

FIXED POINTS OF GENERALIZED ASYMPTOTIC CONTRACTIONS

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Abstract. Following Suzuki's asymptotic contraction of Meir-Keeler type (ACMK), we obtain a coincidence theorem for a generalized ACMK for a pair of maps and derive some general fixed point theorems on metric spaces.

Key Words and Phrases: Coincidence point, fixed point, asymptotic contraction, asymptotic contraction of Meir-Keeler type, generalized asymptotic contraction of Meir-Keeler type.

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1. INTRODUCTION

In 2003, Kirk [17] introduced the notion of *asymptotic contractions* on a metric space, and proved a fixed point theorem for this new class of maps.

Definition 1.1. ([17]). Let (X, d) be a metric space. A self-map T of X is an *asymptotic contraction* on X if there exists a continuous function φ from $[0, \infty)$ into itself and a sequence $\{\varphi_n\}$ of functions from $[0, \infty)$ into itself such that

- (K1): $\varphi(0) = 0$;
- (K2): $\varphi(r) < r$ for $r \in (0, \infty)$;
- (K3): $\{\varphi_n\}$ converges to φ uniformly on the range of d ; and
- (K4): for $x, y \in X$ and $n \in \mathbb{N}$, $d(T^n x, T^n y) \leq \varphi_n(d(x, y))$.

Theorem 1.1. ([17]). Let (X, d) be a complete metric space and T a continuous asymptotic contraction on X with $\{\varphi_n\}$ and φ as in Definition 1.1. Assume that there exists $x \in X$ such that the orbit $\{T^n x : n \in \mathbb{N}\}$ of x is bounded, and that φ_n is continuous for $n \in \mathbb{N}$. Then there exists a unique fixed point $z \in X$. Moreover $\lim_n T^n x = z$ for all $x \in X$.

Theorem 1.1 is an asymptotic version of Boyd and Wong [4] (see also [13], [17]). It has important outcomes in metric fixed point theory (see, for instance, [1], [2], [3], [5], [6], [7], [8], [9], [11], [12], [13], [15], [17], [19], [24], [27], [31], [32], [33], [34], [35], [36].)

Underlying the power and importance of this new class of maps, Briseid [5, 7] has observed that a continuous self-map of a compact metric space satisfying any one of the first 50 contractive conditions listed by Rhoades [25] is an asymptotic contraction. Włodarczyk *et al.* [34] and [35] discussed some ideas for applications of the theory of asymptotic contractions in the analysis of set-valued dynamical systems.

The purpose of this paper is to present a brief review of numerous definitions and fixed point theorems which followed Kirk's asymptotic contractions. Further, we obtain coincidence and fixed point theorems for generalized asymptotic contractions of Meir-Keeler type on metric spaces.

2. REVIEW OF ASYMPTOTIC CONTRACTIONS

Jachymski and Jòżwic [13] showed that the continuity of the map T is essential in Theorem 1.1. Further, they extended Theorem 1.1 and obtained a complete characterization of asymptotic contractions on a compact metric space.

Proof of Theorem 1.1 in [17] involves a sophisticated ultrapower technique. Arandelović's attempt [1] (see also [2]) to provide a simple constructive proof of Theorem 1.1 was perfected by Jachymski [15].

Improving upon Theorem 1.1, Chen [9] obtained the following result under weaker assumptions. In this paper, R^+ denotes the set of all nonnegative real numbers.

Theorem 2.1. *Let (X, d) be a complete metric space and $T : X \rightarrow X$ a self-map satisfying the conditions (C1)-(C3):*

(C1): $d(T^n x, T^n y) \leq \varphi_n(d(x, y))$
for all $x, y \in X$, where $\varphi_n : R^+ \rightarrow R^+$ and $\lim_{n \rightarrow \infty} \varphi_n = \varphi$ uniformly on any bounded interval $[0, b]$. Suppose that φ is upper semicontinuous and $\varphi(t) < t$ for $t > 0$.

