

FIXED POINTS AND SELECTIONS FOR MULTI-VALUED OPERATORS

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Abstract. The purpose of this paper is to report several results in the fixed point theory and selections theory for multi-valued operators.

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1 Introduction

Fixed point theory is one of the most powerful tool for the study of a lot of problems arising in pure and applied mathematics. The main purpose of this paper is to report several fixed point results and selection theorems for multi-valued operators. The structure of this paper is the following: first of all, in the second section, we consider some notations, notions and preliminary results that we need throughout the paper. Then in the third paragraph, we present some Krasnoselskii-type fixed points theorems for multi-valued operators. In section 4, we concentrate on some properties of the fixed points set of a multi-valued operator. Finally, in the last paragraph we consider some selection theorems for multi-valued operators with decomposable values. For more details and further results, we refer to [49], [51] and [64].

2 Preliminaries

Let (X, d) be a metric space, $x_0 \in X$ and $r > 0$. We denote:

$B(x_0; r) = \{x \in X : d(x_0, x) < r\}$, $\tilde{B}(x_0; r) = \{x \in X : d(x_0, x) \leq r\}$,
 $\mathcal{P}(X) = \{A : A \text{ is a subset of } X\}$, $P(X) = \{A \in \mathcal{P}(X) : A \text{ is nonempty}\}$,
 $P_p(X) = \{A \in P(X) : A \text{ has the property "p"}\}$, where "p" could be: cl = closed,
 b = bounded, cp = compact, cv = convex (for normed spaces X), etc.

If $A, B \in P(X)$, we define the functional:

$$D : P(X) \times P(X) \rightarrow \mathbb{R}_+, D(A, B) = \inf\{d(a, b) \mid a \in A, b \in B\}$$

and the following generalized functionals:

$$\delta : P(X) \times P(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\}, \delta(A, B) = \sup\{d(a, b) \mid a \in A, b \in B\}$$

$$\rho : P(X) \times P(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\}, \rho(A, B) = \sup\{D(a, B) \mid a \in A\}$$

$$H : P(X) \times P(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\}, H(A, B) = \max\{\rho(A, B), \rho(B, A)\}.$$

Throughout the paper, the symbol \mathcal{M} indicates the family of all metric spaces. Let $X \in \mathcal{M}$. The space X is called an absolute retract for metric spaces (briefly $X \in AR(\mathcal{M})$) if, for any $Y \in \mathcal{M}$ and any $Y_0 \in P_{cl}(X)$, every continuous function $f_0 : Y_0 \rightarrow X$ has a continuous extension over Y , that is $f : Y \rightarrow X$. Obviously, any absolute retract is arcwise connected. Let $X, Y \in \mathcal{M}$ and $T : X \rightarrow P(Y)$ be a multifunction. We will denote by the symbol $G(T) = \{(x, y) \in X \times Y \mid y \in T(x)\}$ the graph of T . If $T : X \rightarrow P(X)$ is a multi-valued operator then we denote by $FixT$ the fixed points set of T , i.e. $FixT = \{x \in X \mid x \in T(x)\}$. A multi-function $T : X \rightarrow P_{cl}(Y)$ is, by definition, lower semi-continuous (briefly, l.s.c.) if, for any open set A of Y , the set $T^{-1}(A) := \{x \in X : T(x) \cap A \neq \emptyset\}$ is open in X . When for any open set A of Y , the set $\{x \in X : T(x) \subset A\}$ is open in X , we say that T is upper semi-continuous (briefly u.s.c.). A continuous multi-function $T : X \rightarrow P_{cl}(Y)$ is, by definition, both l.s.c. and u.s.c. Also, T is said to be closed if and only if the set $G(T)$ is closed in $X \times Y$.

Definition 2.1. (see Rus-Petruşel-Sîntămărian [73]) Let (X, d) be a metric space and $T : X \rightarrow P(X)$ a multi-valued operator. By definition, T is a multi-valued weakly Picard operator (briefly m.w.P.o.) if and only if for all $x \in X$ and all $y \in T(x)$ there exists a sequence $(x_n)_{n \in \mathbb{N}}$ such that:

- i) $x_0 = x, x_1 = y$
- ii) $x_{n+1} \in T(x_n)$, for all $n \in \mathbb{N}$
- iii) the sequence $(x_n)_{n \in \mathbb{N}}$ is convergent and its limit is a fixed point of T .

Let us remark that a sequence $(x_n)_{n \in \mathbb{N}}$ satisfying the conditions (i) and (ii) in the previous definition is, by definition, a sequence of successive approximations of T , starting from (x, y) .

Definition 2.2. (see Covitz-Nadler [23]) Let (X, d) be a metric space. Then $T : X \rightarrow P_{cl}(X)$ is a multi-valued L -contraction, if there exists $L \in]0, 1[$ such that: $H(T(x), T(y)) \leq Ld(x, y)$, for every $x, y \in X$.

Definition 2.3. (see Reich [66]) Let (X, d) be a metric space. Then $T : X \rightarrow P_{cl}(X)$ is said to be a multi-valued Reich-type operator if there exist $\alpha, \beta, \gamma \in \mathbb{R}_+$, $\alpha + \beta + \gamma < 1$ such that: $H(T(x), T(y)) \leq \alpha d(x, y) + \beta D(x, T(x)) + \gamma D(y, T(y))$, for all $x, y \in X$.

Definition 2.4. (see Rus [70] and Petruşel [49]) Let (X, d) be a complete metric space. A multi-valued operator $T : X \rightarrow P_{cl}(X)$ is said to be a multi-valued Rus-type graphic-contraction if $G(T)$ is closed and the following condition is satisfied: there exist $\alpha, \beta \in \mathbb{R}_+$, $\alpha + \beta < 1$ such that: $H(T(x), T(y)) \leq \alpha d(x, y) + \beta D(y, T(y))$, for every $x \in X$ and every $y \in T(x)$. Moreover, the operator T is a multi-valued graphic-contraction if T is a multi-valued Rus-type contraction with $\beta = 0$.

