the generalized Pompeiu-Hausdorff functional on $P((X, \mathcal{P}))$, defined as

$$H_\alpha : P((X, \mathcal{P})) \times P((X, \mathcal{P})) \rightarrow \mathbb{R}_+ \cup \{+\infty\},$$

$$H_\alpha(B, C) = \max\left\{\sup_{b \in B} D_\alpha(b, C), \sup_{c \in C} D_\alpha(c, B)\right\}.$$

Let (X, \mathcal{P}) be a gauge space. If $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ is a multivalued operator, then $x \in X$ is called fixed point for F if and only if $x \in F(x)$. The set

$$Fix(F) := \{x \in X \mid x \in F(x)\}$$

is called the fixed point set of F .

For a multivalued operator $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ we will denote by

$$Graph(F) := \{(x, y) \in X \times Y : y \in F(x)\}$$

the graphic of F .

Notice that $f : (X, \mathcal{P}) \rightarrow (X, \mathcal{P})$ is a selection for $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ if $f(x) \in F(x)$, for each $x \in X$.

For the following notions see I.A. Rus [21] and [20], I.A. Rus, A. Petruşel, A. Sintămărian [25] and A. Petruşel [19].

Definition 1.5. Let (X, \mathcal{P}) be a gauge space and $F : (X, \mathcal{P}) \rightarrow P_d((X, \mathcal{P}))$ be a multivalued operator. By definition, F is a multivalued weakly Picard (briefly MWP) operator if for each $x \in X$ and each $y \in F(x)$ there exists a sequence $(x_n)_{n \in \mathbb{N}}$ such that:

- (i) $x_0 = x, x_1 = y$;
- (ii) $x_{n+1} \in F(x_n)$, for each $n \in \mathbb{N}$;
- (iii) the sequence $(x_n)_{n \in \mathbb{N}}$ is convergent and its limit is a fixed point of F .

Remark 1.6. A sequence $(x_n)_{n \in \mathbb{N}}$ satisfying the condition (i) and (ii), in the Definition 1 is called a sequence of successive approximations of F starting from $(x, y) \in \text{Graph}(F)$.

If $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ is a MWP operator, then we define $F^\infty : \text{Graph}(F) \rightarrow P(\text{Fix}F)$ by the formula $F^\infty(x, y) := \{ z \in \text{Fix}(F) \mid \text{there exists a sequence of successive approximations of } F \text{ starting from } (x, y) \text{ that converges to } z \}$.

Definition 1.7. Let (X, \mathcal{P}) be a gauge space and $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ be a MWP operator. Then, F is called a c -multivalued weakly Picard operator (briefly c -MWP operator) if and only if there exists a selection f^∞ of F^∞ such that

$$p_\alpha(x, f^\infty(x, y)) \leq c \cdot p_\alpha(x, y), \text{ for all } (x, y) \in \text{Graph}(F), \alpha \in A.$$

For the theory of multivalued weakly Picard operators see [19] and [25].

The purpose of this paper is to present some results concerning the Ulam-Hyers stability of some operatorial inclusions (such as the fixed point inclusion) by using the weakly Picard operator technique.

2. ULAM-HYERS STABILITY FOR FIXED POINT INCLUSIONS

Definition 2.1. Let (X, \mathcal{P}) be a gauge space and $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ be a multivalued operator. The fixed point inclusion

$$x \in F(x), \quad x \in X \tag{2.1}$$

is called generalized Ulam-Hyers stable if and only if there exists $\psi := \{\psi_\alpha\}_{\alpha \in A}$ a family of mappings, where each $\psi_\alpha : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is increasing, continuous in 0 and $\psi_\alpha(0) = 0$ such that for each $\varepsilon_\alpha > 0$ and for each solution $y^* \in X$ of the inequation

$$D_\alpha(y, F(y)) \leq \varepsilon_\alpha \tag{2.2}$$

there exists a solution x^* of the fixed point inclusion (2.1) such that

$$p_\alpha(y^*, x^*) \leq \psi_\alpha(\varepsilon_\alpha), \text{ for all } \alpha \in A.$$

If there exists $c = \{c_\alpha\}_{\alpha \in A} \in (0, \infty)^A$ such that $\psi_\alpha(t) := c_\alpha t$, for each $t \in \mathbb{R}_+$ and $\alpha \in A$, then the fixed point inclusion (2.1) is said to be Ulam-Hyers stable.