(C2): *There exists a positive integer n^* such that φ_{n^*} is upper semicontinuous and $\varphi_{n^*}(0) = 0$.*

(C3): *There exists $x_0 \in X$ such that the orbit $O(x_0)$ is bounded.*

Then T has a unique fixed point $x^ \in X$ such that $\lim_{n \rightarrow \infty} T^n x = x^*$ for all $x \in X$.*

Arandelović [2] presented a fixed point theorem of Kirk type unifying and generalizing fixed point theorems of Kirk [17], Jachymski and Jòżwic [13] and Chen [9].

As Theorem 2.1 does not guarantee the uniform convergence of the iterates of the map T (see also [3]), Reich and Zaslavski [24] obtained a convergence theorem [3, Theorem 1.3] for asymptotic contractions with some additional hypotheses. Further, modifying the condition (C2) a slightly, Sastry *et al.* [27] obtained effectively another version of Theorem 2.1.

Gerhardy [11] obtained a quantitative version of Theorem 1.1 by using the techniques of proof-mining (for proof-mining technique, one may refer to Kohlenbach and

Oliva [20]). Indeed, he introduced the following alternative definition of asymptotic contraction and obtained a fixed point theorem for the same.

Definition 2.1. ([11]). Let (X, d) be a metric space and T a self-map on X . The map T is called a *G-asymptotic contraction* on X if for each $b > 0$ there exists moduli $\eta^b : (0, b) \rightarrow (0, 1)$ and $\beta^b : (0, b] \times (0, \infty) \rightarrow \mathbb{N}$ and the following hold:

(G1): there exists a sequence of functions $\phi_n^b : (0, \infty) \rightarrow (0, \infty)$ such that for all $x, y \in X$, for all $\varepsilon > 0$ and for all $n \in \mathbb{N}$,

$$b > d(x, y) \geq \varepsilon \Rightarrow d(T^n x, T^n y) \leq \phi_n^b(\varepsilon).d(x, y);$$

(G2): for each $0 < l \leq b$ the function $\beta_l^b := \beta^b(l, \cdot)$ is a modulus of uniform convergence for each ϕ_n^b on $[l, b]$, i.e.,

$$\forall \varepsilon > 0 \forall s \in [l, b] \forall m, n \geq \beta_l^b(\varepsilon), \quad (|\phi_m^b(s) - \phi_n^b(s)| \leq \varepsilon); \text{ and}$$

(G3): defining $\phi^b := \lim_{n \rightarrow \infty} \phi_n^b$, then for each $0 < \varepsilon \leq b$, we have $\phi^b(s) + \eta^b(\varepsilon) \leq 1$ for each $s \in [\varepsilon, b]$.

Theorem 2.2. [11]. *Let (X, d) be a complete metric space and $T : X \rightarrow X$ a continuous G-asymptotic contraction, where $b > 0$ and η, β are given. If for some $x_0 \in X$, the sequence $\{x_n\}$ is bounded by b then T has a unique fixed point z and $\{x_n\}$ converges to z .*

Since the convergence to the fixed point of a continuous G-asymptotic contraction need not be monotone (see also [5, p. 367], [6, p. 18], [13]), Theorem 2.2 does not provide a full rate of convergence. Briseid [5] gives an explicit rate of convergence for the iteration sequence for modified G-asymptotic contractions, expressed in the relevant moduli and a bound on the sequence. Further, a characterization of Kirk's asymptotic contractions (cf. Definition 1.1), G-asymptotic contractions (cf. Definition 2.1) and modified G-asymptotic contractions [5, Definition 2.2] on bounded complete metric spaces has been discussed in [5] (see also [6], [7] and [8]).

Recently Kirk [18] introduced the following notion of an asymptotic pointwise contraction.

Definition 2.2. Let K be a weakly compact convex subset of a Banach space X . A map $T : K \rightarrow K$ is an asymptotic pointwise contraction if there exists a function $\alpha : K \rightarrow [0, 1)$ such that, for each integer $n \geq 1$,

$$\|T^n x - T^n y\| \leq \alpha_n(x)\|x - y\| \text{ for each } x, y \in K,$$

where $\alpha_n \rightarrow \alpha$ pointwise on K .