Definition 2.5. (see Frigon-Granas [29] and Petruşel [59]) Let (X, d) be a complete metric space, $x_0 \in X$ and $r \geq 0$. The multi-valued operator T is called a Frigon-Granas-type operator if $T : \tilde{B}(x_0; r) \rightarrow P_{cl}(X)$ and satisfies the following assertion:

i) there exist $\alpha, \beta, \gamma \in \mathbb{R}_+$, $\alpha + \beta + \gamma < 1$ such that:

$$H(T(x), T(y)) \leq \alpha d(x, y) + \beta D(x, T(x)) + \gamma D(y, T(y)), \text{ for all } x, y \in \tilde{B}(x_0; r)$$

We also recall the definition of Kuratowski's measure of non-compactness :

Definition 2.6. Let X be a metric space and S a bounded subset of X . We set $\alpha(S) = \inf\{\varepsilon > 0 \mid \text{there exists } m \text{ and exists } S_1, \dots, S_m \text{ such that } S = \bigcup_{i \leq m} S_i \text{ and } \text{diam}(S_i) \leq \varepsilon\}$.

Definition 2.7. Let X a Banach space and $T : X \rightarrow P_{b,cl}(X)$ be a multivalued operator. Then T is said to be an (α, L) -contraction if and only if there exists $L \in]0, 1[$ such that $\alpha(T(A)) \leq L\alpha(A)$, for each $A \in P_b(X)$. (where α is the Kuratowski measure of non-compactness on X)

A multivalued operator $T : X \rightarrow P(X)$ is called compact if and only if $T(A)$ is relatively compact, for each $A \in P_b(X)$.

Definition 2.8. Let $F : [a, b] \times \mathbb{R}^n \rightarrow P_{cl}(\mathbb{R}^n)$ a multivalued operator. Then F is called integrably bounded if and only if there exists a function $r \in L^1[a, b]$ such that for every $v \in F(t, x)$, $|v| \leq r(t)$ a.e.

Definition 2.9. Let (X, d) be a metric space and E be a Banach space. Then $F : X \rightarrow P(E)$ is called:

a) locally selectionable at $x_0 \in X$ if and only if for all $y_0 \in F(x_0)$ there exist a neighborhood $N(x_0)$ and a continuous function $f : N(x_0) \rightarrow E$ such that $f(x_0) = y_0$ and $f(x) \in F(x)$, for each $x \in N(x_0)$.

b) measurable if and only if $F^{-1}(C)$ belongs to the σ -algebra \mathcal{B} of Borel subsets of X , for each closed subset C of E .

Definition 2.10. Let X be a nonempty set and E be a Banach space and $F : X \rightarrow P(E)$ be a multivalued operator.

i) The set defined by $F^{-1}(y) = \{x \in X \mid y \in F(x)\}$ is said to be the fibre of F at the point $y \in E$.

ii) The singlevalued operator $f : X \rightarrow E$ is a selection for F if and only if $f(x) \in F(x)$ for every $x \in X$.

Definition 2.11. (see Deguire-Lassonde [24] and [25]) Let X be a topological space and $\{Y_i \mid i \in I\}$ an arbitrary family of topological spaces.

i) We say that $\{f_i : X \rightarrow Y_i \mid i \in I\}$ is a selecting family for the family of multivalued operators $\{F_i : X \rightarrow \mathcal{P}(Y_i) \mid i \in I\}$ if and only if for each $x \in X$ there exists $i \in I$ such that $f_i(x) \in F_i(x)$.

ii) If $\{Y_i \mid i \in I\}$ is an arbitrary family of convex subsets of a Hausdorff topological vector space then the family $\{F_i : X \rightarrow \mathcal{P}(Y_i) \mid i \in I\}$ is said to be of Ky Fan-type if and only if each F_i has convex values and open fibres and for every $x \in X$ there is $i \in I$ such that $F_i(x) \neq \emptyset$.

Definition 2.12. The topological space X has the compact fixed point property if and only if every continuous mapping $f : X \rightarrow X$ with relatively compact image has a fixed point.

We consider now some known results that will be used in the following sections.

Theorem 2.13. (see [75]) *Let X be a metric space and Y be a closed subset of a Banach space Z . Assume that the multivalued operator $F : X \times Y \rightarrow P_{cl,cv}(Y)$ satisfies the following conditions:*

- i) $H(F(x, y_1), F(x, y_2)) \leq L\|y_1 - y_2\|$, for each $(x, y_1), (x, y_2) \in X \times Y$;*
- ii) for every $y \in Y$, $F(\cdot, y)$ is l.s.c. on the space X .*

Then there exists a continuous mapping $f : X \times Y \rightarrow Y$ such that :

$$f(x, y) \in F(x, f(x, y)), \text{ for each } (x, y) \in X \times Y$$

Theorem 2.14. (see [51]) *Let X be a Banach space and $F_1, F_2 : X \rightarrow P_{b,cl}(X)$ be two multivalued operators, such that F_1 is a L -contraction and F_2 is compact. Then $F_1 + F_2$ is (α, L) -contraction.*

3 Fixed point theorems for the sum of two multivalued operators

A first multivalued version of the Krasnoselskii's fixed point principle is:

Theorem 3.1. *Let X be a Banach space, $Y \in P_{cl,cv}(X)$ and $A : Y \rightarrow P_{b,cl,cv}(X)$, $B : Y \rightarrow P_{cp,cv}(X)$ two multivalued operators. If the following conditions are satisfied:*

- (i) $A(y_1) + B(y_2) \subset Y$, for each $y_1, y_2 \in Y$;*
- (ii) A is L -contraction;*
- (iii) B is l.s.c. and $B(Y)$ is relatively compact;*

then $Fix(A + B) \neq \emptyset$.

Proof. Let $C : Y \rightarrow \mathcal{P}(Y)$ be a multivalued operator defined as follows:

a) for each $x \in Y$ consider the multivalued operator $T_x : Y \rightarrow P_{cp,cv}(Y)$, $T_x(y) = A(y) + B(x)$. Since T_x is multivalued L -contraction (indeed, on have: $H(T_x(y_1), T_x(y_2)) = H(A(y_1) + B(x), A(y_2) + B(x)) \leq H(A(y_1), A(y_2)) \leq L\|y_1 - y_2\|$, for each $y_1, y_2 \in Y$), from Covitz-Nadler fixed point theorem (see [23]) it follows that for every $x \in Y$ the fixed point set for the multifunction T_x , $Fix T_x = \{y \in Y \mid y \in A(y) + B(x)\}$ is nonempty and closed.

b) From Theorem 2.13. it follows that there exists a continuous mapping $f : Y \times Y \rightarrow Y$ such that $f(x, y) \in A(f(x, y)) + B(x)$. (Let us observe that the multivalued operator $F : Y \times Y \rightarrow P_{cp,cv}(Y)$ defined by $F(x, y) = A(y) + B(x)$, for each $(x, y) \in Y \times Y$ satisfies the hypothesis of Theorem 2.13.) Let us define $C(x) = Fix T_x$, $C : Y \rightarrow P_{cl}(Y)$. Let us consider the singlevalued operator $c : Y \rightarrow Y$ defined by $c(x) = f(x, x)$, for each $x \in Y$.