Definition 2.2. (Espinola-Petruşel [9]) Let (X, \mathcal{P}) be a gauge space and $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ be a multivalued operator. Then F is an admissible c_α -MWP operator (briefly c_α -AMWP operator) if and only if $c_\alpha \in (0, \infty)$, for each $\alpha \in A$ and the following conditions are satisfied:

1) there exists a selection f^∞ of F^∞ such that

$$p_\alpha(x, f^\infty(x, y)) \leq c_\alpha p_\alpha(x, y), \text{ for all } (x, y) \in \text{Graph}(F) \text{ and for all } \alpha \in A.$$

2) for every $x \in X$ and every $q = \{q_\alpha\} \in (1, \infty)^A$, there exists $y \in F(x)$ such that

$$p_\alpha(x, y) \leq q_\alpha D_\alpha(x, F(x)), \text{ for all } \alpha \in A.$$

Theorem 2.3. Let (X, \mathcal{P}) be a gauge space and $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ be a c_α -AMWP operator. Then, the fixed point inclusion (2.1) is Ulam-Hyers stable.

Proof. Let $\varepsilon_\alpha > 0$ and $y^* \in F^\infty(x, y)$ be a solution of (2.2), i.e., $D_\alpha(y^*, F(y^*)) \leq \varepsilon_\alpha$, for all $\alpha \in A$. From condition 2) of Definition 2 we have that for every $q = \{q_\alpha\} \in (1, \infty)^A$ there exists $u^* \in F(y^*)$ such that $p_\alpha(y^*, u^*) \leq q_\alpha D_\alpha(y^*, F(y^*))$. Then from condition 1) from Definition 2 for $(u^*, y^*) \in \text{Graph}(F)$ we consider $x^* := f^\infty(y^*, u^*)$ which satisfies the following relations:

- (i) x^* is a solution of the fixed point inclusion (2.1).
- (ii) $p_\alpha(y^*, x^*) = p_\alpha(y^*, f^\infty(y^*, u^*)) \leq c_\alpha p_\alpha(y^*, u^*)$
 $\leq c_\alpha q_\alpha D_\alpha(y^*, F(y^*)) \leq c_\alpha q_\alpha \varepsilon_\alpha.$

Thus the fixed point inclusion is Ulam-Hyers stable.

O'Regan, Petruşel and Petru proved in [16] the existence of a fixed point for a Ćirić-type multivalued operator. We will show now that the fixed point inclusion (2.1) is Ulam-Hyers stable provided the multivalued operator F satisfies a Ćirić-type contraction condition. Our tool will be the abstract result given in Theorem 2.

Theorem 2.4. Let (X, \mathcal{P}) be a complete gauge space and $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ be a multivalued operator with closed graph. We suppose that:

- (i) there exists $\{a_\alpha\}_{\alpha \in A} \in (0, 1)^A$ such that, for every $\alpha \in A$, the following implication holds: for each $x, y \in X$ we have:

$$H_\alpha(F(x), F(y)) \leq a_\alpha \cdot M_\alpha^F(x, y),$$

where

$$M_\alpha^F(x, y) := \max\{p_\alpha(x, y), D_\alpha(x, F(x)), D_\alpha(y, F(y)), \frac{1}{2}[D_\alpha(x, F(y)) + D_\alpha(y, F(x))]\}.$$

- (ii) for every $x, y \in X$, every $u \in F(x)$ and every $q = \{q_\alpha\}_{\alpha \in A} \in (1, \infty)^A$ there exists $v \in F(y)$ such that $p_\alpha(u, v) \leq q_\alpha \cdot H_\alpha(F(x), F(y))$, for every $\alpha \in A$.

Then the fixed point inclusion (2.1) is Ulam-Hyers stable.

Proof. We have to show that F is a c_α -AMWP operator.