Kirk [18] also obtained a fixed point theorem for asymptotic pointwise contractions defined on a bounded closed convex subset of a super reflexive Banach space. The proof outlined there involves a sophisticated ultrapower technique, and also requires some additional assumptions.

Kirk and Xu [19] give a simple and elementary proof (in the sense that ultrapower methods are not needed) of the fact that an asymptotic pointwise contraction defined on a weakly compact convex set has a unique fixed point (with convergence of iterates). In conjunction with the concept of asymptotic pointwise contractions, Kirk and Xu

[19] introduced the the notion of pointwise asymptotically nonexpansive maps and pointwise eventually nonexpansive maps.

Definition 2.3. (cf. [19]). A map $T : K \rightarrow K$ is pointwise eventually nonexpansive if for each $x \in K$, there exists $n(x) \in \mathbb{N}$ such that $n \geq n(x)$,

$$\|T^n x - T^n y\| \leq \|x - y\|, \quad x, y \in K.$$

Kirk and Xu [19] posed two questions regarding the existence of fixed points of eventually nonexpansive maps in reflexive Banach spaces having the fixed point property for nonexpansive maps.

Hussain and Khamsi [12] extend Definition 2.2 to a metric space as follows.

Definition 2.4. Let (X, d) be a metric space. A self-map $T : X \rightarrow X$ is an asymptotic pointwise map if there exists a map $\alpha_n : X \rightarrow [0, \infty)$ such that

$$d(T^n x, T^n y) \leq \alpha_n(x)d(x, y) \text{ for any } y \in X.$$

(i) If $\{\alpha_n\}$ converges pointwise to $\alpha : M \rightarrow [0, 1)$, then T is called asymptotic pointwise contraction.

(ii) If $\limsup_{n \rightarrow \infty} \alpha_n(x) \leq 1$, then T is called asymptotic pointwise nonexpansive.

(iii) If $\limsup_{n \rightarrow \infty} \alpha_n(x) \leq k$, with $0 < k < 1$, then T is called strongly asymptotic pointwise nonexpansive.

They [12] also extend the main results of Kirk [18] to metric spaces and discuss the case of multivalued maps as well.

Generalizing Banach contraction principle, Meir-Keeler [22] obtained the following theorem.

Theorem 2.3. Let (X, d) be a complete metric space and T a self-map of X . Assume that for every $\varepsilon > 0$, there exists $\delta > 0$ such that

$$\text{(MK)} \quad \varepsilon \leq d(x, y) < \varepsilon + \delta \Rightarrow d(Tx, Ty) < \varepsilon$$

for all $x, y \in X$. Then T has a unique fixed point.

Cho *et al.* [10], Jachymski [13], Lim [21], Park and Rhoades [23], Rus [26], Singh and Kumar [28], Suzuki [31, 32, 33] and many others obtained various generalizations of Theorem 2.3. For a good bibliography on the development of the condition (MK), one may refer to [26] and [28].

In [31], Suzuki combined the two ideas of Meir-Keeler contraction (MKC) and Kirk asymptotic contraction (KAC) and introduced the following notion of *asymptotic contraction of Meir-Keeler type* (see also [32], [33]).

Definition 2.5. Let (X, d) be a metric space. A self-map T of X is an *asymptotic contraction of Meir-Keeler type* (ACMK for short) if there exists a sequence φ_n of functions from $[0, \infty)$ into itself satisfying the following conditions:

$$\text{(S1): } \limsup \varphi_n(\varepsilon) \leq \varepsilon \text{ for all } \varepsilon \geq 0;$$

$$\text{(S2): } \text{for each } \varepsilon > 0, \text{ there exists } \delta > 0 \text{ and } \nu \in \mathbb{N} \text{ such that } \varphi_\nu(t) \leq \varepsilon \text{ for all } t \in [\varepsilon, \varepsilon + \delta];$$

$$\text{(S3): } d(T^n x, T^n y) < \varphi_n(d(x, y)) \text{ for all } n \in \mathbb{N} \text{ and } x, y \in X \text{ with } x \neq y.$$

Inspired by Jachymski and Jòżwic [13, Lemma 4], Suzuki [31] obtained the following result.