Then c is a continuous mapping having the property that $c(x) = f(x, x) \in A(f(x, x)) + B(x) = A(c(x)) + B(x)$, for each $x \in Y$.

Now, we will prove that $c(Y)$ is relatively compact. For this purpose it is sufficient to show that $C(Y)$ is relatively compact. Let us observe that $C(Y)$ is totally bounded:

Indeed $B(Y)$ being relatively compact it is also totally bounded. So, there exists $Z = \{x_1, \dots, x_n\} \subset Y$ such that $B(Y) \subset \{z_1, \dots, z_n\} + B(0, (1 - L)\varepsilon) \subset \bigcup_{i=1}^n B(x_i) +$

$B(0, (1-L)\varepsilon)$ (where $z_i \in B(x_i)$, for each $i = 1, 2, \dots, n$). It follows that, for each $x \in Y$, $B(x) \subset \bigcup_{i=1}^n B(x_i) + B(0, (1-L)\varepsilon)$ and hence there exists an element $x_k \in Z$ such that $\rho(B(x), B(x_k)) < (1-L)\varepsilon$. Then:

$$\begin{aligned} \rho(C(x), C(x_k)) &= \rho(\text{Fix } T_x, \text{Fix } T_{x_k}) \leq \frac{1}{1-L} \sup_{y \in Y} \rho(T_x(y), T_{x_k}(y)) = \\ &= \frac{1}{1-L} \sup_{y \in Y} \rho(A(y) + B(x), A(y) + B(x_k)) \leq \frac{1}{1-L} \sup_{y \in Y} \rho(B(x), B(x_k)) < \\ &< \frac{1}{1-L} (1-L)\varepsilon = \varepsilon \end{aligned}$$

It follows that for each $u \in C(x)$ there is $v_k \in C(x_k)$ such that $\|u - v_k\| < \varepsilon$. Hence, for each $x \in Y$, $C(x) \subset Q + B(0, \varepsilon)$, where $Q = \{v_1, \dots, v_k, \dots, v_n\}$, $v_i \in C(x_i)$, $i = 1, 2, \dots, n$.

Since in a Banach space a totally bounded set is relatively compact the conclusion follows.

Finally, let us observe that the mapping $c : Y \rightarrow Y$ satisfies the assumptions of Schauder's fixed point theorem. Let $x^* \in Y$ be a fixed point for c . On have that $x^* = c(x^*) \in A(c(x^*)) + B(x^*) = A(x^*) + B(x^*)$.

Using the measures of non-compactness technique (see [51]) another fixed point result for the sum of two multi-valued operators is the following:

Theorem 3.2. *Let X be a Banach space, $Y \in P_{b,cl,cv}(X)$ and $A, B : Y \rightarrow P_{cp,cv}(X)$ two multivalued operators. If the following conditions are satisfied:*

- (i) $A(y) + B(y) \subset Y$, for each $y \in Y$;
- (ii) A is L -contraction;
- (iii) B is u.s.c. and compact;

then $\text{Fix}(A + B) \neq \emptyset$.

As application, from Theorem 3.2., we get the following existence result for an integral inclusion (see [51] for more details).

Theorem 3.3. *Consider the following Fredholm-Volterra integral inclusion:*

$$x(t) \in \lambda_1 \int_a^b K_1(t, s, x(s)) + \lambda_2 \int_a^t K_2(t, s, x(s)) ds, \quad t \in [a, b]. \quad (3.1)$$

We assume that:

i) $K_1 : [a, b] \times [a, b] \times \mathbb{R}^n \rightarrow P_{cl,cv}(\mathbb{R}^n)$ is a lower semicontinuous, measurable and integrably bounded multivalued operator

ii) $K_2 : [a, b] \times [a, b] \times \mathbb{R}^n \rightarrow P_{cp,cv}(\mathbb{R}^n)$ is an upper semicontinuous, measurable and integrably bounded (by an integrable function m_{K_2}) multivalued operator

iii) there exists $L > 0$ such that

$$H(K_1(t, s, u_1), K_1(t, s, u_2)) \leq L \|u_1 - u_2\|, \quad \text{for each } (t, s, u_1), (t, s, u_2) \in [a, b] \times [a, b] \times \mathbb{R}^n$$

iv) λ_2 satisfy the following relation:

$$|\lambda_2| \leq \frac{R}{2M_{K_2}(b-a)}, \text{ where } R \geq \frac{\delta}{1 - \frac{|\lambda_1|L}{2\tau}}$$

(with $M_{K_2} = \max_{t \in [a,b]} m_{K_2}(t)$, $\tau > |\lambda_1|L$ and δ is an upper bound for the set of contin-

uous selections for the multivalued operator $t \mapsto \lambda_2 \int_a^b K_2(t, s, y(s))ds$, $y \in C[a, b]$).

Then, there exists $y_0 \in C[a, b]$, such that the integral inclusion (3.1.) has a solution $y^* \in \tilde{B}(y_0; R) \subset C[a, b]$.

Sketch of the proof. Let $A, B : C[a, b] \rightarrow \mathcal{P}(C[a, b])$ be two multivalued operators given by

$$A(y) = \left\{ u \in C[a, b] \mid u(t) \in \lambda_1 \int_a^t K_1(t, s, y(s))ds, \quad t \in [a, b] \right\}$$

$$B(y) = \left\{ v \in C[a, b] \mid v(t) \in \lambda_2 \int_a^t K_2(t, s, y(s))ds, \quad t \in [a, b] \right\}$$

Obviously $y^* \in \text{Fix}(A + B)$ if and only if y^* is a solution for (3.1.).

Then on can prove that the multifunctions A and B satisfies the assumptions of Theorem 3.2. \square

4 Properties of the fixed points set for multifunctions

Contrary to the single-valued case, the fixed points set for a multivalued contraction is not necessarily a singleton and hence it is of interest to study some properties (compactness, absolute retract property, data dependence etc.) of it.