Let $x_0 \in X$ and $x_1 \in F(x_0)$ be arbitrary. For every $q = \{q_\alpha\}_{\alpha \in A} \in (1, \infty)^A$, by (ii), there exists $x_2 \in F(x_1)$ such that

$$p_\alpha(x_1, x_2) \leq q_\alpha H_\alpha(F(x_0), F(x_1)), \text{ for each } \alpha \in A.$$

Then:

$$\begin{aligned} p_\alpha(x_1, x_2) &\leq q_\alpha H_\alpha(F(x_0), F(x_1)) \\ &\leq q_\alpha a_\alpha M_\alpha^F(x_0, x_1) \\ &= q_\alpha a_\alpha \max\{p_\alpha(x_0, x_1), D_\alpha(x_0, F(x_0)), D_\alpha(x_1, F(x_1)), \frac{1}{2}D_\alpha(x_0, F(x_1))\}. \end{aligned}$$

We introduce the following notation:

$$\Gamma := \max\{p_\alpha(x_0, x_1), D_\alpha(x_0, F(x_0)), D_\alpha(x_1, F(x_1)), \frac{1}{2}D_\alpha(x_0, F(x_1))\}$$

and will choose $q = \{q_\alpha\}_{\alpha \in A} \in (1, \infty)^A$ such that $1 < q_\alpha < \frac{1}{a_\alpha}$, for each $\alpha \in A$.

If $\Gamma = p_\alpha(x_0, x_1)$ then $p_\alpha(x_1, x_2) \leq q_\alpha a_\alpha p_\alpha(x_0, x_1)$.

If $\Gamma = D_\alpha(x_0, F(x_0))$ then since $D_\alpha(x_0, F(x_0)) \leq p_\alpha(x_0, x_1)$ we have

$$p_\alpha(x_1, x_2) \leq q_\alpha a_\alpha p_\alpha(x_0, x_1).$$

If $\Gamma = D_\alpha(x_1, F(x_1))$ then $p_\alpha(x_1, x_2) \leq q_\alpha a_\alpha D_\alpha(x_1, F(x_1)) \leq q_\alpha a_\alpha p_\alpha(x_1, x_2)$, which is a contradiction since $1 < q_\alpha < \frac{1}{a_\alpha}$, for each $\alpha \in A$.

If $\Gamma = \frac{1}{2}D_\alpha(x_0, F(x_1))$ then

$$\begin{aligned} p_\alpha(x_1, x_2) &\leq q_\alpha a_\alpha \frac{1}{2}D_\alpha(x_0, F(x_1)) \leq \frac{q_\alpha a_\alpha}{2}p_\alpha(x_0, x_2) \leq \\ &\leq \frac{q_\alpha a_\alpha}{2}[p_\alpha(x_0, x_1) + p_\alpha(x_1, x_2)]. \end{aligned}$$

Hence, we obtain that

$$p_\alpha(x_1, x_2) \leq \frac{q_\alpha a_\alpha}{2 - q_\alpha a_\alpha} p_\alpha(x_0, x_1).$$

Then

$$\begin{aligned} \Gamma &= \frac{1}{2}D_\alpha(x_0, F(x_1)) \leq \frac{1}{2}p_\alpha(x_0, x_1) \leq \frac{1}{2}[p_\alpha(x_0, x_1) + p_\alpha(x_1, x_2)] \leq \\ &\leq \frac{1}{2}[1 + \frac{q_\alpha a_\alpha}{2 - q_\alpha a_\alpha}]p_\alpha(x_0, x_1) = \frac{1}{2 - q_\alpha a_\alpha}p_\alpha(x_0, x_1) < p_\alpha(x_0, x_1), \end{aligned}$$

which is a contradiction with the definition of Γ .

Thus in all cases we have that

$$p_\alpha(x_1, x_2) \leq q_\alpha a_\alpha p_\alpha(x_0, x_1).$$

By induction, we will obtain a sequence $(x_n)_{n \in \mathbb{N}}$ of successive approximations for F starting from x_0 , satisfying the following assertion:

$$p_\alpha(x_n, x_{n+1}) \leq (q_\alpha a_\alpha)^n p_\alpha(x_0, x_1), \text{ for every } n \in \mathbb{N}^* \text{ and } \alpha \in A.$$