Theorem 2.4. *Let (X, d) be a complete metric space and T an ACMK on X . Assume that T^l is continuous for some $l \in \mathbb{N}$. Then there exists a unique fixed point $z \in X$. Moreover, $\lim_n T^n x = z$ for all $x \in X$.*

Recently Singh and Pant [30] obtained the following generalization and extension of Theorems 1.1 and 2.4. In all that follows Y denotes an arbitrary nonempty set.

Theorem 2.5. *Let (X, d) be a complete metric space and T a self-map satisfying the conditions (S1), (S2) and the following:*

(S4): $d(T^n x, T^n y) < \varphi_n(m(x, y))$ for all $n \in \mathbb{N}$ and $x, y \in X$ with $x \neq y$,
where $m(x, y) = \max\{d(x, y), d(x, Tx), d(y, Ty)\}$.

If T^k is continuous for some $k \in \mathbb{N}$ then T has a unique fixed point $z \in X$.

Moreover, $\lim_n T^n x = z$ for all $x \in X$.

Theorem 2.6. *Let (X, d) be a metric space and $T, f : Y \rightarrow X$ satisfying the conditions (S1) and the following:*

(S5): $T(Y) \subseteq f(Y)$;

(S6): for each $\varepsilon > 0$ there exists $\delta > 0$ and $\mu \in \mathbb{N}$ such that

$\varphi_\mu(t) < \varepsilon$ for all $t \in [\varepsilon, \varepsilon + \delta]$;

(S7): $d(T^n x, T^n y) < \varphi_n(d(fx, fy))$ for all $n \in \mathbb{N}$ and $x, y \in X$ with $x \neq y$.

If $T(Y)$ or $f(Y)$ is a complete subspace of X then T and f have a coincidence.

Further, if $Y = X$, then T and f have a unique common fixed point provided that T and f commute just at a coincidence point.

3. GENERALIZED ASYMPTOTIC CONTRACTIONS OF MEIR-KEELER TYPE

First we present an extension of Suzuki's definition of ACMK (cf. Definition 2.2) for a pair of maps on an arbitrary nonempty set with values in a metric space.

Definition 3.1. Let (X, d) be a metric space and $T, f : Y \rightarrow X$. The map T will be called a *generalized asymptotic contraction of Meir-Keeler type* (in short, GACMK) with respect to f if the following hold:

(P1) $\limsup_n \varphi_n(\varepsilon) \leq \varepsilon$ for all $\varepsilon \geq 0$;

(P2) for each $\varepsilon > 0$ there exists $\delta > 0$ and $\mu \in \mathbb{N}$ such that $\varphi_\mu(t) < \varepsilon$ for all $t \in [\varepsilon, \varepsilon + \delta]$;

(P3) $d(T^n x, T^n y) < \varphi_n(M(x, y))$ for all $n \in \mathbb{N}$ and $x, y \in X$ with $M(x, y) > 0$, where $M(x, y) = \max\{d(fx, fy), d(fx, Tx), d(fy, Ty), \frac{1}{2}[d(fx, Ty) + d(fy, Tx)]\}$.

The following result for GACMK extends Theorems 2.4-2.6.

Theorem 3.1. *Let (X, d) be a metric space and $T, f : Y \rightarrow X$ such that $TY \subseteq fY$. Let T be a GACMK with respect to f . If $T(Y)$ or $f(Y)$ is a complete subspace of X then T and f have a coincidence point.*

Further, if $Y = X$, then T and f have a unique common fixed point provided that T and f commute at a coincidence point.