In this framework, J. Saint-Raymond established the following theorem.

Theorem 4.1. ([65]) *Let T be a multi-valued contraction from the complete metric space X to itself. If T takes compact values, the fixed points set $\text{Fix}T$ is compact too.*

As regard to the same problem, B. Ricceri stated the following very important theorem:

Theorem 4.2. ([69]) *Let E be a Banach space and let X be a nonempty, closed, convex subset of E . Suppose $T : X \rightarrow P_{cl,cv}(X)$ is a multi-valued contraction. Then $\text{Fix}T$ is an absolute retract for metric spaces.*

Using a similar idea as in [29] we shall prove first the following existence result:

Theorem 4.3. *Let (X, d) be a complete metric space $x_0 \in X$, $r > 0$ and $T : \tilde{B}(x_0, r) \rightarrow P_{cl}(X)$ a multivalued operator satisfying the following assertions:*

i) T is a Reich-type multivalued operator

$$ii) D(x_0, T(x_0)) < \frac{1 - (\alpha + \beta + \gamma)}{1 - \gamma} r.$$

Then $\text{Fix}T \neq \emptyset$.

Proof. We shall prove, by induction, the existence of a sequence $(x_n)_{n \in \mathbb{N}}$ in $\tilde{B}(x_0, r)$ such that

a) $x_n \in T(x_{n-1})$, for each $n \in \mathbb{N}^*$

b) $d(x_{n-1}, x_n) < (\alpha + \beta + \gamma)^{n-1} \frac{1 - (\alpha + \beta + \gamma)}{1 - \gamma} r$, for each $n \in \mathbb{N}^*$.

For $n = 1$ the assertions a) and b) are true.

If the relations hold for $i \in \{1, n\}$ let us show the existence of x_{n+1} .

We have:

$$\begin{aligned} H(T(x_{n-1}), T(x_n)) &\leq \alpha d(x_{n-1}, x_n) + \beta D(x_{n-1}, T(x_{n-1})) + \gamma D(x_n, T(x_n)) \leq \\ &\leq \alpha d(x_{n-1}, x_n) + \beta d(x_{n-1}, x_n) + \gamma H(T(x_{n-1}), T(x_n)). \end{aligned}$$

Hence

$$\begin{aligned} H(T(x_{n-1}), T(x_n)) &\leq \frac{\alpha + \beta}{1 - \gamma} d(x_{n-1}, x_n) < \frac{\alpha + \beta}{1 - \gamma} (\alpha + \beta + \gamma)^{n-1} \frac{1 - (\alpha + \beta + \gamma)}{1 - \gamma} r < \\ &< (\alpha + \beta + \gamma)^n \frac{1 - (\alpha + \beta + \gamma)}{1 - \gamma} r. \end{aligned}$$

So we get that there exists $x_{n+1} \in T(x_n)$ such that

$$d(x_n, x_{n+1}) < (\alpha + \beta + \gamma)^n \frac{1 - (\alpha + \beta + \gamma)}{1 - \gamma} r,$$

proving the existence of the point x_{n+1} satisfying a) and b). Let us denote by $l = \alpha + \beta + \gamma$. Further on, we shall prove that $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence. Indeed

$$d(x_n, x_{n+p}) < (l^n + \dots + l^{n+p-1}) \frac{1 - l}{1 - \gamma} r \leq \frac{l^n}{1 - \gamma} r \rightarrow 0, \quad \text{as } n \rightarrow \infty.$$

This implies that $x_n \rightarrow x^*$ as $n \rightarrow \infty$ and because T has closed values we get by standard arguments that $x^* \in T(x^*)$. \square

Remark 4.4. When $\beta = \gamma = 0$ we get Theorem 3.1 from [29].

Remark 4.5. When $\alpha = 0$ and $\beta = \gamma = h$ (with $h \in \mathbb{R}$, $0 < h < 1/2$) we obtain a fixed point result for a Kannan-type multivalued operator.

Another result of this type is:

Theorem 4.6. Let (X, d) be a complete metric space, $x_0 \in X$, $r > 0$ and

$T : \tilde{B}(x_0; r) \rightarrow P_{cl}(X)$ satisfying:

i) T is a graphic-contraction

ii) T is a closed multifunction

iii) $D(x_0, T(x_0)) < (1 - \alpha)r$.

Then $\text{Fix}T \neq \emptyset$.

For the fixed points set of a Frigon-Granas type multifunction we have:

Theorem 4.7. Let (X, d) be a complete metric space, $x_0 \in X$ and $r > 0$. Let us suppose that $T : \tilde{B}(x_0; r) \rightarrow P_{cp}(X)$ satisfies the following two conditions:

i) there exist $\alpha, \beta \in \mathbb{R}_+$, $\alpha + 2\beta < 1$ such that

$$H(T(x), T(y)) \leq \alpha d(x, y) + \beta [D(x, T(x)) + D(y, T(y))], \text{ for each } x, y \in \tilde{B}(x_0; r)$$

ii) $D(x_0, T(x_0)) < [1 - (\alpha + 2\beta)](1 - \beta)^{-1}r$.

Then the fixed points set $FixT$ is compact.

Proof. It is not difficult to see that $FixT \in P_{cl}(\tilde{B}(x_0; r))$. Assume that $FixT$ is not compact. Because $FixT$ is complete, it cannot be precompact, so there exist $\delta > 0$ and a sequence $(x_i)_{i \in \mathbb{N}} \subset FixT$ such that $d(x_i, x_j) \geq \delta$, for each $i \neq j$. Put $\rho = \inf\{R\}$ there exists $a \in \tilde{B}(x_0; r)$ such that $B(a, R)$ contains infinitely many x_i 's. Obviously $\rho \geq \frac{\delta}{2} > 0$. Let $\varepsilon > 0$ such that $\varepsilon < \frac{1 - \alpha - 2\beta}{1 + \alpha}\rho$ and choose $a \in \tilde{B}(x_0; r)$ such that the set $J = \{i : x_i \in B(a, \rho + \varepsilon)\}$ is infinite.