For each $n, m \in \mathbb{N}^*$ and for every $\alpha \in A$ we have

$$\begin{aligned} p_\alpha(x_n, x_{n+m}) &\leq p_\alpha(x_n, x_{n+1}) + \dots + p_\alpha(x_{n+m-1}, x_{n+m}) \leq \\ &\leq [1 + \dots + (q_\alpha a_\alpha)^{m-1}] \cdot (q_\alpha a_\alpha)^n p_\alpha(x_0, x_1) = \\ &= \frac{1 - (q_\alpha a_\alpha)^m}{1 - q_\alpha a_\alpha} \cdot (q_\alpha a_\alpha)^n p_\alpha(x_0, x_1) \leq \frac{(q_\alpha a_\alpha)^n}{1 - q_\alpha a_\alpha} p_\alpha(x_0, x_1). \end{aligned}$$

Letting $n \rightarrow +\infty$ and taking into account the completeness of the gauge space, we obtain that the sequence $(x_n)_{n \in \mathbb{N}}$ is Cauchy. Thus, the sequence is convergent and it converges to a fixed point of F since the multivalued operator $F : (X, \mathcal{P}) \rightarrow P((X, \mathcal{P}))$ has closed graph.

Hence the multivalued operator F is a c_α -AMWP with $c_\alpha = \frac{1}{1 - q_\alpha a_\alpha}$. Applying Theorem 2 we obtain the Ulam-Hyers stability of the fixed point inclusion (2.1).

3. APPLICATION

We give at the beginning of this section the notion of Ulam-Hyers stability for an integral inclusion. Let us consider the following integral inclusion:

$$x(t) \in \int_{-t}^t K(t, s, x(s))ds + g(t) \text{ a.e. } t \in [0, \infty), \quad (3.1)$$

where $\int_{-t}^t K(t, s, x(s))ds$ denotes the multivalued integral in Aumann's sense, see [3].

A solution of the integral inclusion (3.1) is a continuous function which satisfies the inclusion.

Definition 3.1. The integral inclusion (3.1) is Ulam-Hyers stable if and only if there exists $c = \{c_\alpha\}_{\alpha \in A} \in (0, \infty)^A$ such that for each $\varepsilon = \{\varepsilon_\alpha\}_{\alpha \in A} \in (0, \infty)^A$ and for any ε -solution y^* of (3.1) (i.e., any $y^* \in C(\mathbb{R}, \mathbb{R}^m)$ which satisfies the inequality

$$|y^*(t) - \int_{-t}^t K(t, s, x(s))ds - g(t)| \leq \varepsilon_\alpha, \text{ for each } t \geq 0 \quad (3.2)$$

there exists a solution x^* of the inclusion (3.1) such that

$$|y^*(t) - x^*(t)| \leq c_\alpha \cdot \varepsilon_\alpha, \text{ for each } t \geq 0.$$

Then we have the following result.

Theorem 3.2. We suppose that

- (i) $K : [0, \infty) \times [0, \infty) \times \mathbb{R}^m \rightarrow P_{cp}(\mathbb{R}^m)$ is jointly measurable for all $x \in C[0, \infty)$;
- (ii) $g \in C(\mathbb{R}, \mathbb{R}^m)$;
- (iii) for almost every $(t, s) \in [0, \infty) \times [0, \infty)$ the multivalued operator $K(t, s, \cdot) : \mathbb{R}^m \rightarrow P(\mathbb{R}^m)$ is continuous;
- (iv) there exists $L_K > 0$ such that for every $u, v \in \mathbb{R}^m$

$$H(K(t, s, u), K(t, s, v)) \leq L_K \cdot \|u - v\|.$$

Then:

- a) The integral inclusion (3.1) has at least one solution in $C(\mathbb{R}, \mathbb{R}^m)$.
- b) The integral inclusion (3.1) is Ulam-Hyers stable.