Proof. Pick $x_0 \in Y$. Define a sequence $\{y_n\}$ by $y_n = Tx_n = fx_{n+1}$, $n = 0, 1, 2, \dots$. We can do so since the range of f contains the range of T . First we show that

$$\lim_{n \rightarrow \infty} d(Tx_n, Tx_{n+1}) = \lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = 0. \quad (3.1)$$

It initially holds if $x_0 = x_1$. In the other case of $x_0 \neq x_1$, we assume that $\alpha := \limsup_n d(Tx_n, Tx_{n+1}) > 0$. From the condition (P2), we can choose $\mu_1 \in \mathbb{N}$ satisfying $\varphi_{\mu_1}(d(Tx_0, Tx_1)) \leq d(Tx_0, Tx_1)$. By (P3) and (P1),

$$d(y_{\mu_1+1}, y_{\mu_1+2}) = d(Tx_{\mu_1+1}, Tx_{\mu_1+2}) < \varphi_{\mu_1}(M(x_1, x_2)) \leq M(x_1, x_2).$$

Then proceeding as in [30],

$$\begin{aligned} \alpha : &= \limsup_{n \rightarrow \infty} d(Tx_{\mu_1+n}, Tx_{\mu_1+n+1}) & (3.2) \\ &\leq \limsup_{n \rightarrow \infty} \varphi_n(M(Tx_{\mu_1}, Tx_{\mu_1+1})) \leq M(Tx_{\mu_1}, Tx_{\mu_1+1}) \\ &= \max\{d(fx_{\mu_1+1}, fx_{\mu_1+2}), d(fx_{\mu_1+1}, Tx_{\mu_1+1}), d(fx_{\mu_1+2}, Tx_{\mu_1+2}), \\ &\quad \frac{1}{2}[d(fx_{\mu_1+1}, Tx_{\mu_1+2}) + d(fx_{\mu_1+2}, Tx_{\mu_1+1})]\} \\ &= \max\{d(Tx_{\mu_1}, Tx_{\mu_1+1}), d(Tx_{\mu_1}, Tx_{\mu_1+1}), d(Tx_{\mu_1+1}, Tx_{\mu_1+2}), \\ &\quad \frac{1}{2}[d(Tx_{\mu_1}, Tx_{\mu_1+2}) + 0]\} \\ &= \max\{d(Tx_{\mu_1}, Tx_{\mu_1+1}), d(Tx_{\mu_1+1}, Tx_{\mu_1+2}), \\ &\quad \frac{1}{2}[d(Tx_{\mu_1}, Tx_{\mu_1+1}) + d(Tx_{\mu_1+1}, Tx_{\mu_1+2})]\} \\ &= \max\{d(Tx_{\mu_1}, Tx_{\mu_1+1}), d(Tx_{\mu_1+1}, Tx_{\mu_1+2})\}. \end{aligned}$$

If

$$\max\{d(Tx_{\mu_1}, Tx_{\mu_1+1}), d(Tx_{\mu_1+1}, Tx_{\mu_1+2})\} = d(Tx_{\mu_1+1}, Tx_{\mu_1+2}),$$

we have a contradiction. Therefore

$$\max\{d(Tx_{\mu_1}, Tx_{\mu_1+1}), d(Tx_{\mu_1+1}, Tx_{\mu_1+2})\} = d(Tx_{\mu_1}, Tx_{\mu_1+1})$$

and we conclude that $M(Tx_{\mu_1}, Tx_{\mu_1+1}) = d(Tx_{\mu_1}, Tx_{\mu_1+1})$.

By (3.2),

$$\begin{aligned} d(Tx_{\mu_1+1}, Tx_{\mu_1+2}) &< \varphi_{\mu_1}(M(x_1, x_2)) \leq M(x_1, x_2) \\ &= \max\{d(fx_1, fx_2), d(fx_1, Tx_1), d(fx_2, Tx_2), \\ &\quad \frac{1}{2}[d(fx_1, Tx_2) + d(fx_2, Tx_1)]\} \\ &= \max\{d(Tx_0, Tx_1), d(Tx_0, Tx_1), d(Tx_1, Tx_2), \\ &\quad \frac{1}{2}[d(Tx_0, Tx_2) + 0]\} \\ &= \max\{d(Tx_0, Tx_1), d(Tx_1, Tx_2), \frac{1}{2}[d(Tx_0, Tx_1) + d(Tx_1, Tx_2)]\} \\ &= d(Tx_0, Tx_1). \end{aligned}$$

So $\alpha < d(Tx_0, Tx_1)$. By a similar argument, we obtain $\alpha < d(Tx_k, Tx_{k+1})$ for all $k \in \mathbb{N} \cup \{0\}$. Hence $\{d(Tx_n, Tx_{n+1})\}$ converges to α .