For each $i \in J$, we have

$$\begin{aligned} D(x_i, T(a)) &\leq H(T(x_i), T(a)) \leq \alpha d(x_i, a) + \beta_i [D(x_i, T(x_i)) + D(a, T(a))] = \\ &= \alpha d(x_i, a) + \beta D(a, T(a)) < \alpha(\rho + \varepsilon) + \beta d(a, y), \text{ for every } y \in T(a). \end{aligned}$$

Then

$$D(x_i, T(a)) < \alpha(\rho + \varepsilon) + \beta[d(a, x_i) + d(x_i, y)] < \alpha(\rho + \varepsilon) + \beta(\rho + \varepsilon) + \beta d(x_i, y),$$

for every $y \in T(a)$. Taking $\inf_{y \in T(a)}$ we get : $D(x_i, T(a)) \leq (\alpha + \beta)(\rho + \varepsilon)(1 - \beta)^{-1}$, for each $i \in J$. So, we can choose some $y_i \in T(a)$ such that $d(x_i, y_i) \leq (\alpha + \beta)(\rho + \varepsilon)(1 - \beta)^{-1}$, for each $i \in J$. By the compactness of $T(a)$ there exists $b \in T(a)$ such that the following set: $J' = \{i \in J \mid d(y_i, b) < \varepsilon\}$ is infinite. Then, for each $i \in J'$ we get $d(x_i, b) \leq d(x_i, y_i) + d(y_i, b) < (\alpha + \beta)(\rho + \varepsilon)(1 - \beta)^{-1} + \varepsilon = (\alpha + \beta)(1 - \beta)^{-1}\rho + \varepsilon(1 + (\alpha + \beta)(1 - \beta)^{-1}) < \rho$. This contradicts the definition of ρ , because the set $B(b, R)$ contains infinitely many x_i 's. (where $R = (\alpha + \beta)\rho(1 - \beta)^{-1} + \varepsilon(1 + (\alpha + \beta)(1 - \beta)^{-1})$). \square

Corollary 4.8. Let (X, d) be a complete metric space and $T : X \rightarrow P_{cp}(X)$ be a multivalued operator. Let us suppose that there exist $\alpha, \beta \in \mathbb{R}_+$ with $\alpha + 2\beta < 1$ such that

$$H(T(x), T(y)) \leq \alpha d(x, y) + \beta [D(x, T(x)) + D(y, T(y))],$$

for each $x, y \in X$.

Then the fixed points set $FixT$ is compact.

Only minor modifications of the above technique are needed in order to obtain the following result:

Theorem 4.9. Let (X, d) be a complete metric space and $T : X \rightarrow P_{cp}(X)$ be a multivalued operator. If the following assertions are true:

i) there exist $\alpha, \beta \in \mathbb{R}_+$, $\alpha + \beta < 1$ such that

$$H(T(x), T(y)) \leq \alpha d(x, y) + \beta D(x, T(x)), \text{ for each } x, y \in X$$

ii) $D(x_0, T(x_0)) < [1 - (\alpha + \beta)](1 - \beta)^{-1}r$.

then the fixed points set $FixT$ is compact.

We consider now another result regarding the structure of the set of all fixed points for a multi-valued Reich-type operator with convex values.

Theorem 4.10. *Let E be a Banach space, $X \in P_{cl,cv}(E)$ and $T : X \rightarrow P_{cl,cv}(X)$ be a l.s.c. multi-valued Reich-type operator. Then $FixT \in AR(\mathcal{M})$.*

Proof. Let us remark first that $FixT \in P_{cl}(X)$ (see for example [73]). Let K be a paracompact topological space, $A \in P_{cl}(K)$ and $\psi : A \rightarrow FixT$ a continuous mapping. Using Theorem 2 from B. Ricceri [69] (taking $G(t) = X$, for each $t \in K$) it follows the existence of a continuous function $\varphi_0 : K \rightarrow X$ such that $\varphi_0|_A = \psi$. We next consider $q \in]1, (\alpha + \beta + \gamma)^{-1}[$. We claim that there exists a sequence $(\varphi_n)_{n \in \mathbb{N}}$ of continuous functions from K to X with the following properties:

- (i) $\varphi_n|_A = \psi$
- (ii) $\varphi_n(t) \in T(\varphi_{n-1}(t))$, for all $t \in K$
- (iii) $\|\varphi_n(t) - \varphi_{n-1}(t)\| \leq [(\alpha + \beta + \gamma)q]^{n-1} \|\varphi_1(t) - \varphi_0(t)\|$, for all $t \in K$.

To see this, we proceed by induction on n . Clearly, for each $t \in A$ we have that $\psi(t) \in T(\varphi_0(t))$. On the other hand, the multi-function $t \mapsto T(\varphi_0(t))$ is l.s.c. on K with closed, convex values and hence using again Theorem 2 in [69] it follows that there is a continuous function $\varphi_1 : K \rightarrow X$ such that $\varphi_1|_A = \psi$ and $\varphi_1(t) \in T(\varphi_0(t))$, for all $t \in K$. Hence, the conditions (i), (ii), (iii) are true for φ_1 . Suppose now we have constructed p continuous functions $\varphi_1, \varphi_2, \dots, \varphi_p$ from K to X in such a way that (i), (ii), (iii) are true for $n \in \{1, 2, \dots, p\}$. Using the Reich-type contraction condition for T , we have

$$\begin{aligned} D(\varphi_p(A), T(\varphi_p(t))) &\leq H(T(\varphi_{p-1}(t)), T(\varphi_p(t))) \leq \\ &\leq \alpha \|\varphi_{p-1}(t) - \varphi_p(t)\| + \beta D(\varphi_{p-1}(t), T(\varphi_{p-1}(t))) + \gamma D(\varphi_p(t), T(\varphi_p(t))) \leq \\ &\leq \alpha \|\varphi_{p-1}(t) - \varphi_p(t)\| + \beta \|\varphi_{p-1}(t) - \varphi_p(t)\| + \gamma D(\varphi_p(t), T(\varphi_p(t))) \end{aligned}$$

so that

$$\begin{aligned} D(\varphi_p(t), T(\varphi_p(t))) &\leq (\alpha + \beta)(1 - \gamma)^{-1} \|\varphi_p(t) - \varphi_{p-1}(t)\| \leq \\ &\leq (\alpha + \beta)(1 - \gamma)^{-1} [(\alpha + \beta + \gamma)q]^{p-1} \|\varphi_1(t) - \varphi_0(t)\| < (\alpha + \beta + \gamma)^p q^{p-1} \|\varphi_1(t) - \varphi_0(t)\| < \\ &< [(\alpha + \beta + \gamma)q]^p \|\varphi_1(t) - \varphi_0(t)\|. \end{aligned}$$