Proof. a) We consider the sequentially complete gauge space $(C(\mathbb{R}, \mathbb{R}^m), (d_n)_{n \in \mathbb{N}})$ where

$$d_n(x, y) = \sup_{t \in [-n, n]} \left\{ \|x(t) - y(t)\| \cdot e^{-\tau \|t\|} \right\}, \quad \tau > 0, \quad n \in \mathbb{N}^*,$$

and the multivalued operator

$$F(x)(t) = \int_{-t}^t K(t, s, x(s))ds + g(t).$$

Let $x_1, x_2 \in C([-n, n], \mathbb{R}^m)$ and $u_1 \in F(x_1)$. Then $u_1 \in \mathbb{R}^m$ and

$$u_1(t) \in \int_{-t}^t K(t, s, x(s)) ds + g(t).$$

Thus there exists $k_1(t, s) \in K(t, s, x(s))$ such that $u_1(t) = \int_{-t}^t k_1(t, s) ds + g(t)$. Since

$$H(K(t, s, x_1(s)), K(t, s, x_2(s))) \leq L_K \cdot \|x_1(s) - x_2(s)\|$$

follows that there exists $v \in K(t, s, x_2(s))$ such that

$$\|k_1(t, s) - v\| \leq L_K \cdot \|x_1(s) - x_2(s)\|.$$

Thus the multivalued operator G defined by

$$G(t) = K(t, s, x_2(s)) \cap \{v : \|k_1(t, s) - v\| \leq L_K \cdot \|x_1(s) - x_2(s)\|\}$$

has nonempty values and is measurable. By Kuratowski and Ryll Nardzewski's selection theorem there exists $k_2(t, s)$ a measurable selection for G . Then $k_2(t, s) \in K(t, s, x_2(s))$ and

$$\|k_1(t, s) - k_2(t, s)\| \leq L_K \cdot \|x_1(s) - x_2(s)\|.$$

Let $u_2(t) = \int_{-t}^t k_2(t, s) ds + g(t) \in F(x_2)$. Then for $t \in [-n, n]$, $n \in \mathbb{N}^*$ we have

$$\begin{aligned} \|u_1(t) - u_2(t)\| &\leq \int_{-\|t\|}^{\|t\|} \|k_1(t, s) - k_2(t, s)\| ds \\ &\leq \int_{-\|t\|}^{\|t\|} L_K \cdot \|x_1(s) - x_2(s)\| ds \\ &= \int_{-\|t\|}^{\|t\|} L_K \cdot \|x_1(s) - x_2(s)\| \cdot e^{-\tau\|s\|} \cdot e^{\tau\|s\|} ds \\ &\leq L_K \cdot d_n(x_1, x_2) \cdot \int_{-\|t\|}^{\|t\|} e^{\tau\|s\|} ds = L_K \cdot d_n(x_1, x_2) \cdot \frac{e^{\tau\|t\|}}{\tau}. \end{aligned}$$

Thus $d_n(u_1, u_2) \leq \frac{L_K}{\tau} \cdot d_n(x_1, x_2)$. Choosing $\tau > L_K$ we have that $L_F := \frac{L_K}{\tau} < 1$. By the analogous relation obtained by interchanging the roles of x_1 and x_2 it follows that

$$H_n(F(x_1), F(x_2)) \leq L_F \cdot d_n(x_1, x_2).$$

In what follows we want to prove that the multivalued operator F is an admissible contraction. We have already obtained the first condition, so it remains to show that for every $x \in C([-n, n], \mathbb{R}^m)$ and every $\varepsilon \in (0, \infty)^{\mathbb{N}^*}$, there exists $y \in F(x)$ such that $d_n(x, y) \leq D_n(x, F(x)) + \varepsilon_n$, for every $n \in \mathbb{N}^*$.

Supposing the contrary, we have that there exists $\varepsilon \in (0, \infty)^{\mathbb{N}^*}$ and exists $x \in C([-n, n], \mathbb{R}^m)$ such that for all $y \in F(x)$ we have $d_n(x, y) > D_n(x, F(x)) + \varepsilon_n$. It follows that $D_n(x, F(x)) \geq D_n(x, F(x)) + \varepsilon_n$ and so $\varepsilon_n \leq 0$, for every $n \in \mathbb{N}^*$, which is a contradiction.

Thus the multivalued operator F is an admissible contraction. This implies that F is also a c_n -AMWP operator with $c_n = (1 - L_F)^{-1}$, hence we have the existence of the solution.

b) Applying Theorem 2 the second conclusion follows too.

Remark 3.3. For other Ulam-Hyers stability theorems see [6] (for a classical approach) and [5], [18], [20], [22], [23] (by Picard and weakly Picard operator technique).

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