Since $0 < \alpha < d(Tx_0, Tx_1) < \infty$, there exists $\delta_2 > 0$ and $\mu_2 \in \mathbb{N}$ such that

$$\varphi_{\mu_2}(t) \leq \alpha \text{ for all } t \in [\alpha, \alpha + \delta_2].$$

We choose $\mu_3 \in \mathbb{N}$ with $d(Tx_{\mu_3}, Tx_{\mu_3+1}) < \alpha + \delta_2$. Then we have

$$d(Tx_{\mu_2+\mu_3}, Tx_{\mu_2+\mu_3+1}) < \varphi_{\mu_2}d(Tx_{\mu_3}, Tx_{\mu_3+1}) \leq \alpha,$$

a contradiction. This proves that $\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = 0$.

Now we show that $\{y_n\}$ is Cauchy sequence. Suppose $\{y_n\}$ is not Cauchy. Then there exists $\beta > 0$ and increasing sequences $\{m_k\}$ and $\{n_k\}$ of positive integers, such that for all $n \leq m_k < n_k$,

$$d(y_{m_k}, y_{n_k}) \geq \beta \text{ and } d(y_{m_k}, y_{n_k-1}) < \beta.$$

By the triangle inequality,

$$d(y_{m_k}, y_{n_k}) \leq d(y_{m_k}, y_{n_k-1}) + d(y_{n_k-1}, y_{n_k}).$$

Making $k \rightarrow \infty$, $d(y_{m_k}, y_{n_k}) < \beta$. Thus $d(y_{m_k}, y_{n_k}) \rightarrow \beta$ as $k \rightarrow \infty$. By (P2),

$$\begin{aligned} d(y_{m_k+n}, y_{n_k+n}) &= d(Tx_{m_k+n}, Tx_{n_k+n}) \\ &< \varphi_n(M(x_{m_k}, x_{n_k})) \\ &= \varphi_n(\max\{d(fx_{m_k}, fx_{n_k}), d(fx_{m_k}, Tx_{m_k}), d(fx_{n_k}, Tx_{n_k}), \\ &\quad \frac{1}{2}[d(fx_{m_k}, Tx_{n_k}) + d(fx_{n_k}, Tx_{m_k})]\}) \\ &= \varphi_n(\max\{d(y_{m_k-1}, y_{n_k-1}), d(y_{m_k-1}, y_{m_k}), d(y_{n_k-1}, y_{n_k}), \\ &\quad \frac{1}{2}[d(y_{m_k-1}, y_{n_k}) + d(y_{n_k-1}, y_{m_k})]\}). \end{aligned}$$

Making $k \rightarrow \infty$, $\beta \leq \varphi_n(\beta) < \beta$, a contradiction, and the sequence $\{y_n\}$ is Cauchy.

Suppose $f(Y)$ is complete. Then $\{y_n\}$ being contained in $f(Y)$ has a limit in $f(Y)$. Call it z . Let $u \in f^{-1}z$. Then $fu = z$. Using (P3),

$$\begin{aligned} d(Tu, Tx_n) &\leq \varphi(M(u, x_n)) \\ &= \varphi(\max\{d(fu, fx_n), d(fu, Tu), d(fx_n, Tx_n), \\ &\quad \frac{1}{2}[d(fu, Tx_n) + d(fx_n, Tu)]\}). \end{aligned}$$

Making $n \rightarrow \infty$, $d(Tu, z) \leq \varphi(d(Tu, z)) < d(Tu, z)$. Therefore $Tu = z = fu$. Now if $Y = X$ and the pair (T, f) commutes just at u then $Tfu = fTu$ and $TTu = Tfu = fTu = ffu$. In view of (A2), it follows that

$$\begin{aligned} d(Tu, TTu) &\leq \varphi(M(u, Tu)) \\ &= \varphi(\max\{d(fu, fTu), d(fu, Tu), d(fTu, TTu), \\ &\quad \frac{1}{2}[d(fu, TTu) + d(fTu, Tu)]\}) \\ &< d(Tu, TTu), \end{aligned}$$

a contradiction. Therefore $TTu = Tu$ and $fTu = TTu = Tu = z$.