We next define

$$Q_p(t) = \begin{cases} B(\varphi_p(t), [(\alpha + \beta + \gamma)q]^p \|\varphi_1(t) - \varphi_0(t)\|), & \text{if } t \in K \text{ and } \varphi_1(t) \neq \varphi_0(t) \\ \{\varphi_p(t)\}, & \text{if } \varphi_1(t) = \varphi_0(t) \end{cases}$$

Obviously $T(\varphi_p(t)) \cap Q_p(t) \neq \emptyset$, for all $t \in K$. We can apply now (taking $G(t) = F(\varphi_p(t))$, $f(t) = \varphi_p(t)$ and the mapping $g(t) = [(\alpha + \beta + \gamma)q]^p \|\varphi_1(t) - \varphi_0(t)\|$, for all $t \in K$). Proposition 3 from [69], we obtain that the multi-function $t \mapsto \overline{T(\varphi_p(t))} \cap Q_p(t)$ is l.s.c. on K with nonempty, closed, convex values. Because of Theorem 2 in [69], this produces a continuous function $\varphi_{p+1} : K \rightarrow X$ such that $\varphi_{p+1}|_A = \psi$ and $\varphi_{p+1}(t) \in \overline{T(\varphi_p(t))} \cap Q_p(t)$, for all $t \in K$. Thus the existence of the sequence $\{\varphi_n\}$ is established. Consider now the open covering of K defined by

the formula: $(\{t \in K \mid \|\varphi_1(t) - \varphi_0(t)\| < \lambda\})_{\lambda > 0}$. Moreover, because of (iii) and the fact that X is complete, the sequence $\{\varphi_n\}_{n \in \mathbb{N}}$ converges uniformly on each of the following set $K_\lambda = \{t \in K \mid \|\varphi_1(t) - \varphi_0(t)\| < \lambda\}$ ($\lambda > 0$). Let $\varphi : K \rightarrow X$ be the pointwise limit of $(\varphi_n)_{n \in \mathbb{N}}$. Obviously φ is continuous and $\varphi|_A = \psi$. Moreover, a simple computation ensures that $\varphi(t) \in T(\varphi(t))$ for all $t \in K$ and this completes the proof. \square

Remark 4.11. *If $\beta = \gamma = 0$ then the previous theorem coincides with B. Ricceri's result (Theorem 4.2 below).*

Remark 4.12. *Of course, it is also possible to formulate version of Theorem 4.10., where T is a multi-valued Rus-type graphic contraction. It is an open question if such a result holds for a Frigon-Granas type multi-function.*

The second aim of this section is to study the data dependence problem of the fixed points set for some Frigon-Granas-type multifunctions.

Theorem 4.13. *Let (X, d) be a complete metric space, $x_0 \in X$, $r > 0$ and $T_1, T_2 : \tilde{B}(x_0; r) \rightarrow P_{cl}(X)$ be multifunctions satisfying the following assertions:*

- i) T_i is a multivalued α_i -contraction, for $i \in \{1, 2\}$*
- ii) $\delta(x_0, T_i(x_0)) < (1 - \alpha_i)r$, for $i \in \{1, 2\}$*
- iii) there exists $\eta > 0$ such that $H(T_1(x), T_2(x)) \leq \eta$, for each $x \in \tilde{B}(x_0; r)$.*

Then:

- a) $FixT_i \in P_{cl}(\tilde{B}(x_0; r))$ for $i \in \{1, 2\}$*
- b) $H(FixT_1, FixT_2) \leq \frac{\eta}{1 - \max\{\alpha_1, \alpha_2\}}$.*

Proof. a) We denote by T each of the two multifunctions T_1 and T_2 . For each $x \in \tilde{B}(x_0; r)$ we have that $T(x) \subset \tilde{B}(x_0; r)$. Indeed, let $u \in T(x)$ be arbitrary. Then

$$d(x_0, u) \leq d(x_0, y) + d(y, u) \leq (1 - \alpha)r + d(y, u) \quad \text{for each } y \in T(x_0).$$

Taking the infimum after $y \in T(x_0)$ we get:

$$\begin{aligned} d(x_0, u) &\leq (1 - \alpha)r + D(u, T(x_0)) \leq (1 - \alpha)r + H(T(x), T(x_0)) \leq \\ &\leq (1 - \alpha)r + \alpha d(x, x_0) \leq r, \end{aligned}$$

proving the fact that $T : \tilde{B}(x_0; r) \rightarrow P_{cl}(\tilde{B}(x_0; r))$. The conclusion a) follows from Covitz-Nadler theorem (see [23]) and the part b) from Rus-Petruşel-Sîntămărian result in [73]. \square

Remark 4.14. *It is an open problem, the data dependence of the fixed points set for the Frigon-Granas-type multifunctions satisfying the weaker condition*

$$D(x_0, T(x_0)) < (1 - \alpha)r.$$

Similarly, we can prove:

Theorem 4.15. *Let (X, d) be a complete metric space, $x_0 \in X$, $r > 0$ and $T_1, T_2 : \tilde{B}(x_0; r) \rightarrow P_{cl}(X)$ be multifunctions such that:*

- i) T_i is a multivalued Reich-type operator with $\alpha_i, \beta_i, \gamma_i \in \mathbb{R}_+$, $\alpha_i + \beta_i + \gamma_i < 1$, for each $i \in \{1, 2\}$.*

$$ii) \delta(x_0, T_i(x_0)) < \frac{1 - (\alpha_i + \beta_i + \gamma_i)}{1 - \gamma_i} r \text{ for } i \in \{1, 2\}.$$

iii) there exists $\eta > 0$ such that $H(T_1(x), T_2(x)) \leq \eta$, for each $x \in \tilde{B}(x_0; r)$.

Then:

a) $FixT_i \in P_{cl}(\tilde{B}(x_0, r))$, for $i \in \{1, 2\}$

$$b) H(FixT_1, FixT_2) \leq \frac{1 - \min\{\gamma_1, \gamma_2\}}{1 - \max\{\alpha_1 + \beta_1 + \gamma_1, \alpha_2 + \beta_2 + \gamma_2\}}.$$

Let us remark now that, if $T : \tilde{B}(x_0; r) \rightarrow P_{cl}(X)$ is a Frigon-Granas-type multifunction, such that

$$D(x_0, T(x_0)) < (1 - \alpha)r,$$

then T is not necessarily a m.w.P.o.

This situation suggests the following concept:

Definition 4.16. Let (X, d) be a metric space, $Y \in P(X)$ and $T : Y \rightarrow P(X)$ be a multivalued operator. By definition, T is a multivalued weakly pseudo-Picard operator (briefly m.w.p.P.o.) if and only if there exist $x_0 \in Y$, $y_0 \in T(x_0)$ and a sequence $(u_n)_{n \in \mathbb{N}} \subset Y$ such that

i) $u_0 = x_0$, $u_1 = y_0$

ii) $u_{n+1} \in T(u_n)$ for all $n \in \mathbb{N}$

iii) the sequence $(u_n)_{n \in \mathbb{N}}$ converges and its limit is a fixed point of T .

Example 4.17. Let (X, d) be a complete metric space, $x_0 \in X$, $r > 0$ and $T : \tilde{B}(x_0; r) \rightarrow P_{cl}(X)$ a multifunction such that $D(x_0, T(x_0)) < (1 - \alpha)r$. Then T is a m.w.p.P.o.

Proof. The conclusion follows from Frigon-Granas theorem (see [29] Theorem 3.1). \square

Example 4.18. Let (X, d) be a complete metric space, $x_0 \in X$, $r > 0$ and $T : \tilde{B}(x_0; r) \rightarrow P_{cl}(X)$ a Reich-type multifunction, such that

$$D(x_0, T(x_0)) < \frac{1 - (\alpha + \beta + \gamma)}{1 - \gamma} r.$$

Then T is a m.w.p.P.o.

Proof. The conclusion follows from Theorem 4.3. \square

Example 4.19. Let (X, d) be a complete metric space, $\varepsilon > 0$ and $T : X \rightarrow P_{cl}(X)$ be a multi-valued operator satisfying the following assertions:

i) there exists $\alpha \in [0, 1[$ such that for each $x, y \in X$ with $d(x, y) < \varepsilon$

$$H(T(x), T(y)) \leq \alpha d(x, y).$$

ii) there exists $x_0 \in X$ such that $D(x_0, T(x_0)) < \varepsilon$.

Then T is a m.w.p.P.o.

Proof. The conclusion is an easy consequence of Theorem 3.1 in [10]. \square

Example 4.20. Let (X, d) be a complete metric space and let $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ be a map which satisfies:

a) φ is nondecreasing and continuous from the right

b) for each $u > 0$, $\sum_{n \geq 0} \varphi^n(u) < \infty$

c) $\varphi(u) = 0$ if and only if $u = 0$.

Assume that $T : X \rightarrow P_{b,cl}(X)$ is a multifunction for which there exists $\varepsilon > 0$ such that the following two conditions are satisfied:

i) for each $x, y \in X$ with $d(x, y) < \varepsilon$ we have that

$$H(T(x), T(y)) \leq \varphi(d(x, y))$$

ii) there exists $x_0 \in X$ such that $D(x_0, T(x_0)) < \varepsilon$.

Then T is a m.w.p.P.o.

Proof. The conclusion follows from Theorem 3.1 in [10]. \square

In [74], we proved the data dependence of the fixed points set for so-called c-m.w.P.o. It is an open question, if some similar results can be obtained for some multivalued weakly pseudo-Picard operators.

5 Fixed points and selections for multifunctions with decomposable values

Throughout this section $(\Omega, \mathcal{A}, \mu)$ is a complete σ -finite nonatomic measure space and E is a Banach space. Let $L^1(\Omega, E)$ be the Banach space of all measurable functions $u : \Omega \rightarrow E$ which are Bochner μ -integrable. We call a set $K \subset L^1(\Omega, E)$ decomposable if for all $u, v \in K$ and each $A \in \mathcal{A}$:

$$u\chi_A + v\chi_{\Omega \setminus A} \in K, \tag{5.2}$$

where χ_A stands for the characteristic function of the set A .

This notion is, somehow, similar to convexity, but there exist also major differences. For example, the following theorem is a "decomposable" version of the well-known Michael's selection theorem for l.s.c. multifunctions.

Theorem 5.1. (see [15]) *Let (X, d) be a separable metric space, E a separable Banach space and let $F : X \rightarrow P_{cl,dec}(L^1(\Omega, E))$ be a l.s.c. multivalued operator. Then F has a continuous selection.*

Our first result, concerning the existence of continuous selections for a locally selectionable multifunction, is as follows:

Lemma 5.2. *Let (X, d) be a separable metric space, $(\Omega, \mathcal{A}, \mu)$ be a complete σ -finite and nonatomic measure space and E be a Banach space. Let $F : X \rightarrow P_{dec}(L^1(\Omega, E))$ be a locally selectionable multivalued operator. Then F has a continuous selection.*

Proof We associate to any $y \in X$ and $z \in F(y)$ an open neighborhood $N(y)$ and a local continuous selection $f_y : N(y) \rightarrow L^1(\Omega, E)$, satisfying $f_y(y) = z$ and $f_y(x) \in F(x)$ when $x \in N(y)$. We denote by $\{V_n\}_{n \in \mathbb{N}^*}$ a countable locally finite open refinement of the open covering $\{N(y) \mid y \in X\}$ and by $\{\psi_n\}_{n \in \mathbb{N}^*}$ a continuous partition of unity associated to $\{V_n\}_{n \in \mathbb{N}^*}$.

Then, for each $n \in \mathbb{N}^*$ there exist $y_n \in X$ such that $V_n \subset N(y_n)$ and a continuous function $f_{y_n} : N(y_n) \rightarrow L^1(\Omega, E)$ with $f_{y_n}(y_n) = z_n$, $f_{y_n}(x) \in F(x)$, for all $x \in N(y_n)$.

We define $\lambda_0(x) = 0$ and $\lambda_n(x) = \sum_{m \leq n} \psi_m(x)$, $n \in \mathbb{NN}^*$. Let $g_{m,n} \in L^1(\Omega, \mathbb{R}_+)$ be the function defined by $g_{m,n}(t) = \|z_n(t) - z_m(t)\|$, for each $m, n \geq 1$.

We arrange these functions into a sequence $\{g_k\}_{k \in \mathbb{NN}^*}$.