In case $T(Y)$ is a complete subspace of X , the condition $TY \subseteq fY$ implies that the sequence $\{y_n\}$ converges in $f(Y)$, and the previous argument works. The uniqueness of the common fixed point follows easily. \square

The following result is evident as the condition (S7) implies (P3).

Corollary 3.1. *Theorem 2.6.*

Corollary 3.2. *Let (X, d) be a complete metric space and $T : X \rightarrow X$ a map satisfying (S1), (S6) and the following:*

(P4) $d(T^n x, T^n y) < \varphi_n(M_1(x, y))$

for all $n \in \mathbb{N}$ and $x, y \in X$ with $M_1(x, y) > 0$,

where, $M_1(x, y) = \max\{d(x, y), d(x, Tx), d(y, Ty), \frac{1}{2}[d(x, Ty) + d(y, Tx)]\}$.

If T^k is continuous for some $k \in \mathbb{N}$, then T has a unique fixed point $z \in X$.

Proof. It comes from Theorem 3.1 when $Y = X$ and f is the identity map. \square

The following example illustrate the usefulness of Theorem 3.1.

Example 3.1. Let $X = [0, 1]$ be endowed with the usual metric d . Let $T : X \rightarrow X$ be such that

$$Tx = \begin{cases} 1 & \text{if } x = 0, \\ \frac{x}{2} & \text{if } x \in (0, 1]. \end{cases}$$

Jachymski [13] has shown that T satisfies all the conditions of Theorem 1.1 except the continuity with an appropriate choice of φ_n . Since the map T is without fixed point, it does not satisfy the hypotheses of Theorem 2.4 as well. We consider a map $f : X \rightarrow X$ such that

$$fx = x^2.$$

Assume that

$$\varphi_n(t) = \frac{t}{2^{n-1}}, \quad t > 0.$$

Notice that $TX \subset fX$ and fX is obviously complete. Further, this is not difficult to see that the pair of maps T and f satisfy the condition (P3) for all $x, y \in X$.

Evidently $T(\frac{1}{2}) = f(\frac{1}{2}) = \frac{1}{4}$, and T and f are not commuting at the coincidence point $\frac{1}{2}$.

The following example shows the superiority of Theorem 3.1 over Theorems 2.4-2.6.

Example 3.2. Let $X = \{1, 2, 3, 4\}$ be endowed with the usual metric d . Let $f, T : X \rightarrow X$ be such that $T1 = T3 = T4 = 1$, $T2 = 2$ and $\varphi_n(t) = \frac{9t}{10}$ for all $t > 0$ (or any other choice of φ_n with $\varphi_n(t) < t$). Then it can be easily seen that Theorems 2.4 -2.6 are not applicable to this map T . Indeed, as $d(T^n x, T^n y) = 1$ for $x = 1$ and $y = 2$, none of the conditions (S3), (S4) and (S7) is satisfied. However, if we take $f1 = 1$, $f2 = f3 = 4$, $f4 = 2$ then Theorem 3.1 is applicable to these maps. Notice that $TX \subset fX$ and $f1 = T1 = 1$.

The following result generalizes Theorems 2.4 and 2.5.

Theorem 3.2. *Let (X, d) be a complete metric space and $T : X \rightarrow X$ a self-map satisfying (S1), (S2) and (P4). If T^k is continuous for some $k \in \mathbb{N}$ then T has a unique fixed point $z \in X$.*

Proof. It may be completed following the proof of [30, Theorem 2.1]. \square

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