Consider the function $\tau(x) = \sum_{m,n \geq 1} \psi_m(x) \psi_n(x)$. From Lemma 1 in [15], there

exists a family $\{\Omega(\tau, \lambda)\}$ of measurable subsets of Ω such that:

- (a) $\Omega(\tau, \lambda_1) \subseteq \Omega(\tau, \lambda_2)$, if $\lambda_1 \leq \lambda_2$
- (b) $\mu(\Omega(\tau_1, \lambda_1) \Delta \Omega(\tau_2, \lambda_2)) \leq |\lambda_1 - \lambda_2| + 2|\tau_1 - \tau_2|$
- (c) $\int_{\Omega(\tau, \lambda)} g_n d\mu = \lambda \int_{\Omega} g_n d\mu$, $\forall n \leq \tau_0$ for all $\lambda, \lambda_1, \lambda_2 \in [0, 1]$, and all $\tau_0, \tau_1, \tau_2 \geq 0$.

Define $f_n(x) = f_{y_n}(x)$ and $\chi_n(x) = \chi_{\Omega(\tau(x), \lambda_n(x)) \setminus \Omega(\tau(x), \lambda_{n-1}(x))}$ for each $n \in \mathbb{NN}^*$.

Let us consider the singlevalued operator $f : X \rightarrow L^1(\Omega, E)$, defined by $f(x) = \sum_{n \geq 1} f_n(x) \chi_n(x)$, $x \in X$. Then, f is continuous because the functions τ and λ_n are continuous, the characteristic function of the set $\Omega(\tau, \lambda)$ varies continuously in $L^1(\Omega, E)$ with respect to the parameters τ and λ and because the summation defining f is locally finite. On the other hand, from the properties of the sets $\Omega(\tau, \lambda)$ (see [64] for example) and because F has decomposable values, it follows that f is a selection of F . \square

The following result is a selection theorem for the intersection of two multi-valued operators.

Theorem 5.3. *Let (X, d) be a separable metric space, E a separable Banach space, $F : X \rightarrow P_{cl, dec}(L^1(\Omega, E))$ be a l.s.c. multivalued operator and $G : X \rightarrow P_{dec}(L^1(\Omega, E))$ be with open graph. If $F(x) \cap G(x) \neq \emptyset$ for each $x \in X$ then there exists a continuous selection of $F \cap G$.*

Proof Let $x_0 \in X$ and for each $y_0 \in F(x_0)$ we define the multifunction

$$F_0(x) = \begin{cases} \{y_0\}, & \text{if } x = x_0 \\ F(x), & \text{if } x \neq x_0. \end{cases}$$

Obviously $F_0 : X \rightarrow P_{cl, dec}(L^1(\Omega, E))$ is l.s.c. From Theorem 5.1. there exists a continuous selection f of F_0 , i.e. $f_0(x_0) = y_0$ and $f_0(x) \in F(x)$, for each $x \in X$, $x \neq x_0$. Using Proposition 4, p.81 in [5] it follows that $F \cap G$ is locally selectionable at x_0 and has decomposable values. From Lemma 5.2. the conclusion follows. \square

An important result is the following Browder-type selection theorem:

Theorem 5.4. *Let E be a Banach space such that $L^1(\Omega, E)$ is separable. Let K be a nonempty, paracompact, decomposable subset of $L^1(\Omega, E)$ and let $F : K \rightarrow P_{dec}(K)$ be a multivalued operator with open fibres. Then F has a continuous selection.*

Proof For each $y \in K$, $F^{-1}(y)$ is an open subset of K . Since K is paracompact it follows that the open covering $\{F^{-1}(y)\}_{y \in K}$ admits a locally finite open refinement, let say $K = \bigcup_{j \in J} F^{-1}(y_j)$, with $y_j \in K$. Let $\{\psi_j\}_{j \in J}$ be a continuous partition of unity

subordinate to $\{F^{-1}(y_j)\}_{j \in J}$. Using the same construction as in the proof of Lemma 5.2., one can construct a continuous function $f : K \rightarrow K$, $f(x) = \sum_{j \in J} f_j(x) \chi_j(x)$,

where $f_j(x) \in F(x)$ for each $x \in K$. This function is a continuous selection for F . \square

Theorem 5.5. *Let E be a Banach space such that $L^1(\Omega, E)$ is separable. Let I be an arbitrary set of indices, $\{K_i | i \in I\}$ be a family of nonempty, decomposable subsets of $L^1(\Omega, E)$ and X a paracompact space. Let us suppose that the family $\{F_i : X \rightarrow \mathcal{P}_{dec}(K_i) | i \in I\}$ is of Ky Fan-type. Then there exists a selecting family for $\{F_i\}_{i \in I}$.*

Proof Let $\{U_i\}_{i \in I}$ be the open covering of the paracompact space X given by $U_i = \{x \in X | F_i(x) \neq \emptyset\}$ for each $i \in I$. It follows that there exists a locally finite open cover $\{W_i\}_{i \in I}$ such that $\overline{W_i} \subset U_i$ for $i \in I$. Let $V_i = \overline{W_i}$. For each $i \in I$ let us consider the multivalued operator $G_i : X \rightarrow \mathcal{P}(K_i)$, defined by the relation

$$G_i(x) = \begin{cases} F_i(x), & \text{if } x \in V_i \\ K_i, & \text{if } x \notin V_i. \end{cases}$$

Then G_i is a multifunction with nonempty and decomposable values having open fibres (indeed, $G_i^{-1}(y) = F_i^{-1}(y) \cup (X \setminus V_i)$), for each $i \in I$.

Using Theorem 4.4. we have that there exists $f_i : X \rightarrow K_i$ continuous selection for G_i ($i \in I$), for each $i \in I$. It follows that for each $x \in X$ there exists $i \in I$ such that $x \in V_i$ and hence $f_i(x) \in G_i(x) = F_i(x)$, proving that $\{f_i\}_{i \in I}$ is a selecting family for $\{F_i\}_{i \in I}$. \square

By a similar argument we have:

Theorem 5.6. *Let E be a separable Banach space and X a separable metric space. Let I be an arbitrary set of indices, $\{K_i | i \in I\}$ be a family of nonempty, closed, decomposable subsets of $L^1(\Omega, E)$. Let $\{F_i : X \rightarrow \mathcal{P}_{cl,dec}(K_i) | i \in I\}$ be a family of l.s.c. multivalued operators such that for each $x \in X$ there is $i \in I$ such that $F_i(x) \neq \emptyset$. Then $\{F_i\}_{i \in I}$ has a selecting family.*

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